Mathematical Tools for Neural and Cognitive Science

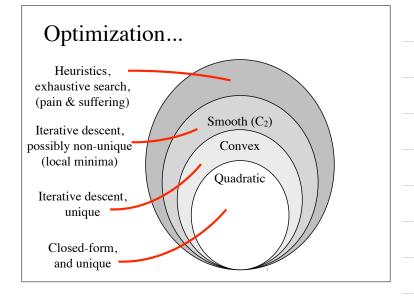
Fall semester, 2020

Section 6

Model fitting: comparison, selection and regularization

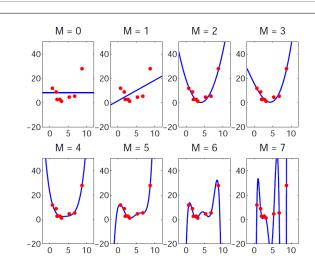
Taxonomy of model-fitting errors

- Unexplainable variability (due to finite/noisy measurements)
- Overfitting (too many params, not enough data)
- Optimization failures (e.g., local minima)
- Model failures (what you'd really like to know)



Model Comparison

- If models are optimized according to some objective, it is natural to compare them based on the value of that objective...
 - for least squares regression, compare the residual squared error of two models (with different regressors).
 - for ML estimates, compute the likelihood (or log likelihood) ratio, and compare to 1 (or zero).
 - for MAP estimates, common to compute the posterior ratio (a.k.a. the *Bayes factor*)
- **Problem**: evaluating the objective with the same data used to optimize the model leads to over-fitting! We really want to predict error on non-training data...



How do we avoid overfitting (i.e., concluding that M=7 is "best")?

Comparing models' predictive performance

Option 1: Include a penalty for number of parameters:

For an ML estimate: $\hat{\theta} = \arg\min_{a} p(\overrightarrow{d} \mid \theta)$

a. Compare Akaike information criterion (AIC) [Akaike, 1974]

$$E_{\text{AIC}}(\overrightarrow{d}, \hat{\theta}) = 2 \dim(\hat{\theta}) - 2 \ln(p(\overrightarrow{d} \mid \hat{\theta}))$$

b. Compare Bayesian information criterion (BIC) [Schwartz, 1978]

$$E_{\text{BIC}}(\overrightarrow{d}, \hat{\theta}) = \dim(\hat{\theta}) \ln\left(\dim(\overrightarrow{d})\right) - 2\ln\left(p(\overrightarrow{d}|\hat{\theta})\right)$$

valid when $\dim(\overrightarrow{d}) >> \dim(\hat{\theta})$

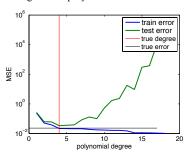
Option 2: Cross-validation: partition data into two subsets, fit parameters to "training" subset, evaluate objective on "test" subset.

Cross-validation

A resampling method for estimating predictive error of a model. Widely used to identify/avoid over-fitting, and to provide a fair comparison of models.

- (1) Randomly partition data into a "training" set, and a "test" set.
- (2) Fit model to training set. Measure error on test set.
- (3) Repeat (many times)
- (4) Choose model that minimizes the average crossvalidated ("test") error

Using cross-validation to select the degree of a polynomial model:



Ridge regression

(a.k.a. Tikhonov regularization)

Ordinary least squares regression:

$$\arg\min_{\vec{\beta}}||\vec{y}-X\vec{\beta}||^2$$

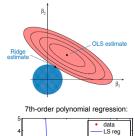
"Regularized" least squares regression:

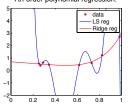
$$\arg\min_{\vec{\beta}}||\vec{y}-X\vec{\beta}||^2+\lambda||\vec{\beta}||^2$$

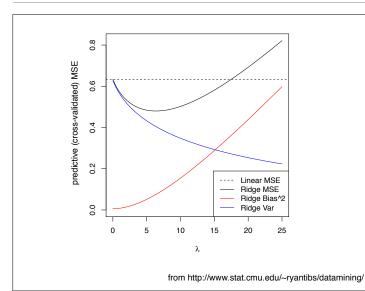
Equivalent formulation: MAP estimate, assuming Gaussian likelihood & prior!

$$\hat{\beta}_{\text{ridge}} = (X^T X + \lambda I)^{-1} X^T \vec{y}$$

Choose lambda by cross-validation:







L_1 regularization

(a.k.a. "least absolute shrinkage and selection operator" - LASSO)

$$\arg\min_{\beta}||\vec{y}-\vec{x}\beta||^2+\lambda|\beta|$$

$$\beta_{\rm OLS}$$
 Assuming $||\vec{x}||^2=1$,
$$[derivation\ on\ board]$$

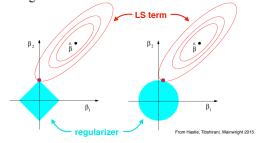
$$\beta_{\rm LASSO}$$

$$\hat{\beta}_{\rm ridge}$$
 MAP interpretation: Gaussian noise, "Laplacian" prior

multi-dimensional LASSO

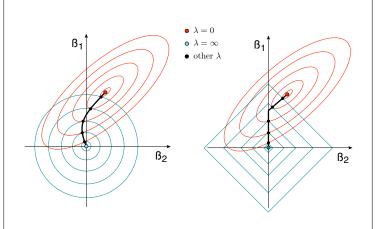
$$rg \min_{ec{eta}} ||ec{y} - X ec{eta}||^2 + \lambda \sum_{k} |eta_k|$$
 L₁ norm (still convex)

Using an absolute error regularization term promotes binary *selection* of regressors:

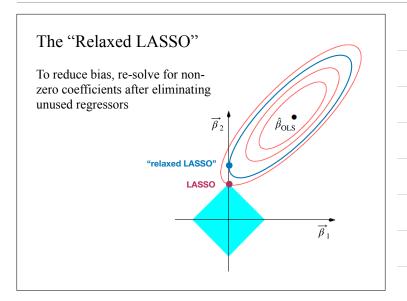


L₂ regularization

L₁ regularization



LASSO vs. ridge regression Table 2.1 Crime data: Crime rate and five predictors, for N = 50 U.S. cities. $\frac{\text{city } \text{ funding } \text{ hs } \text{ not-hs } \text{ college} \text{ colleged } \text{ crime rate } \text{ rate$



Clustering

- K-Means (Lloyd, 1957)
- "Soft-assignment" version of K-means (a form of Expectation-Maximization - EM)
- In general, alternate between:
 - 1) Estimating cluster assignments
- 2) Estimating cluster parameters
- Coordinate descent: converges to (possibly local) minimum
- Need to choose K (number of clusters) cross-validation!

K-Means algorithm - alternate between two steps:

• Estimating cluster assignments: given class centers,

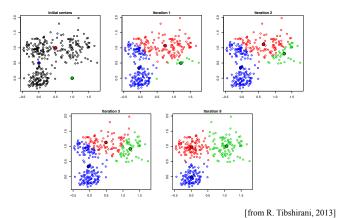
assign each point to closest one.



• Estimating cluster parameters: given assignments, reestimate the centroid of each cluster.

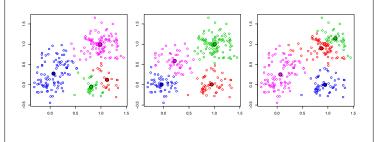
$K ext{-means example}$

Here $X_i \in \mathbb{R}^2$, n=300, and K=3

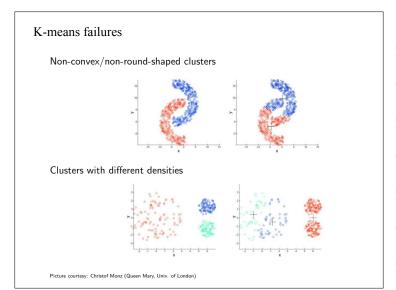


Warning: Initialization matters (due to local minima) ...

Three solutions obtained with different random starting points:



[from R. Tibshirani, 2013]



ML for discrete mixture of Gaussians: soft K-means

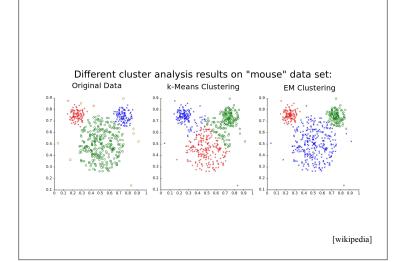
$$p(\vec{x}_n|a_{nk}, \vec{\mu}_k, \Lambda_k) \propto \sum_k \frac{a_{nk}}{\sqrt{|\Lambda_k|}} e^{-(\vec{x}_n - \vec{\mu}_k)^T \Lambda_k^{-1} (\vec{x}_n - \vec{\mu}_k)/2}$$

 a_{nk} = assignment *probability*

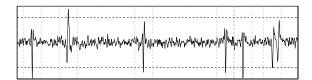
 $\{\vec{\mu}_k, \Lambda_k\}$ = mean/covariance of class k

Intuition: alternate between maximizing these two sets of variables ("coordinate descent")

Essentially, a version of K-means with "soft" (i.e., continuous, as opposed to binary) assignments!



Application to neural "spike sorting"

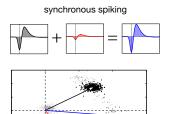


Standard solution:

- 1. Threshold to find segments containing spikes
- 2. Reduce dimensionality of segments using PCA
- 3. Identify spikes using clustering (e.g., K-means)

Note: Fails for overlapping spikes!

Failures of clustering for near-synchronous spikes



PC 1 projection

[Pillow et. al. 2013]

Clustering (K-means) CBP PC 1 PC 1 [Ekanadham et al, 2014]