

Mathematical Tools for Neural and Cognitive Science

Fall semester, 2020

Section 1: Linear Algebra

Linear Algebra

“Linear algebra has become as basic and as applicable as calculus, and fortunately it is easier”

- Gilbert Strang, *Linear Algebra and its Applications*

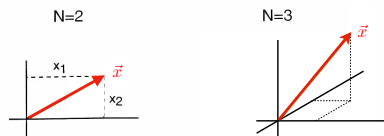
... and this is even more true today than when the book was published!

Vectors

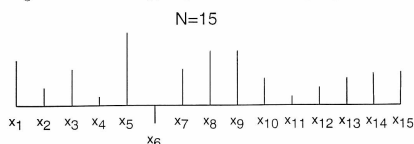
Ordered lists of numbers, depicted in 3 ways:

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_N \end{pmatrix}$$

In two or three dimensions, we can draw these as arrows:



In higher dimensions, we typically must resort to a “spike-plot”:



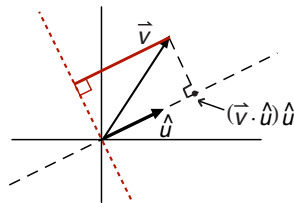
Vector operations

- scalar multiplication
- addition, vector spaces
- length, unit vectors
- inner product (a.k.a. “dot” product)
 - definition/notation: sum of pairwise products
 - geometry: cosines, orthogonality test

[on board: geometry]

Inner product with a unit vector

- projection
- distance to line
- change of coordinates



[on board: geometry]

Vectors as “operators”

- “averager”
- “windowed averager”
- “smooth averager”
- “local differencer”
- “component selector”

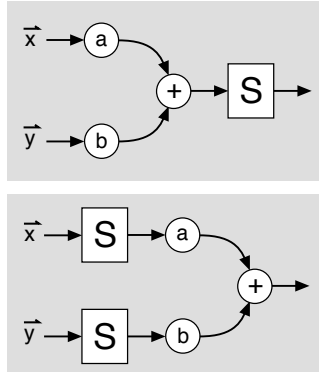
[on board]

Linear System

S is a linear system if (and only if) it obeys the **principle of superposition**:

$$S(a\vec{x} + b\vec{y}) = aS(\vec{x}) + bS(\vec{y})$$

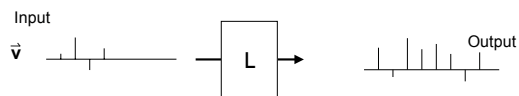
For *any* input vectors $\{\vec{x}, \vec{y}\}$, and *any* scalars $\{a, b\}$, the two diagrams at the right must produce the same response.



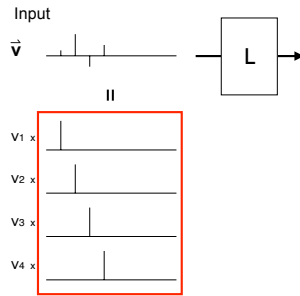
Linear Systems

- Very well understood (150+ years of effort)
- Excellent design/characterization toolbox
- An idealization (they do not exist!)
- Useful nevertheless:
 - conceptualize fundamental issues
 - provide baseline performance
 - good starting point for more complex models

Implications of Linearity

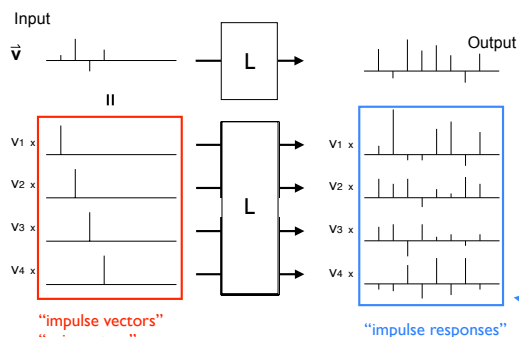


Implications of Linearity



write input vector
as weighted sum of
"impulse" vectors
"standard basis"
"axis vectors"

Implications of Linearity



"impulse vectors"
"axis vectors"
"standard basis"

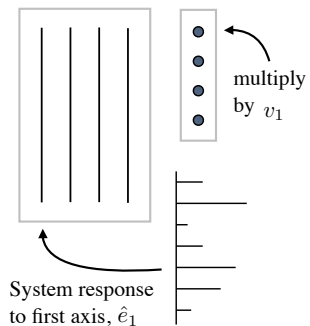
"impulse responses"

Response to *any* input can be computed from *responses to impulses*
This defines the operation of *matrix multiplication*

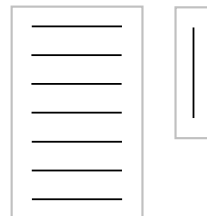
Matrix multiplication

Two different interpretations of $M\vec{v}$:

input perspective:
weighted sum of columns



output perspective:
dot product with rows



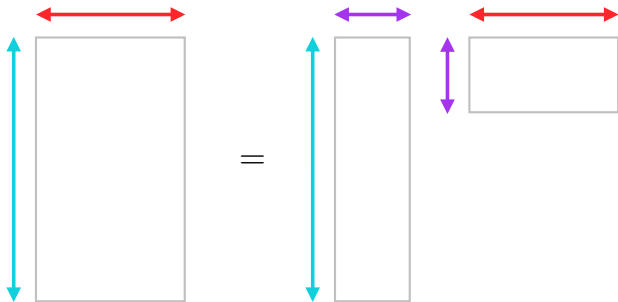
[details on board]

Matrix multiplication

- two interpretations of $M\vec{v}$:
 - input perspective: weighted sum of columns
 - output perspective: inner product with rows
- transpose A^T , symmetric matrices ($A = A^T$)
- distributive property: directly from linearity!
- associative property: cascade of two linear systems is linear. Defines matrix multiplication.

[details on board]

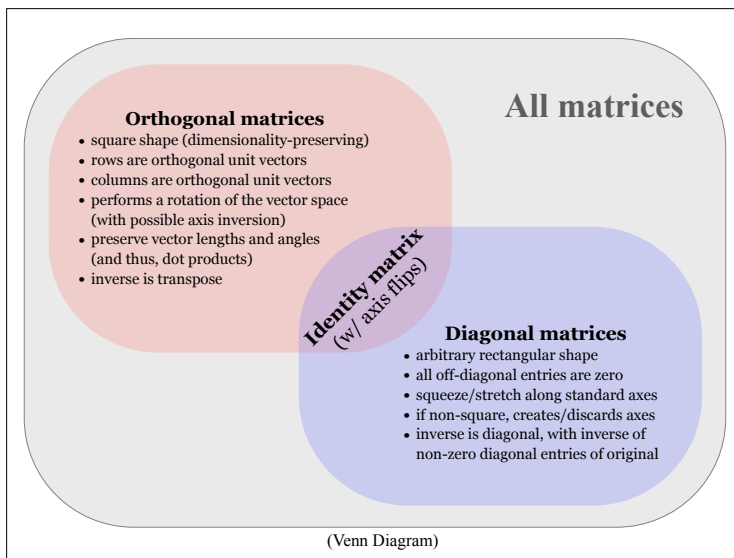
Matrix multiplication: dimensional consistency



Matrix multiplication

- two interpretations of $M\vec{v}$:
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- transpose A^T , symmetric matrices ($A = A^T$)
- distributive property: directly from linearity!
- associative property: cascade of two linear systems is linear. Defines matrix multiplication.
- generally *not* commutative ($AB \neq BA$), but note that $(AB)^T = B^T A^T$
- vectors as matrices: Inner products, Outer products

[details on board]



Singular Value Decomposition (SVD)

Any matrix can be factorized as

$$M = U S V^T$$

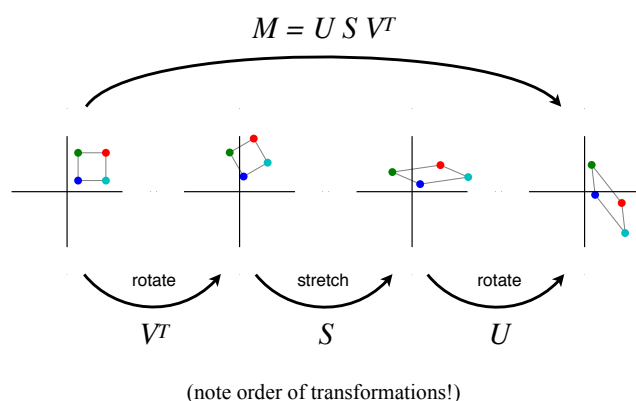
with U and V orthogonal, S diagonal.

- geometry: “rotate, stretch, rotate”
- columns of V are basis for input coordinate system
- columns of U are basis for output coordinate system
- S rescales axes, and determines what “gets through”

[details on board]

SVD geometry (in 2D)

Consider applying M to four vectors (colored points):



Singular Value Decomposition (SVD)

- interpretation: sum of “outer products”
- non-uniqueness? permutations, sign flips
- nullspace and rangespace
- inverse and pseudo-inverse

[details on board]

$$M\vec{x} = \sum_k s_k (\hat{v}_k^T \vec{x}) \hat{u}_k = \sum_k s_k (\hat{u}_k \hat{v}_k^T) \vec{x}$$

