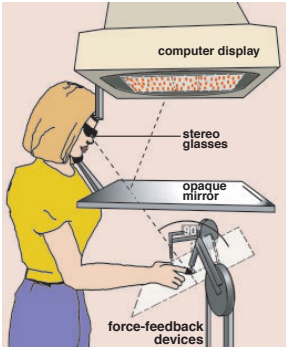


# The effect of joint attention on visual-tactile integration and recalibration

Michael S. Landy  
NYU

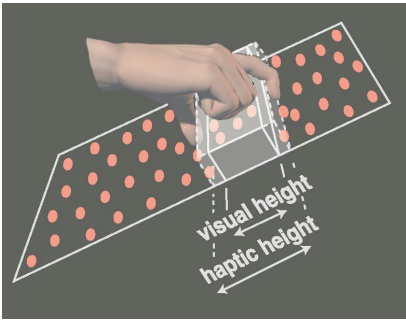
With: Stephanie Badde & Karen Navarro  
Badde, Navarro & Landy, *Cognition*, 197, 104170.

## “Traditional” Cue Integration



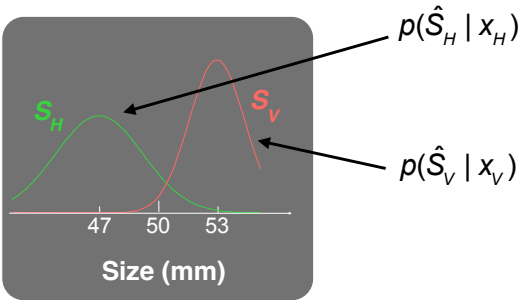
Maloney & Landy, 1989; Clark & Yuille, 1990; Landy et al., 1995; Ernst & Banks, 2002; etc.

## “Traditional” Cue Integration

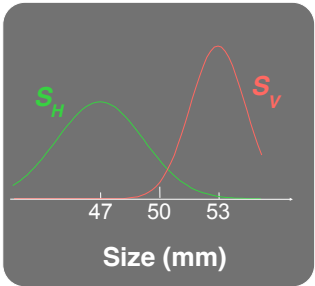


Maloney & Landy, 1989; Clark & Yuille, 1990; Landy et al., 1995; Ernst & Banks, 2002; etc.

## “Traditional” Cue Integration



## “Traditional” Cue Integration



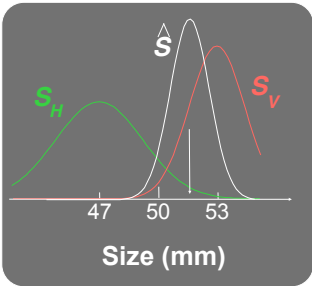
$$\hat{S} = w_H \hat{S}_H + w_V \hat{S}_V$$

$$w_H = \frac{r_H}{r_H + r_V}$$

$$w_V = \frac{r_V}{r_H + r_V}$$

$$\text{Reliability } r = 1 / \sigma^2$$

## “Traditional” Cue Integration



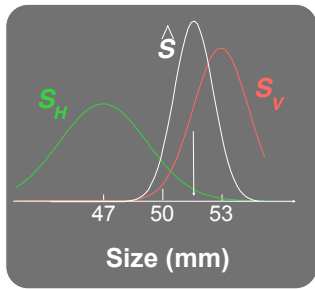
$$\hat{S} = w_H \hat{S}_H + w_V \hat{S}_V$$

$$w_H = \frac{r_H}{r_H + r_V}$$

$$w_V = \frac{r_V}{r_H + r_V}$$

$$\text{Reliability } r = 1 / \sigma^2$$

## “Traditional” Cue Integration



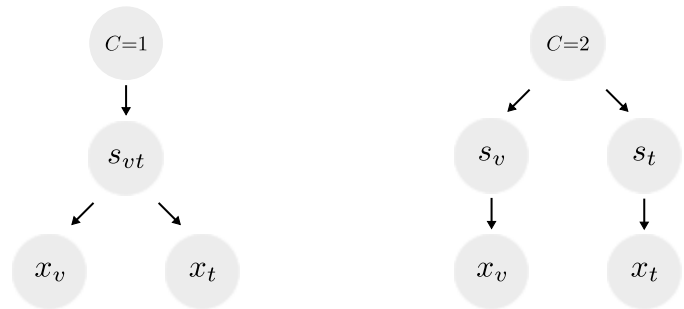
$$\hat{S} = w_H \hat{S}_H + w_V \hat{S}_V$$

$$\sigma_{HV}^2 = \frac{\sigma_H^2 \sigma_V^2}{\sigma_H^2 + \sigma_V^2}$$

$$r_{HV} = r_H + r_V$$

Variance of combined estimate lower than variance of either single-cue estimate

## Causal Inference



Körding et al., 2007

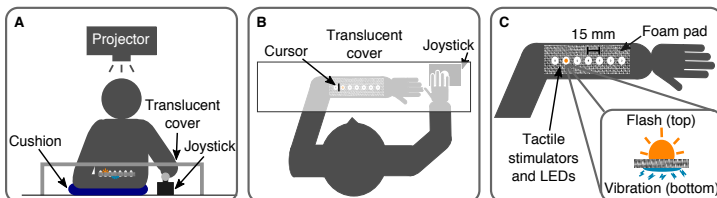
## Ventriloquism and its Aftereffect



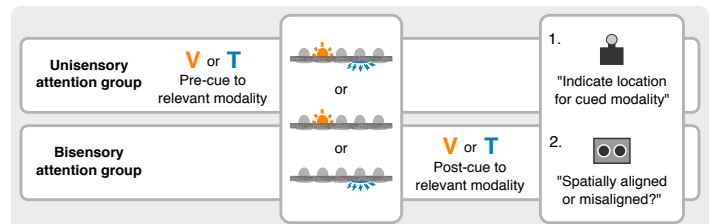
## Ventriloquism and its Aftereffect

- Multisensory integration
- Causal inference
- Bayesian modeling (e.g., Körding et al., 2007)
- Recalibration
- Top-down influences on integration and recalibration:
  - Visual-auditory: cognitively impenetrable
  - Visual-proprioceptive: Effects of instructions and attention
  - Visual-tactile (another body sense)?

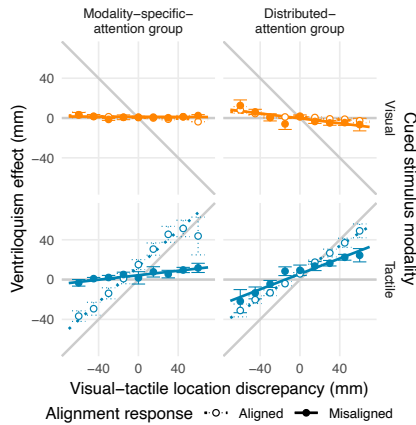
## Experimental Apparatus



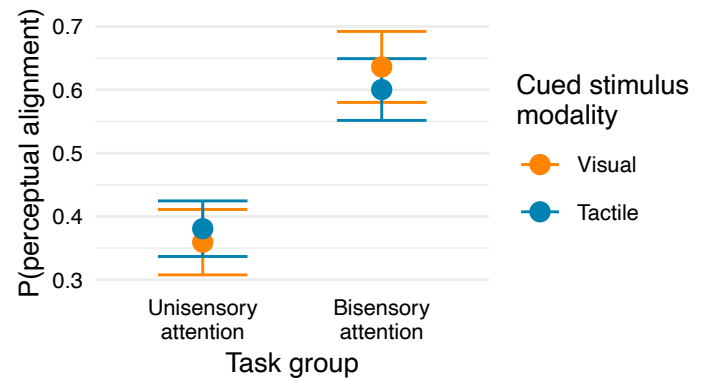
## Ventriloquist Effect: Procedure



## Ventriloquist Effect: Results



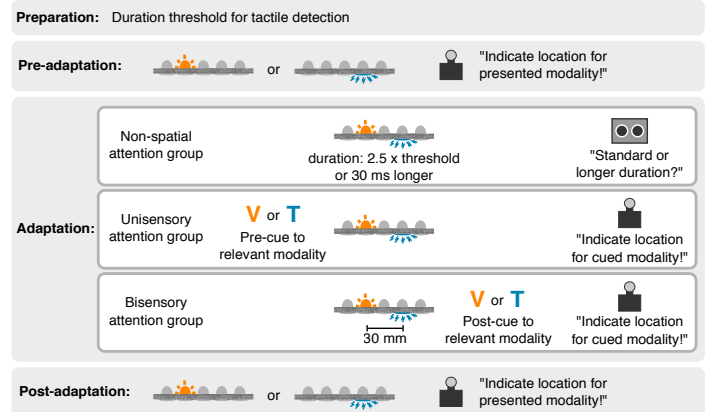
## Ventriloquist Effect: Results



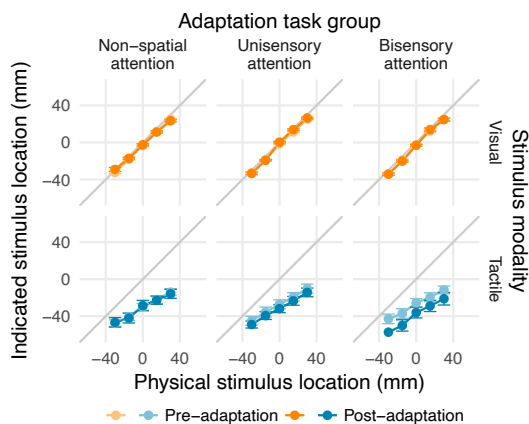
## Ventriloquism Effect: Conclusions

- A small shift of vision toward tactile - larger when both modalities are attended; no effect of perceiving a common cause
- A much larger shift of touch toward vision, maximal when a common cause is perceived. When perceived as misaligned, there is a larger shift when both modalities are attended
- A weak link between vision and touch is strengthened when both modalities are attended

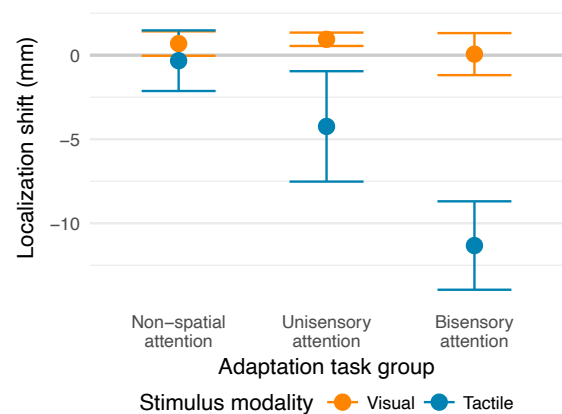
## Ventriloquist Aftereffect: Procedure



## Ventriloquist Aftereffect: Results



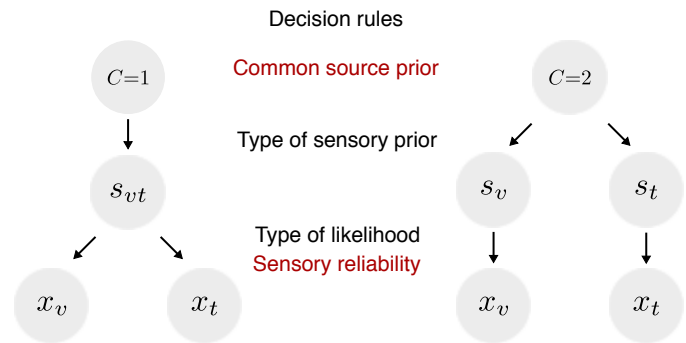
## Ventriloquist Aftereffect: Results



## Ventriloquism Aftereffect: Conclusions

- No recalibration of vision (when tested vs. visual cursor)
- Recalibration of touch significant only when both modalities' locations must be attended
- Is this due to the degree of integration during the adaptation phase?

## Ventriloquism Effect: Models



## Ventriloquism Effect: Models

- Signals:  $s_v, s_t$
- Noisy measurements:  $x_t \sim N(s_t, \sigma_t^2)$ ,  $x_v \sim N(s_v, \sigma_v^2)$
- Number of causes  $C = 1$  or  $2$
- Priors, possibly different for visual, tactile or combined
- Tactile priors possibly bimodal (e.g., centered on wrist and elbow)
- Ideal observer uses Bayesian inference and model averaging over  $C = 1$  and  $C = 2$
- Late noise on observer's estimates
- Measurements are unobservable; to predict responses, integrate over possible measurements

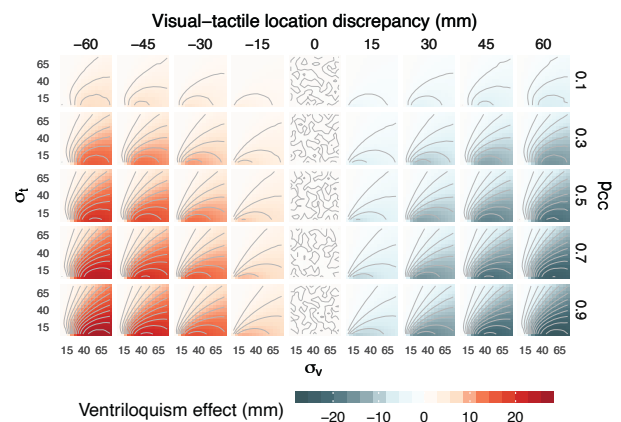
## Ventriloquism Effect: Models

- Effect of modality-specific attention on  $\sigma_t^2, \sigma_v^2, p_{CC}$
- Location estimate models: model averaging, or report integrated estimate when measurements or independent estimates are sufficiently close
- Common-cause decision models: Say " $C = 1$ " when  $p(C = 1 | x_v, x_t) > 0.5$  or when measurements or independent estimates are sufficiently close

## Ventriloquism Effect: Models

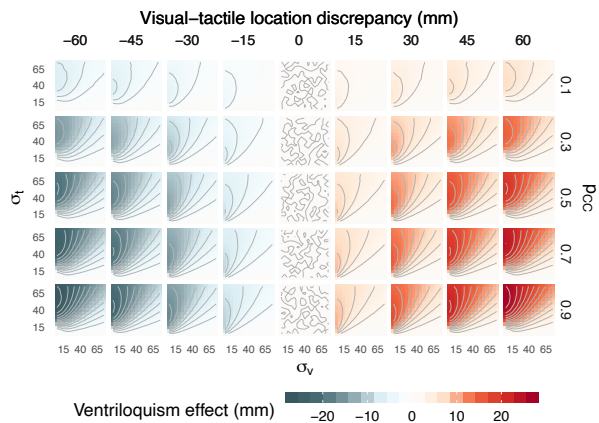
- The winning model (using AIC) was the same for the unisensory and bisensory attention groups
- Localization responses based on the ideal observer, but common-cause judgments based on a heuristic: the distance between the unisensory location estimates
- Required shifted likelihoods and a bimodal tactile prior

## Ventriloquism Model Simulations: Visual Shifts

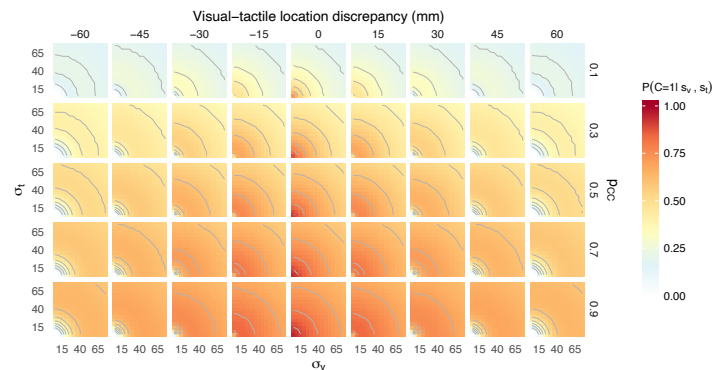




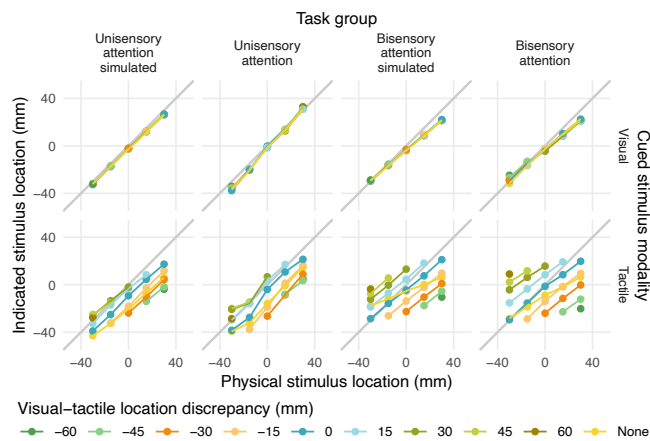
### Ventriloquism Model Simulations: Tactile Shifts



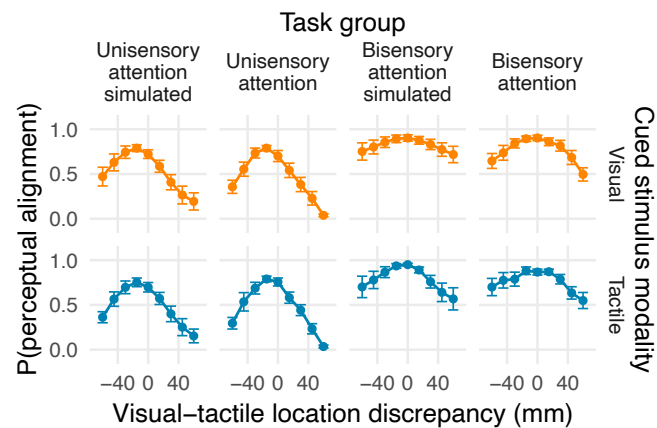
### Ventriloquism Model Simulations: Perceived Spatial Alignment



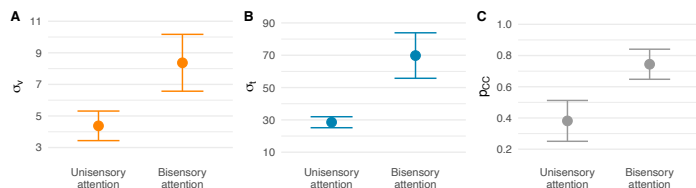
### Ventriloquist Effect: Modeling



### Ventriloquist Effect: Modeling



### Ventriloquist Effect: Modeling



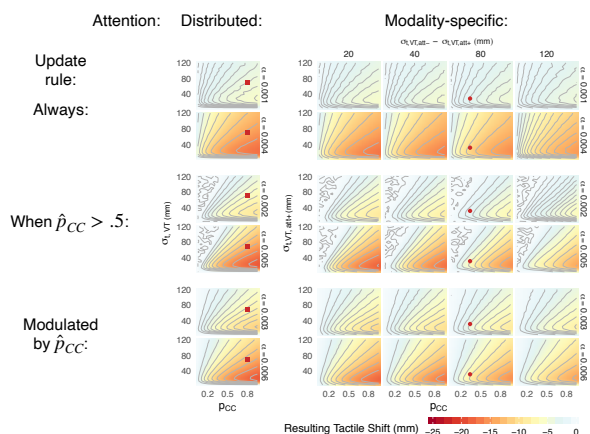
### Ventriloquism Effect: Modeling Results

- Model fits indicate that bisensory attention increases sensory noise (perhaps due to limited capacity) and increases the assumed prior probability of a common cause

## Ventriloquism Aftereffect: Models

- On each trial, likelihood shifts are updated based on the discrepancy between cue measurements and estimates
- Cue estimates depend on measurements, priors, and the estimated probability of a common cause
- Updates can occur
  - Always
  - Only when the probability of a common cause  $> 0.5$
  - Always, but modulated by the probability of a common cause

## Ventriloquist Aftereffect: Modeling



## Ventriloquism Aftereffect: Model Results

- All three models predict greater recalibration with larger  $p_{CC}$  and update rate ( $\alpha$ )
- The dependence of recalibration on reliability (of both the attended and unattended tactile stimulus) is non-monotonic: For higher tactile reliability, reducing tactile reliability leads to greater tactile recalibration, but when reliability is low enough, reducing it further leads to *less* recalibration (as a result of noisier measurements and the effects of causal inference)

## Ventriloquism Aftereffect: Model Results

- All three models predict greater recalibration in the bisensory attention condition
- However, only the second model, in which updates only occur if the estimated probability of a common cause is high, predicts an effect large enough to accord with the observed results

## Conclusions

- The ventriloquist effect and aftereffect have analogues for combinations of visual and tactile stimuli
- Visual attention has substantial contributions to both effects
- Attention to a cue contributes in two ways
- The affect of attention on reliability/discriminability is well-known
- However, the strongest contribution of attention is surprising: it strengthens the “prior” of the two cues as having a common cause, thus “priors” aren’t really prior, but depend on context/state variables

## Tactile/Proprioceptive Integration



## Tactile/Proprioceptive Integration



## Tactile/Proprioceptive Integration

Vector sum  
(not average)



## Tactile/Proprioceptive Integration

## Apparatus

Vector sum  
(not average)



Ideal Observer:

Proprioceptive:

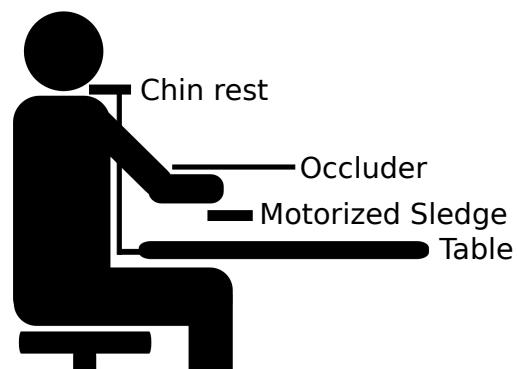
$$\hat{x}_p \sim N(\mu_p, \sigma_p^2)$$

Tactile:

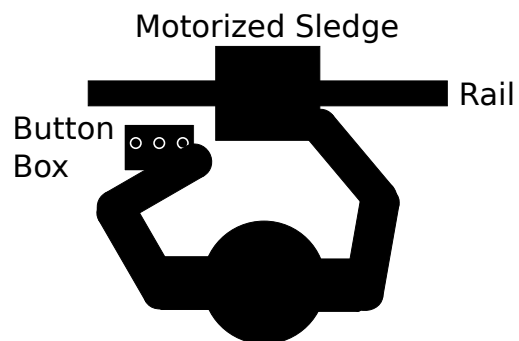
$$\hat{x}_t \sim N(\mu_t, \sigma_t^2)$$

Combined:

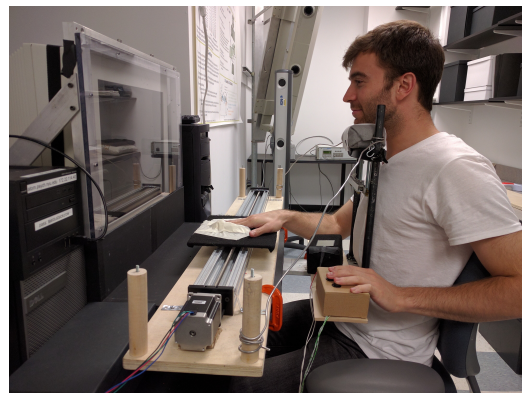
$$\hat{x}_c \sim N(\mu_p + \mu_t, \sigma_p^2 + \sigma_t^2)$$



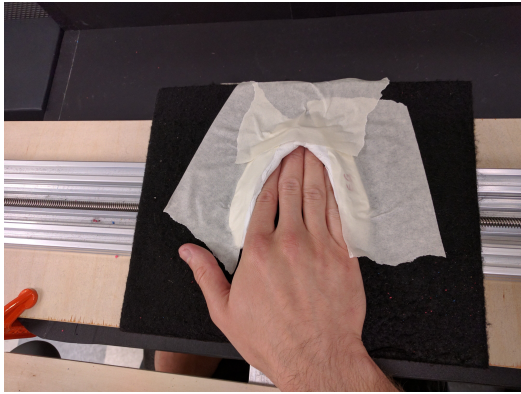
## Apparatus



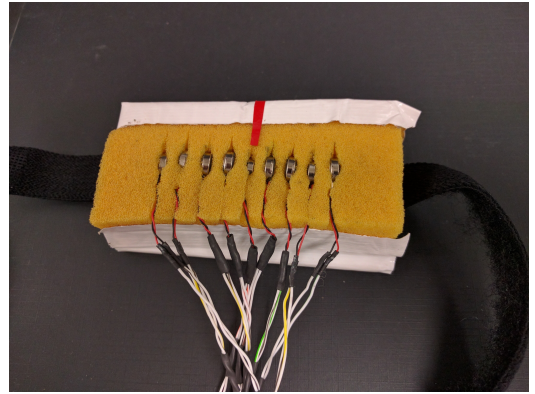
## Apparatus



Apparatus



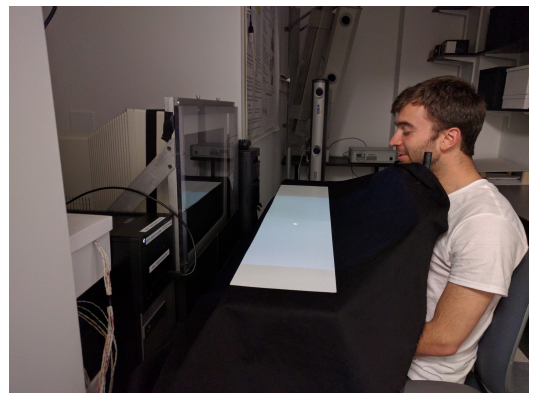
Apparatus



Apparatus



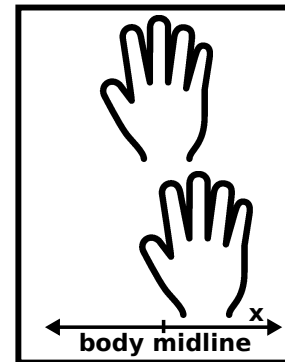
Apparatus



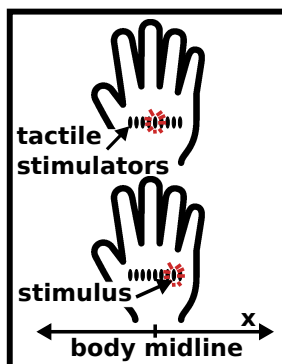
## Expt. 1: Location Discrimination

- Left-right location discrimination
- Determine whether predictions of vector-sum model hold

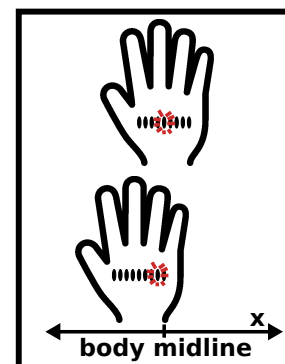
### Task - Proprioceptive



### Task - Tactile



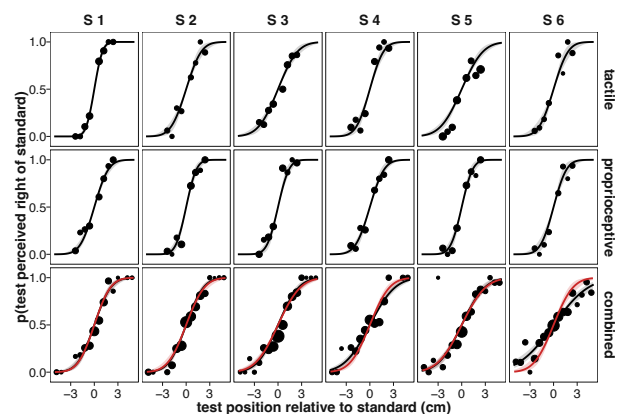
### Task - Combined



## Task

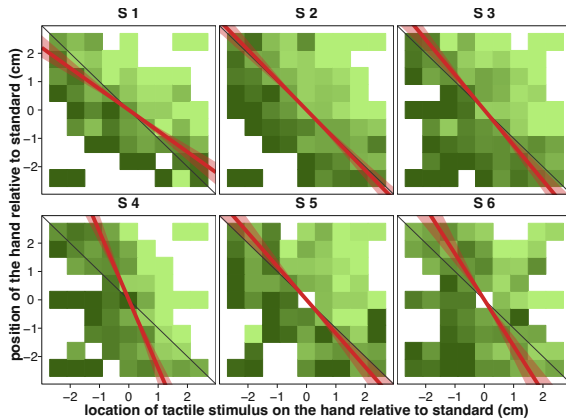
- 2IFC spatial discrimination
- One interval at midline, other varied
- Procedure (combined condition)
  - Mold moves to new location
  - Insert hand
  - One buzzer stimulated
  - Remove hand to pressure plate, hit button
  - Repeat for interval 2
  - Choose rightmost using button box
- White noise in headphones

## Data

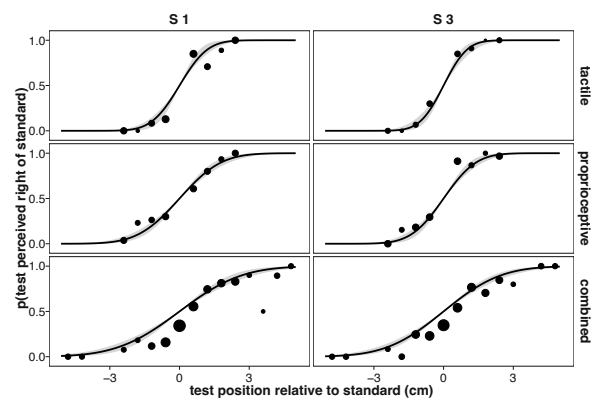




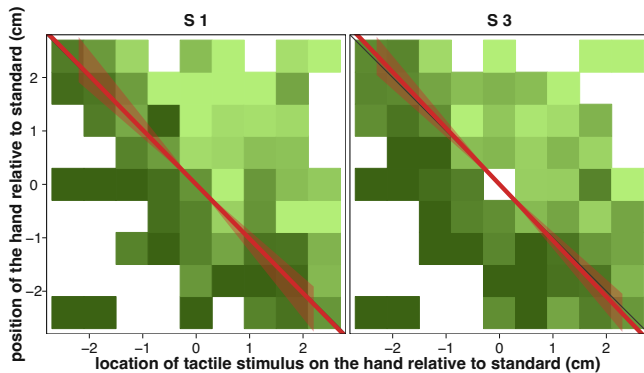
## Data



## Data - Palm



## Data - Palm



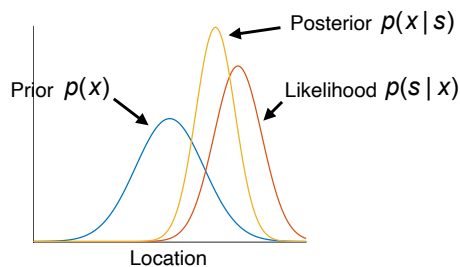
## Conclusions

- Slopes of psychometric functions are indistinguishable from optimal (variances sum)
- Yet, observers give the more reliable cue higher weight in a circumstance where that is irrational

## Just-so Story

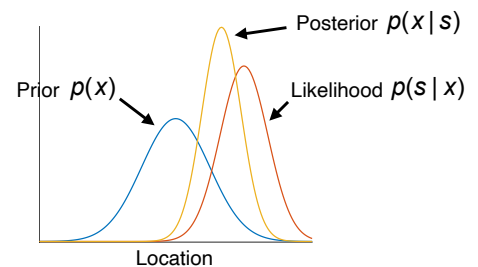
- Perceptual estimates combine sensory and prior information, i.e., is Bayesian:

$$P(x|s) \propto p(s|x)p(x)$$



## Just-so Story

- Perceptual estimates combine sensory and prior information, i.e., is Bayesian.
- The posterior/estimate “regresses” to the prior.



## Just-so Story

- Perceptual estimates combine sensory and prior information, i.e., is Bayesian.
- The posterior/estimate “regresses” to the prior.
- Thus, if proprioception is more precise than haptic localization, the proprioceptive estimate will regress to its prior less than the haptic estimate and, once combined, will appear to have higher weight.