

Mathematical Tools
for Neural and Cognitive Science

Fall semester, 2023

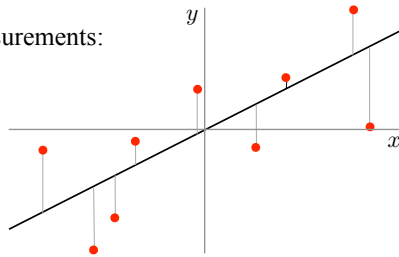
Section 2: Least Squares

Least squares regression:

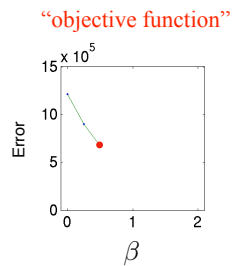
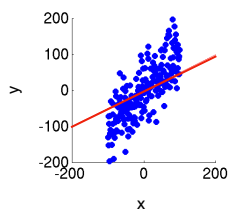
$$\min_{\beta} \sum_n (y_n - \beta x_n)^2$$

“objective” or “error”
function

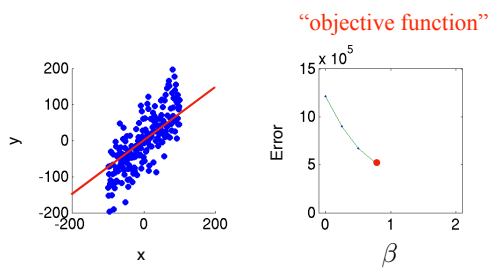
In the space of measurements:



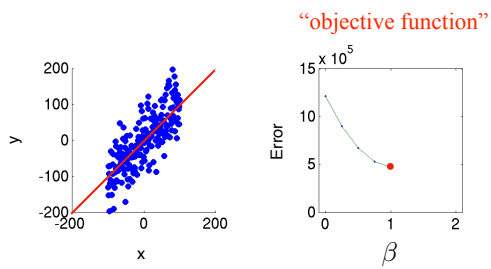
[Gauss, 1795 - age 18!]



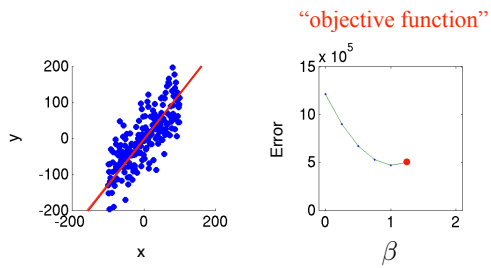
$$\sum_n (y_n - \beta x_n)^2$$



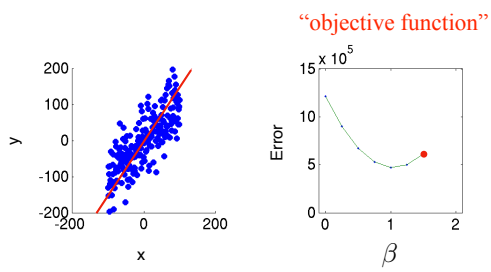
$$\sum_n (y_n - \beta x_n)^2$$



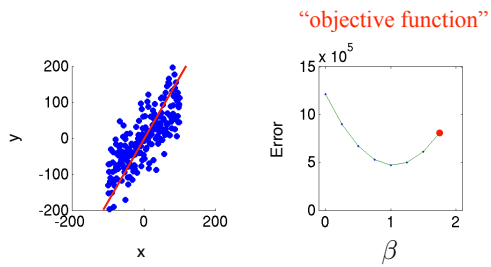
$$\sum_n (y_n - \beta x_n)^2$$



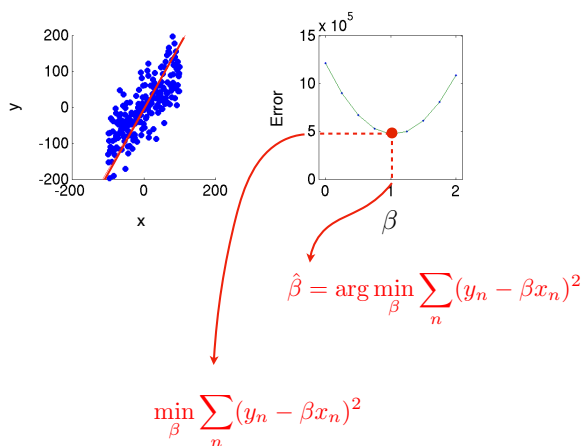
$$\sum_n (y_n - \beta x_n)^2$$



$$\sum_n (y_n - \beta x_n)^2$$



$$\sum_n (y_n - \beta x_n)^2$$

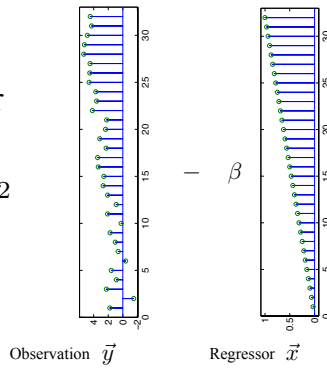


$$\min_{\beta} \sum_n (y_n - \beta x_n)^2$$

can solve this with
calculus... [on board]

... or, with linear
algebra!

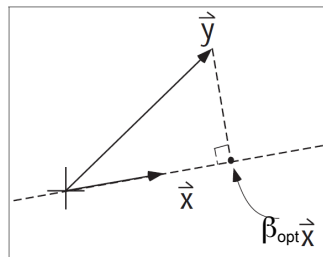
$$\min_{\beta} \|\vec{y} - \beta \vec{x}\|^2$$



$$\min_{\beta} \|\vec{y} - \beta \vec{x}\|^2$$

Geometry:

Note: this is a 2-D cartoon
of the N-D vectors, not the
two-dimensional (x,y)
measurement space of
previous plots!

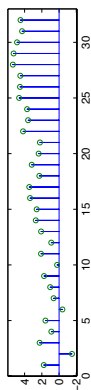


Note: partition of sum of squared data values:

$$\|\vec{y}\|^2 = \underbrace{\|\beta_{\text{opt}} \vec{x}\|^2}_{\text{explained}} + \underbrace{\|\vec{y} - \beta_{\text{opt}} \vec{x}\|^2}_{\text{residual}}$$

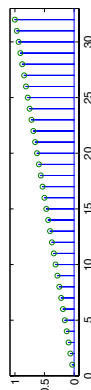
Observation

$\vec{y}$



Regressor

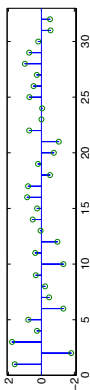
$\vec{x}$



- β

=

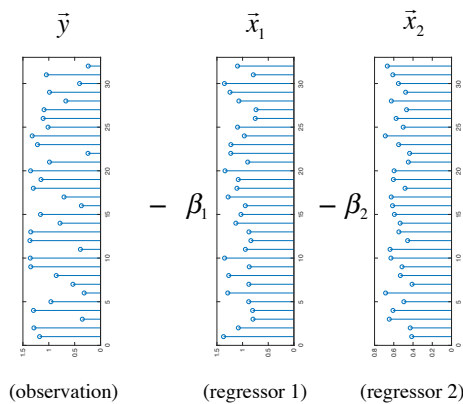
Residual
error



Multiple regression:

$$\min_{\vec{\beta}} \|\vec{y} - \sum_k \beta_k \vec{x}_k\|^2 = \min_{\vec{\beta}} \|\vec{y} - X\vec{\beta}\|^2$$

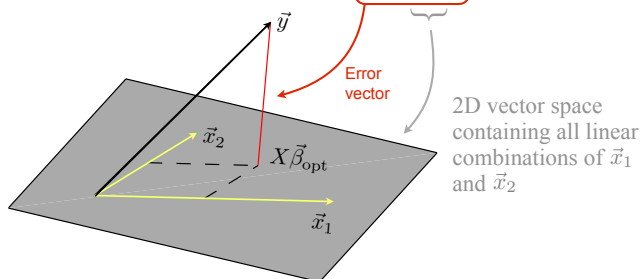
2D example:



Solution via the “Orthogonality Principle”:

Construct matrix X , containing columns $\vec{x}_1$ and $\vec{x}_2$

Orthogonality: $X^T(\vec{y} - X\vec{\beta}) = \vec{0}$



Alternatively, can solve using SVD...

$$\begin{aligned} \min_{\vec{\beta}} \|\vec{y} - X\vec{\beta}\|^2 &= \min_{\vec{\beta}} \|\vec{y} - USV^T\vec{\beta}\|^2 \\ &= \min_{\vec{\beta}} \|U^T\vec{y} - SV^T\vec{\beta}\|^2 \\ &= \min_{\vec{\beta}^*} \|\vec{y}^* - S\vec{\beta}^*\|^2 \end{aligned}$$

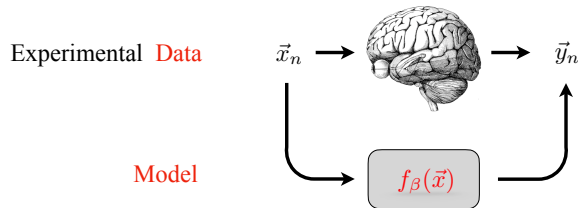
where $\vec{y}^* = U^T\vec{y}$, $\vec{\beta}^* = V^T\vec{\beta}$

Solution: $\beta_{\text{opt},k}^* = y_k^*/s_k$, for each k

or $\vec{\beta}_{\text{opt}}^* = S^\# \vec{y}^* \Rightarrow \vec{\beta}_{\text{opt}} = VS^\#U^T\vec{y}$

[on board: transformations, elliptical geometry]

Fitting a parametric model (general)



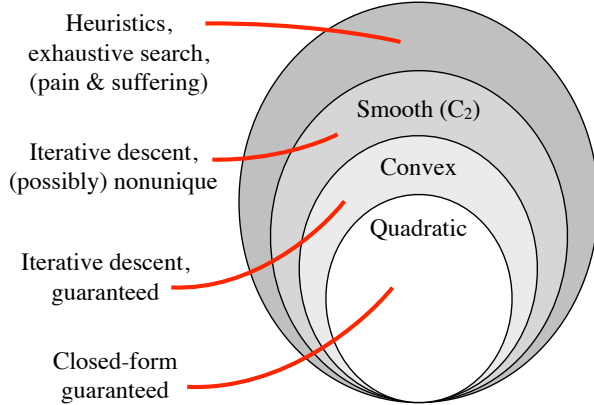
To fit model $f_{\beta}(\vec{x})$ to data $\{\vec{x}_n, \vec{y}_n\}$,

optimize parameters β to minimize an error function:

$$\min_{\beta} \sum_n E(\vec{y}_n, f_{\beta}(\vec{x}_n))$$

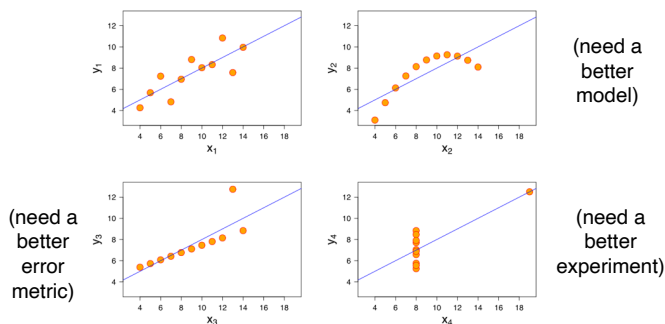
Ingredients: data, model, error function, optimization method

Optimization



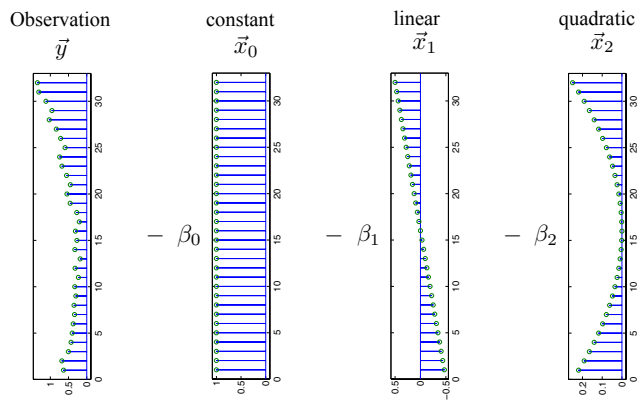
Interpretation warning: fitting a line does not guarantee data actually lie along a line

These 4 data sets give the same regression fit, and same error:

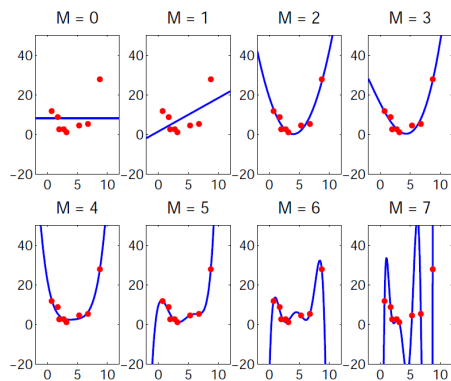


[Anscombe, 1973]

Polynomial regression



Polynomial regression - how many terms?



(to be continued, when we get to “statistics”...)

Weighted Least Squares

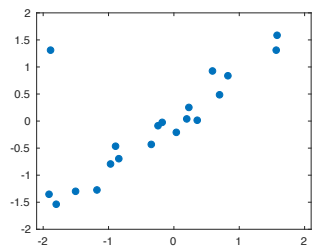
$$\min_{\beta} \sum_n [w_n(y_n - \beta x_n)]^2$$

$$= \min_{\beta} ||W(\vec{y} - \beta \vec{x})||^2$$

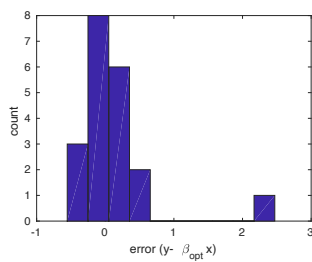
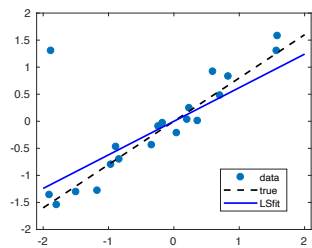
diagonal matrix

Solution via simple extensions of basic regression solution
(i.e., let $\vec{y}^* = W\vec{y}$ and $\vec{x}^* = W\vec{x}$ then solve for β)

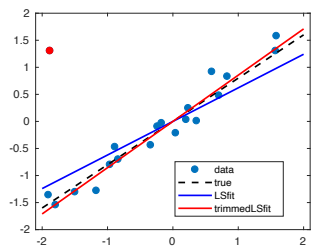
Outliers



Outliers

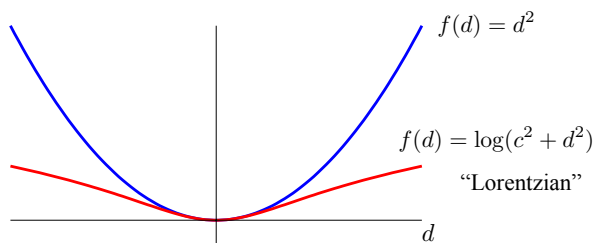


“Trimming”... discard points with large error
(note: a special case of weighted least squares)



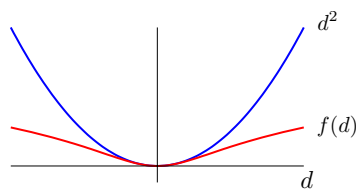
Trimming can be done iteratively (discard outlier, re-fit, repeat), a so-called “greedy” method. When should you stop?

More generally, use a “robust” error metric.
For example:



Note: generally can’t obtain solution directly (i.e., requires an iterative optimization procedure, such as gradient descent).
In some cases, can use iteratively re-weighted least squares (IRLS)...

Iteratively Re-weighted Least Squares (IRLS)



initialize: $w_n^{(0)} = 1$

$$\beta^{(i)} = \arg \min_{\beta} \sum_n \omega_n^{(i)} (y_n - \beta x_n)^2$$

iterate

$$\omega_n^{(i+1)} = \left| \frac{f'(y_n - \beta^{(i)} x_n)}{y_n - \beta^{(i)} x_n} \right|$$

iterate

(one of many variants)

Constrained Least Squares

Linear constraint:

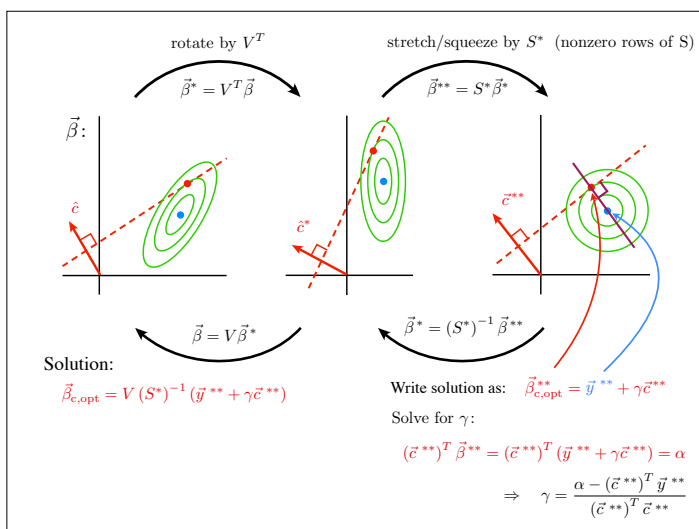
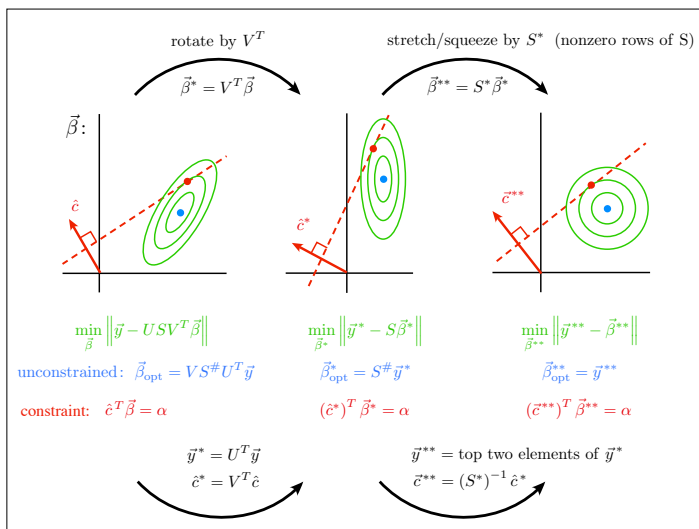
$$\arg \min_{\vec{\beta}} \left\| \vec{y} - X\vec{\beta} \right\|^2, \quad \text{where } \vec{c}^T \vec{\beta} = 1$$

Quadratic constraint:

$$\arg \min_{\vec{\beta}} \left\| X\vec{\beta} \right\|^2, \quad \text{where } \left\| \vec{\beta} \right\|^2 = 1$$

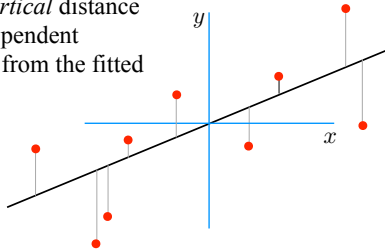
Can be solved exactly using linear algebra (SVD)...

[on board, with geometry]



Standard Least Squares regression

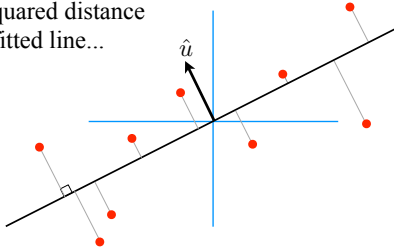
Error is *vertical* distance
(in the “dependent
variable”) from the fitted
line...



$$\arg \min_{\beta} \|\vec{y} - \beta \vec{x}\|^2$$

Total Least Squares Regression (a.k.a “orthogonal regression”)

Error is squared distance
from the fitted line...



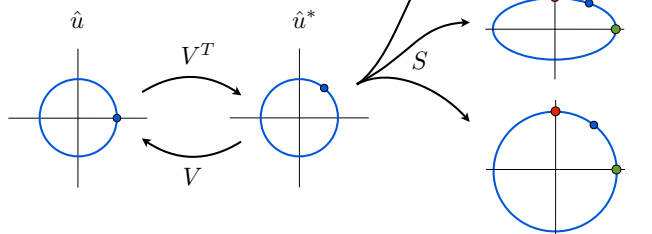
expressed as: $\min_{\hat{u}} \|D\hat{u}\|^2$, where $\|\hat{u}\|^2 = 1$

Note: “data” matrix D now includes both x and y coordinates

Variance of data D , projected onto axis $\hat{u}$:

$$\|USV^T\hat{u}\|^2 = \|SV^T\hat{u}\|^2 = \|S\hat{u}^*\|^2 = \|\vec{u}^{**}\|^2,$$

where $D = USV^T$, $\hat{u}^* = V^T\hat{u}$, $\vec{u}^{**} = S\hat{u}^*$



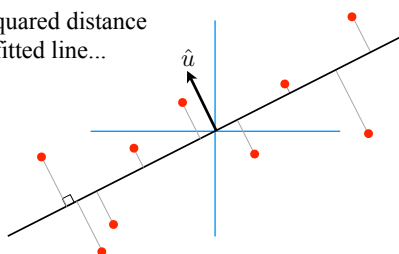
Set of $\hat{u}$'s of
length 1
(i.e., unit vectors)

Set of $\hat{u}^*$'s of
length 1
(i.e., unit vectors)

First two components
of $\vec{u}^{**}$ (rest are zero!),
for three example S 's.

Total Least Squares Regression (a.k.a “orthogonal regression”)

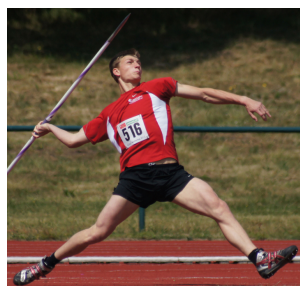
Error is squared distance
from the fitted line...



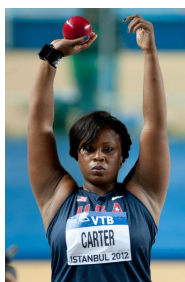
expressed as: $\min_{\hat{u}} \|D\hat{u}\|^2$, where $\|\hat{u}\|^2 = 1$

Note: “data” matrix D now includes both x and y coordinates

Olympic gold medalists
(Rio, 2016)



Thomas Röhler (Germany)



Michelle
Carter
(USA)



Sandra Perković (Croatia)

3D geometry:
Javelin, Discus, Shotput...

Principal Component Analysis (PCA)

The shape of a data cloud can be summarized with an ellipse (ellipsoid), centered around the mean, using a simple procedure:

- (1) Subtract mean of all data points, to re-center around origin
- (2) Assemble centered data vectors in rows of a matrix, D
- (3) Compute the SVD:

$$D = USV^T$$

or just use the smaller matrix $C = D^T D = VS^T SV^T = V\Lambda V^T$

- (4) Columns of V are the *principal components* (axes) of the ellipsoid, diagonal elements s_k or $\sqrt{\lambda_k}$ are the corresponding principle radii, and their product is the volume.

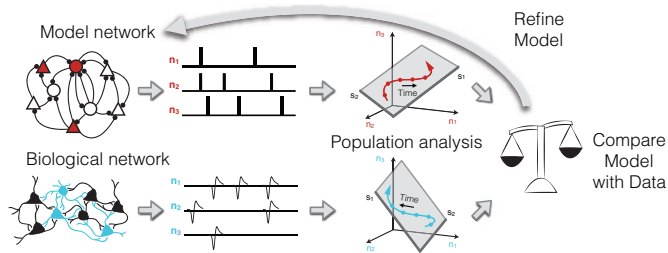
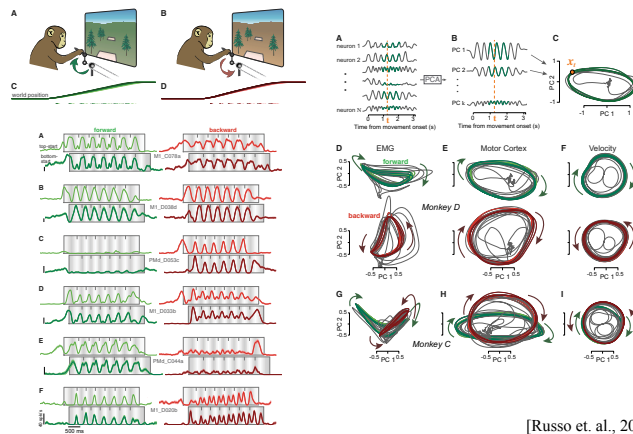


Fig 1. Relating biological and model networks using population analyses: Because a model network typically does not attempt to replicate the precise anatomical connectivity of a biological network, there is not a one-to-one correspondence of each biological neuron with a model neuron. Dimensionality reduction can be used to obtain a concise summary of the population activity from each network. This provides common ground for incisive comparisons between biological and model networks. Discrepancies in the population activity structure between biological and model networks can then help to refine model networks.

[Williamson, Doiron, Smith, Yu 2019]

Example: PCA for dimensionality reduction and visualization



[Russo et. al., 2018]

Eigenvectors/eigenvalues

- An *eigenvector* of a matrix is a vector that is rescaled by the matrix (i.e., the direction is unchanged)
- The corresponding scale factor is called the *eigenvalue*
- For matrix $C = D^T D = V \Lambda V^T$ the columns of V (denoted $\hat{v}_k$) are eigenvectors, with corresponding eigenvalues λ_k :

$$\begin{aligned} C \hat{v}_k &= V \Lambda V^T \hat{v}_k \\ &= V \Lambda \hat{e}_k \\ &= \lambda_k \hat{v}_k \end{aligned}$$