

Mathematical Tools for Neural and Cognitive Science

Fall semester, 2017

Section 1: Linear Algebra

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Linear Algebra

“Linear algebra has become as basic and
as applicable as calculus, and fortunately it
is easier”

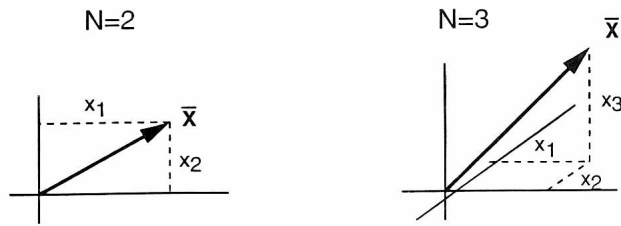
- Gilbert Strang, *Linear Algebra and its Applications*

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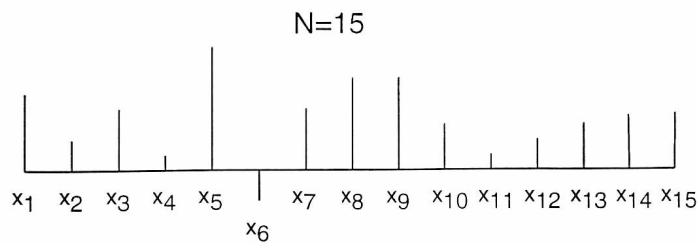
Vectors

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_N \end{pmatrix}$$

In two or three dimensions, we can draw these as arrows:



In higher dimensions, we typically must resort to a “spike-plot”:



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Vector operations

- scalar multiplication
- addition, vector spaces
- length, unit vectors
- inner product (a.k.a. “dot” product)
 - properties: commutative, distributive
 - geometry: cosines, orthogonality test

[on board: geometry]

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Vectors as “operators”

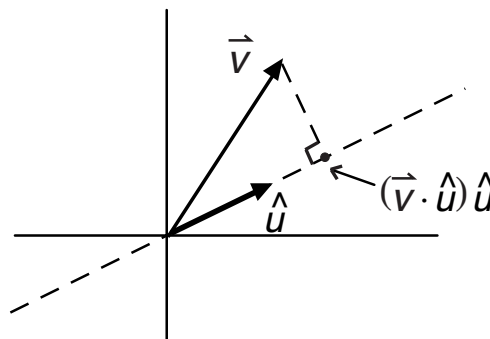
- “averager”
- “windowed averager”
- “gaussian averager”
- “local differencer”
- “component selector”

[answers on board]

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Inner product with a unit vector

- projection
- distance to line
- change of coordinates



[on board: geometry]

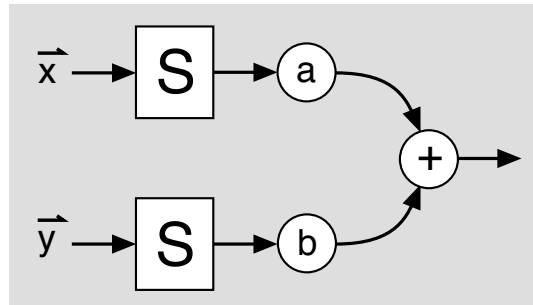
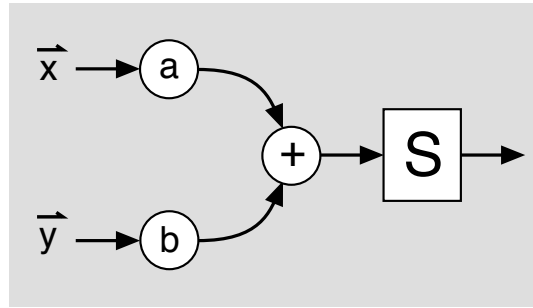
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Linear System

S is a linear system if (and only if) it obeys the **principle of superposition**:

$$S(a\vec{x} + b\vec{y}) = aS(\vec{x}) + bS(\vec{y})$$

For *any* input vectors $\{\vec{x}, \vec{y}\}$, and *any* scalars $\{a, b\}$, the two diagrams at the right must produce the same response:



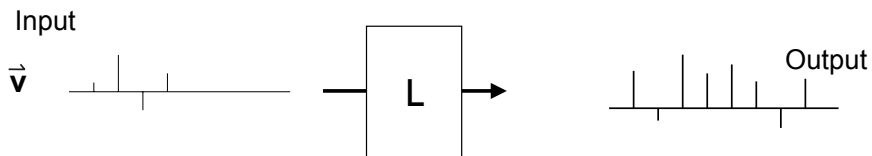
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Linear Systems

- Very well understood (150+ years of effort)
- Excellent design/characterization toolbox
- An idealization (they do not exist!)
- Useful nevertheless:
 - conceptualize fundamental issues
 - provide baseline performance
 - good starting point for more complex models

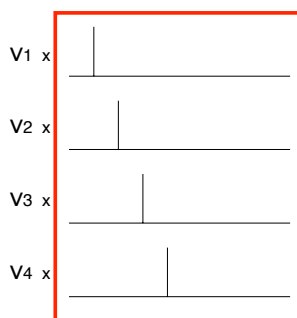
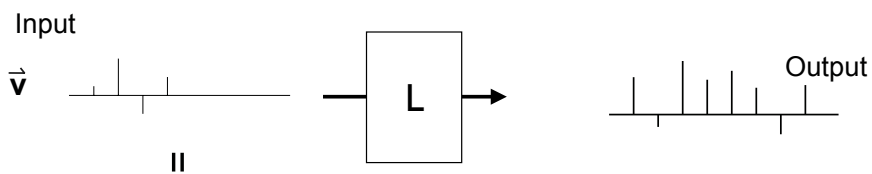
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Implications of Linearity



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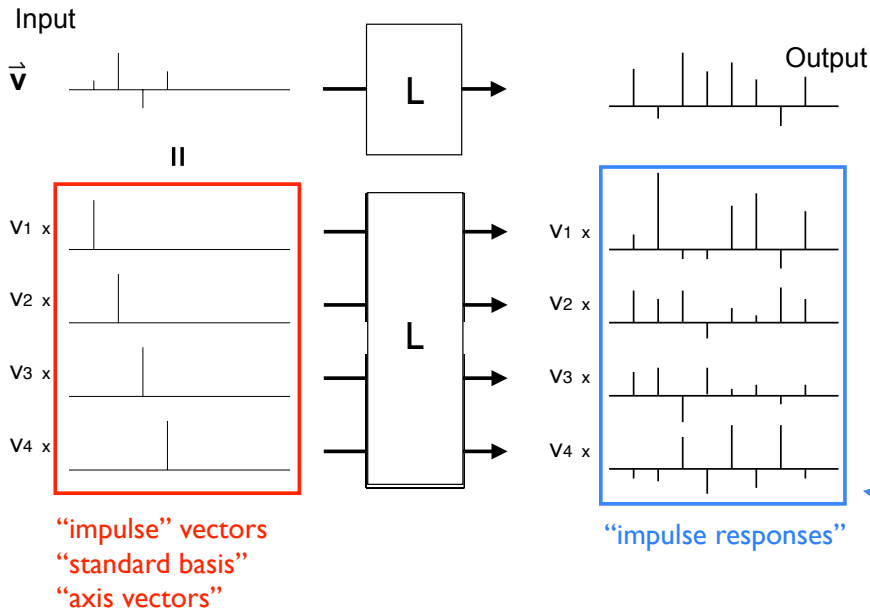
Implications of Linearity



“impulse” vectors
“standard basis”
“axis vectors”

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Implications of Linearity



Response to *any* input can be predicted from **responses to impulses**
This defines the operation of *matrix multiplication*

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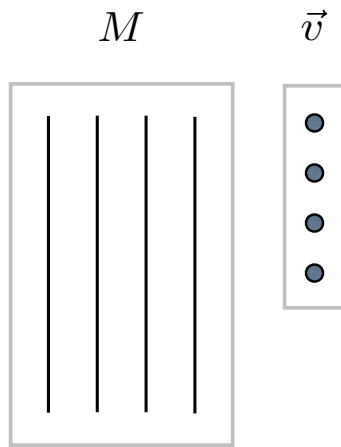
Matrix multiplication

- Two interpretations of matrix times vector:
 - input perspective: weighted sum of columns (from diagram on previous slide)
 - output perspective: inner product with rows
- transpose A^T , symmetric matrices ($A = A^T$)
- distributive property (directly from linearity!)
- associative property - cascade of two linear systems defines the product of two matrices
- generally *not* commutative ($AB \neq BA$), but note that $(AB)^T = B^T A^T$

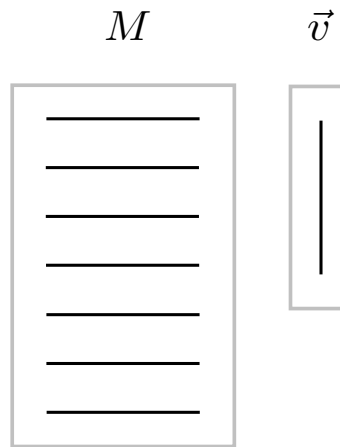
[details on board]

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input perspective:
weighted sum of columns

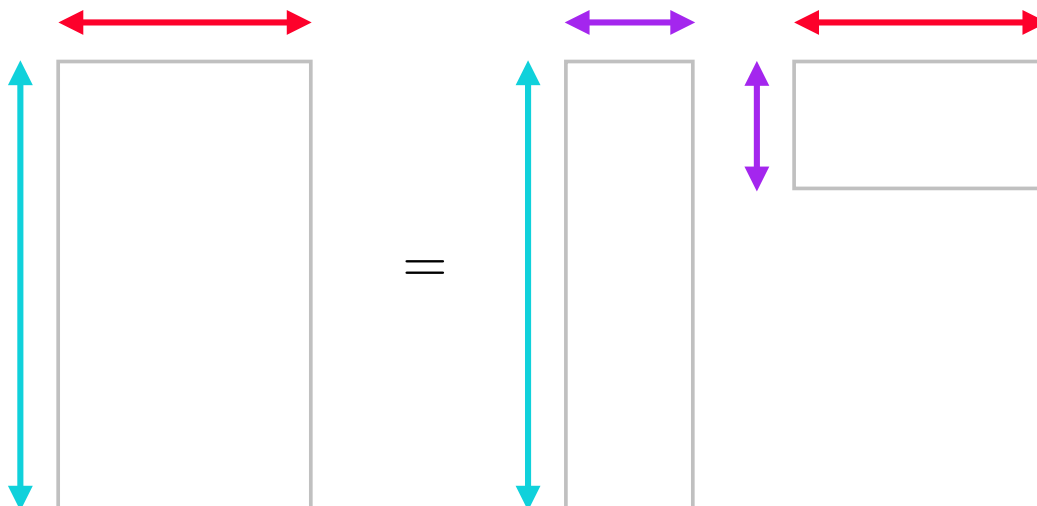


output perspective:
dot product with rows



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Matrix multiplication: dimensional consistency



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All matrices

Orthogonal matrices

- square shape (dimensionality-preserving)
- rows are orthogonal unit vectors
- columns are orthogonal unit vectors
- performs a rotation of the vector space (with possible axis inversion)
- preserve vector lengths and angles (and thus, dot products)
- inverse is transpose

Identity matrix

Diagonal matrices

- arbitrary rectangular shape
- all off-diagonal entries are zero
- squeeze/stretch along standard axes
- if non-square, creates/discards axes
- inverse is diagonal, with inverse of non-zero diagonal entries of original

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Singular Value Decomposition (SVD)

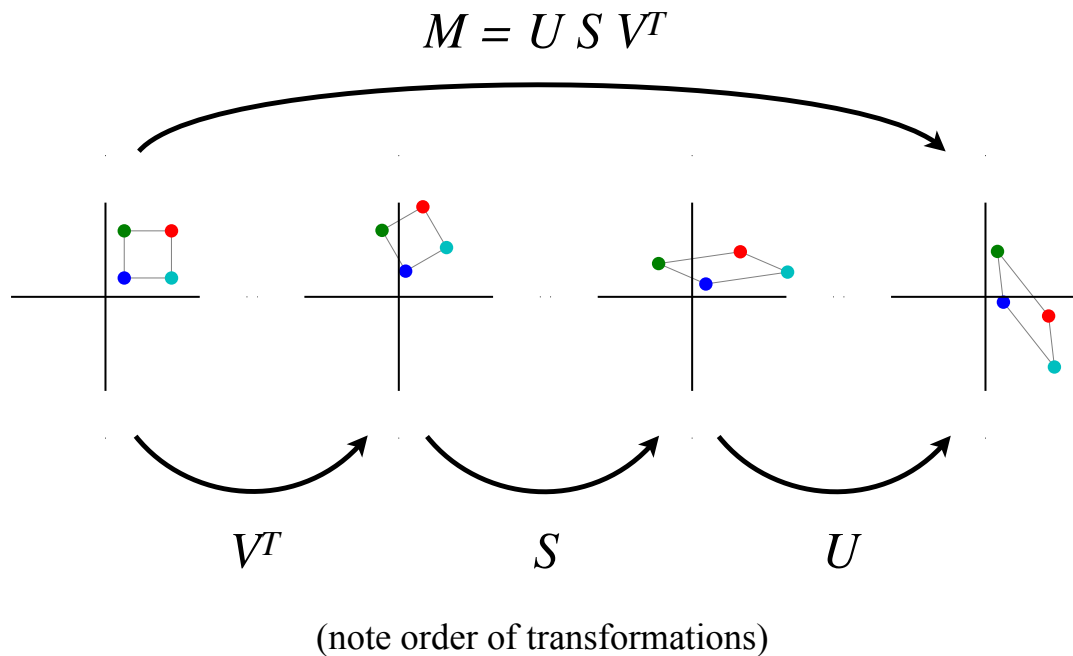
- $M = U S V^T$, “rotate, stretch, rotate”
 - columns of V are basis for input coordinate system
 - columns of U are basis for output coordinate system
 - S rescales axes, and determines what gets through
- interpretation as sum of “outer products”
- non-uniqueness (permutations, sign flips)
- nullspace and rangespace
- inverse and pseudo-inverse

[details on board]

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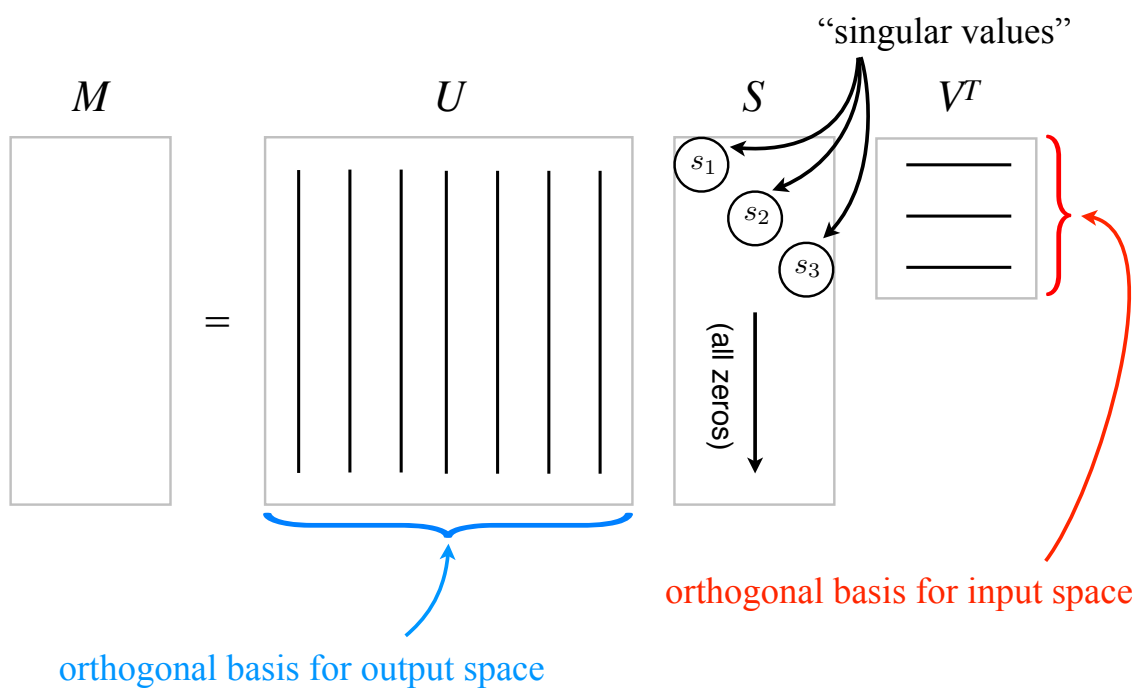
SVD geometry (in 2D)

Consider applying M to four vectors (colored points)

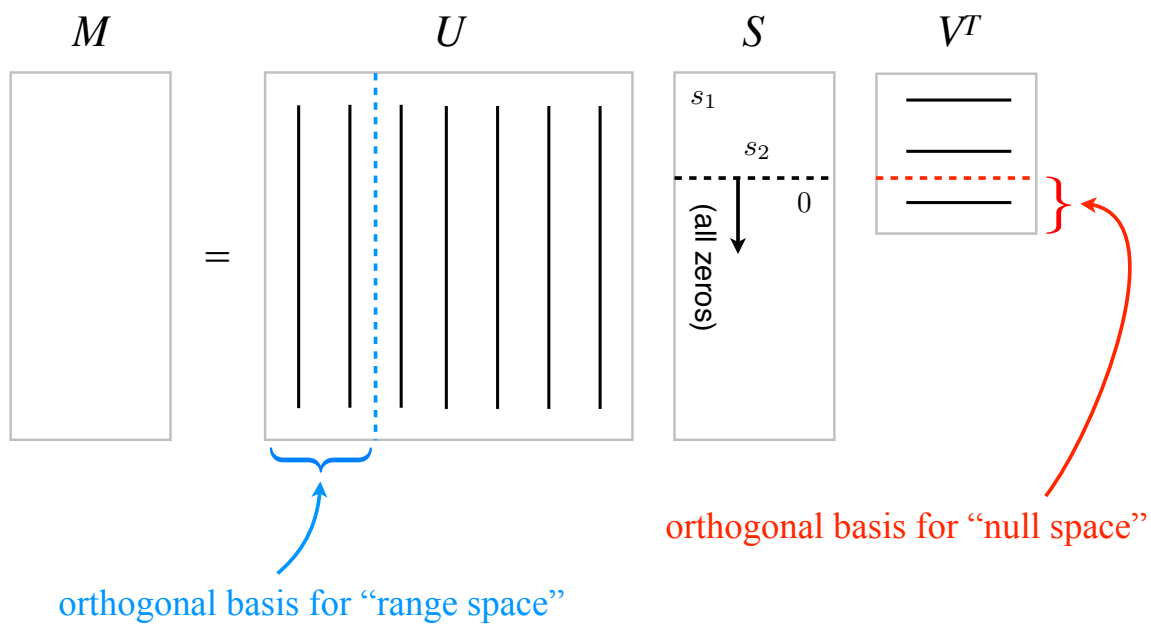


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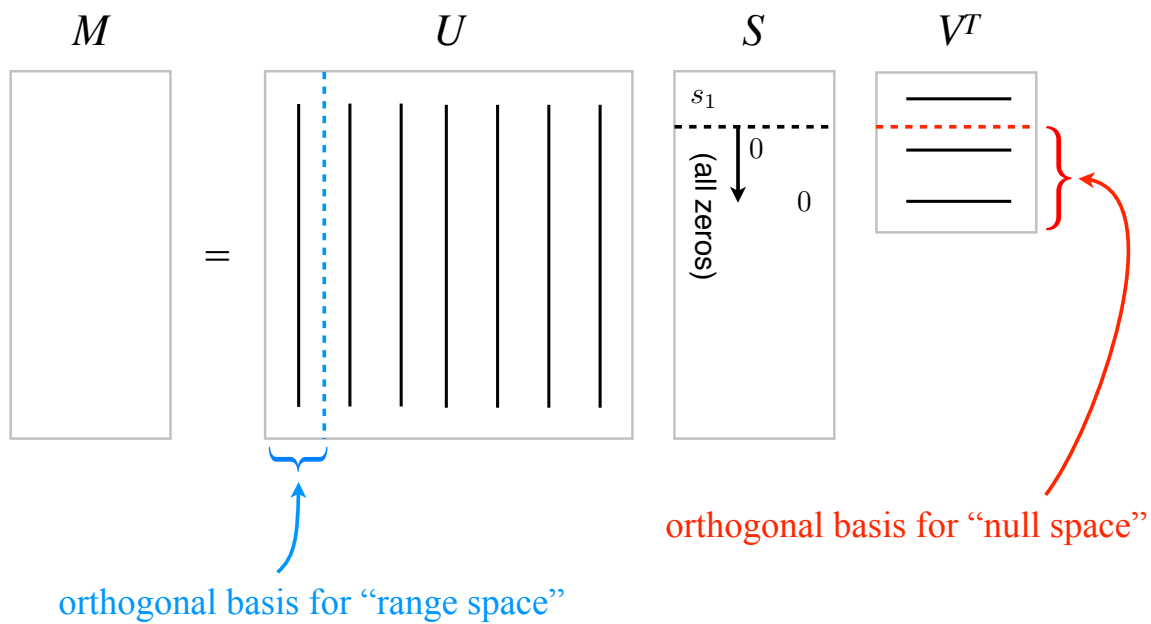
$$M\vec{w} = \sum_k s_k (\vec{v}_k^T \vec{w}) \vec{u}_k = \sum_k s_k (\vec{u}_k \vec{v}_k^T) \vec{w}$$



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