

Mathematical Tools for Neural and Cognitive Science

Fall semester, 2019

Section 1: Linear Algebra

Linear Algebra

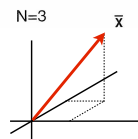
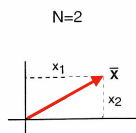
“Linear algebra has become as basic and as applicable as calculus, and fortunately it is easier”

- Gilbert Strang, *Linear Algebra and its Applications*

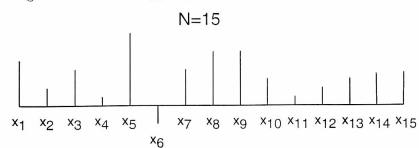
Vectors

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_N \end{pmatrix}$$

In two or three dimensions, we can draw these as arrows:



In higher dimensions, we typically must resort to a “spike-plot”:



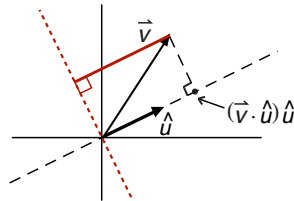
Vector operations

- scalar multiplication
- addition, vector spaces
- length, unit vectors
- inner product (a.k.a. “dot” product)
 - properties: commutative, distributive
 - geometry: cosines, orthogonality test

[on board: geometry]

Inner product with a unit vector

- projection
- distance to line
- change of coordinates



[on board: geometry]

Vectors as “operators”

- “averager”
- “windowed averager”
- “gaussian averager”
- “local differencer”
- “component selector”

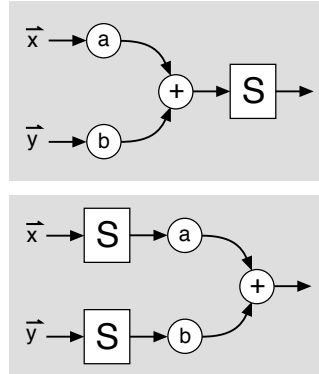
[on board]

Linear System

S is a linear system if (and only if) it obeys the **principle of superposition**:

$$S(a\vec{x} + b\vec{y}) = aS(\vec{x}) + bS(\vec{y})$$

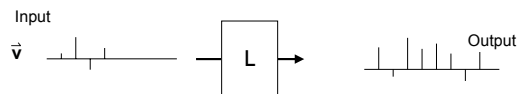
For *any* input vectors $\{\vec{x}, \vec{y}\}$ and *any* scalars $\{a, b\}$, the two diagrams at the right must produce the same response:



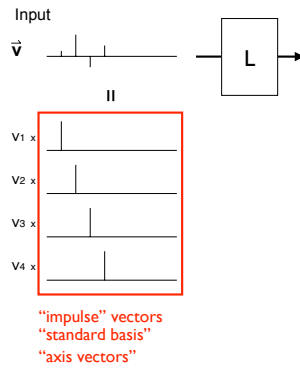
Linear Systems

- Very well understood (150+ years of effort)
- Excellent design/characterization toolbox
- An idealization (they do not exist!)
- Useful nevertheless:
 - conceptualize fundamental issues
 - provide baseline performance
 - good starting point for more complex models

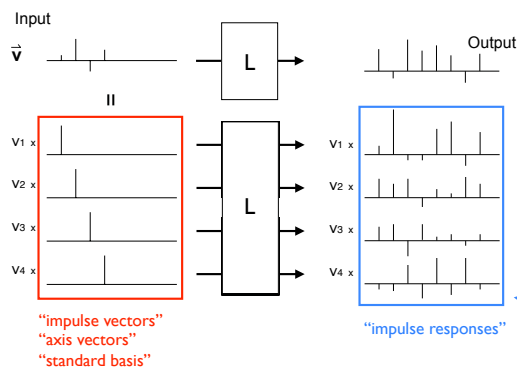
Implications of Linearity



Implications of Linearity



Implications of Linearity



Response to *any* input can be predicted from *responses to impulses*
This defines the operation of *matrix multiplication*

Matrix multiplication

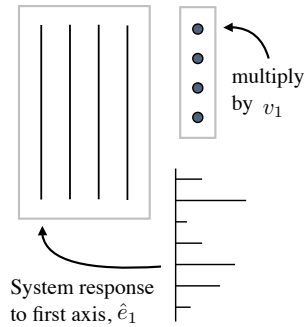
- Two interpretations of $M\vec{v}$ (see next slide):
 - input perspective: weighted sum of columns (from diagrams on previous slides)
 - output perspective: inner product with rows
- distributive property (directly from linearity!)
- associative property: cascade of two linear systems defines the product of two matrices
- transpose A^T , symmetric matrices ($A = A^T$)
- generally *not* commutative ($AB \neq BA$), but note that $(AB)^T = B^T A^T$
- Vectors: Inner products, Outer products

[details on board]

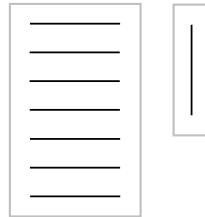
Matrix multiplication

Two interpretations of $M\vec{v}$:

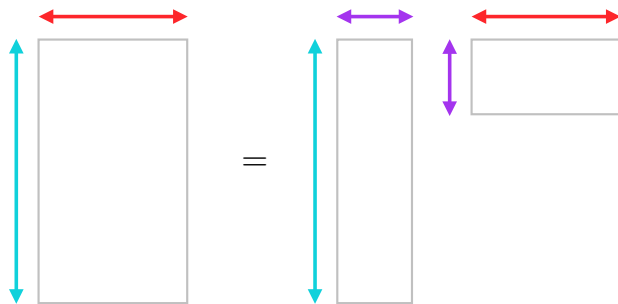
input perspective:
weighted sum of columns



output perspective:
dot product with rows



Matrix multiplication: dimensional consistency



All matrices

Orthogonal matrices

- square shape (dimensionality-preserving)
- rows are orthogonal unit vectors
- columns are orthogonal unit vectors
- performs a rotation of the vector space (with possible axis inversion)
- preserve vector lengths and angles (and thus, dot products)
- inverse is transpose

review/add:

- 1) two matrix types, each with geometric interpretation, understanding of inverse properties, "design" capabilities
- 2) geometry is about WHOLE SPACE
- 3) orthogonal: project onto orthogonal unit vectors \leftrightarrow new coordinate system. Inverse: a) rotate back, b) multiply coordinates by unit vectors (expressed in original coord system).
- 4) diagonal: loss of dimensionality: smashing things down onto subspace.

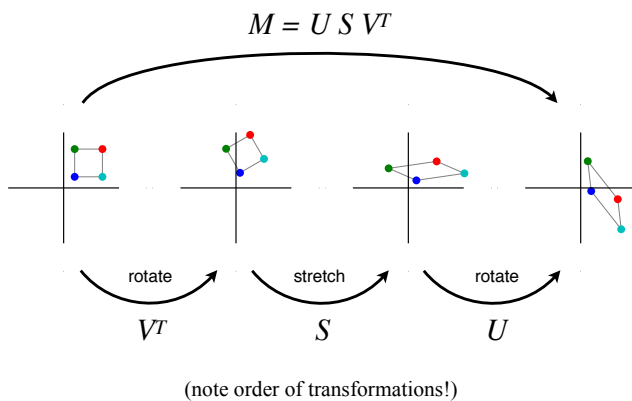
Singular Value Decomposition (SVD)

- can express *any* matrix as $M = U S V^T$
“rotate, stretch, rotate”
 - columns of V are basis for input coordinate system
 - columns of U are basis for output coordinate system
 - S rescales axes, and determines what “gets through”
- interpretation: sum of “outer products”
- non-uniqueness? permutations, sign flips
- nullspace and rangespace
- inverse and pseudo-inverse

[details on board]

SVD geometry (in 2D)

Consider applying M to four vectors (colored points)



$$M\vec{w} = \sum_k s_k (\vec{v}_k^T \vec{w}) \vec{u}_k = \sum_k s_k (\vec{u}_k \vec{v}_k^T) \vec{w}$$

Use hats instead of vectors for u,v.
make input vec(x)

