## Decoding

#### Statistical Analysis and Modeling of Neural Data Eero Simoncelli 10 October 2007

#### the scientist's perspective

P(spikes | stim)



#### the organism's perspective

P(stim | spikes)

The organism receives sensory responses, and must make judgements about the stimulus, remember it, or act on it.

#### the organism's perspective

P(stim | spikes)

[the homunculus, from "Men in Black"]

#### the organism's perspective



#### [the homunculus, from "Men in Black"]

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  - two neurons: linear discriminators, correlations



"vector" decoding [Kalaska, Caminiti Georgopoulous, 1983]

A sum of vectors, weighted by firing rate, predicts arm movement...





Response to wind direction of 4 cercal cricket interneurons [Theunissen & Miller '91]

#### Linear population decoding, cricket cercal interneurons [Salinas & Abbott '94]



- ML for independent Poisson neurons
- ML with Gaussian tuning curves
- ML with von Mises tuning curves
- "vector rule" with cosine tuning curves
- OLE
- Cramer-Rao Bound



For neurons with homogeneous tuning curves  $f_k(x)$  and independent Poisson spiking, ML gives:

$$\frac{\partial}{\partial x}\log p(N_k|x) = \sum_k N_k \frac{\partial}{\partial x}\log f_k(x) = 0$$

In the special case of Gaussian tuning curves, ML estimate is simply a sum of the peak locations of each tuning curve, weighted by the number of spikes

$$\hat{x} = \frac{\sum_k N_k x_k}{\sum N_k}$$

In the special case of von Mises tuning curves (exponential of cosine), ML estimate is angle of a vector computed as the weighted sum of unit vectors in the peak direction of each tuning curve, weighted by the number of spikes

$$\hat{\theta} = \angle \sum_{k} N_k u_k$$



Salinas & Abbott, '94



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**Figure 4**. Inferences with gain encoding. (a) Idealized Gaussian tuning curves to orientation for 16 cells in primary visual cortex. (b) Response of 64 cells with Gaussian tuning curves similar to the ones shown in (a), in response to an orientation of  $-20^{\circ}$ . The cells have been ranked according to their preferred orientation and the responses have been corrupted by independent Poisson noise, a good approximation of the noise observed *in vivo*. (c) The posterior distribution over orientation obtained from applying a Bayesian decoder to the noisy hills shown in (b). With independent Poisson noise, the peak of the distribution is given by the peak of the noisy hill, and the width of the distribution (i.e. the uncertainty) is inversely proportional the amplitude of the noisy hill. Adapted from Ref. [47].

#### - Knill & Pouget, 2005

#### Cramer-Rao Bound

$$\sigma_{\text{est}}^2 \ge \frac{[1 + b_{\text{est}}'(s)]^2}{I_F(s)}$$

$$b_{\text{est}}(s) = \mathbf{E}(\hat{s}(s)) - s$$

$$I_F(s) = \mathbf{E} \left[ -\frac{\partial^2 \log p(r|s)}{\partial s^2} \right]$$

$$I = -E\left[\frac{\partial^{2} \ln P(\mathbf{A} | \theta)}{\partial \theta^{2}}\right]$$

$$P(\mathbf{A} | \theta) = \prod_{i=1}^{n} P(a_{i} = k_{i} | \theta) = \prod_{i=1}^{n} \frac{f_{i}(\theta)^{k_{i}} e^{-f_{i}(\theta)}}{k_{i}!}$$

$$\ln P(\mathbf{A} | \theta) = \sum_{i=1}^{n} k_{i} \ln f_{i}(\theta) - f_{i}(\theta) - \ln (k_{i}!)$$

$$\frac{\partial \ln P(\mathbf{A} | \theta)}{\partial \theta} = \sum_{i=1}^{n} \frac{k_{i} f_{i}'(\theta)}{f_{i}(\theta)} - f_{i}'(\theta)$$

$$\frac{\partial^{2} \ln P(\mathbf{A} | \theta)}{\partial \theta^{2}} = \sum_{i=1}^{n} -\frac{k f_{i}'(\theta)^{2}}{f_{i}(\theta)^{2}} + \frac{k_{i} f_{i}''(\theta)}{f_{i}(\theta)} - f_{i}''(\theta)$$

$$-E\left[\frac{\partial^{2} \ln P(\mathbf{A} | \theta)}{\partial \theta^{2}}\right] = \sum_{i=1}^{n} \frac{f_{i}(\theta) f_{i}'(\theta)^{2}}{f_{i}(\theta)^{2}} - \frac{f_{i}(\theta) f_{i}''(\theta)}{f_{i}(\theta)} + f_{i}''(\theta)$$

$$I = \sum_{i=1}^{n} \frac{f_{i}'(\theta)^{2}}{f_{i}(\theta)}$$



Fisher Information of model neuron, assuming Poisson firing, Gaussian tuning

#### Linear temporal decoding [Rieke etal, 1997]



