



Efficient distribution of resources provides an embedding of environmental statistics

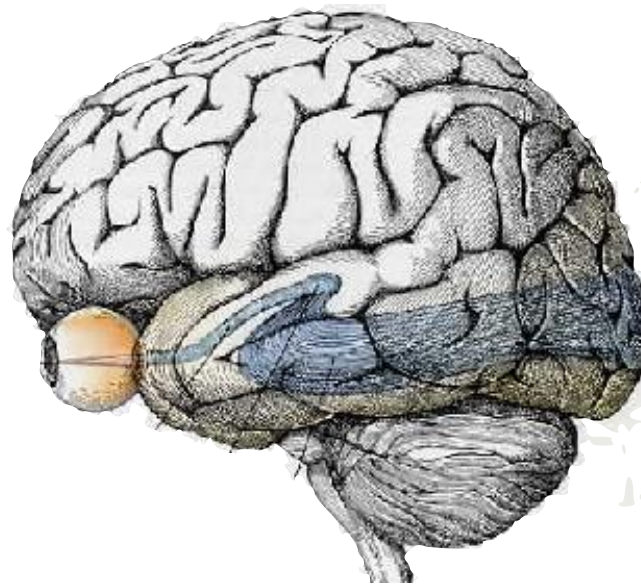
Eero Simoncelli

Howard Hughes Medical Institute
Center for Neural Science,
Courant Inst. of Mathematical Sciences,
New York University

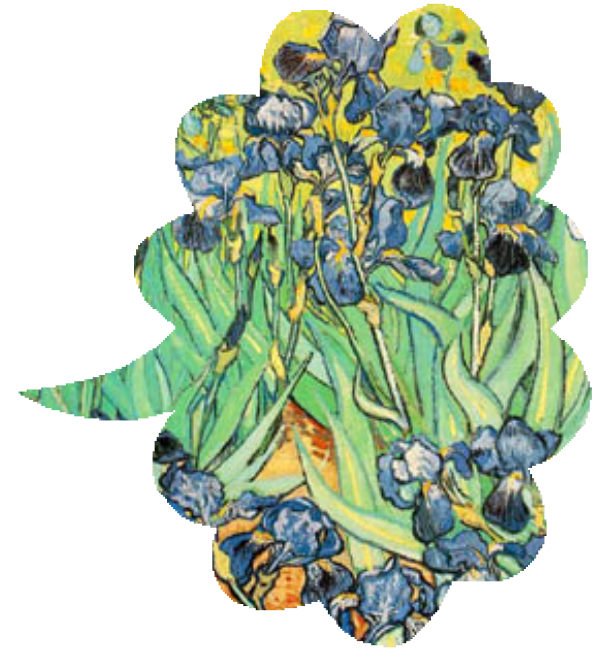




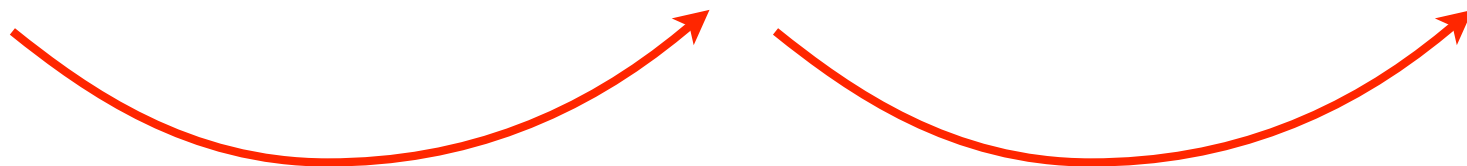
Environment



Physiology

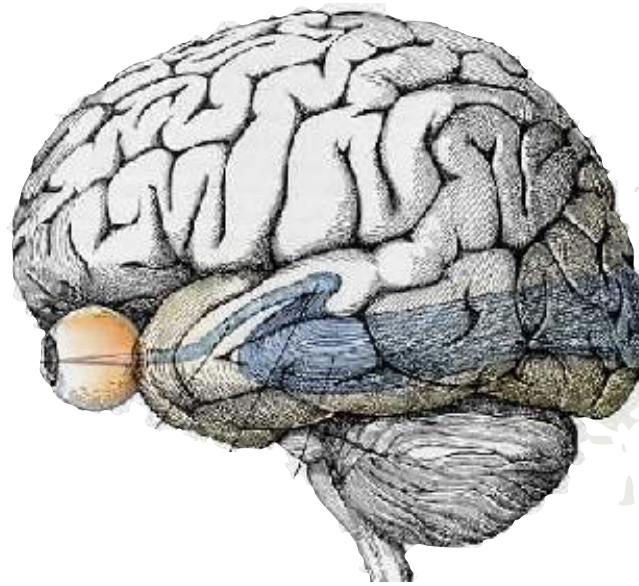


Perception





Environment



Physiology



Perception

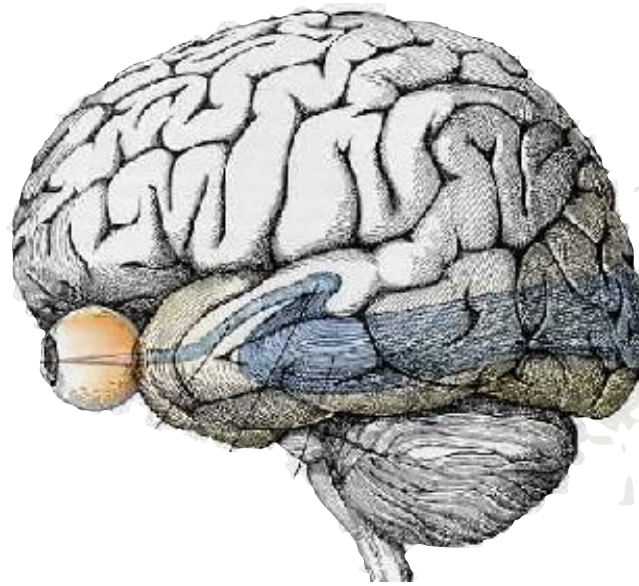


Efficient coding: Sensory systems allocate resources efficiently to capture information about inputs that are likely to occur.

[Barlow '61]



Environment



Physiology

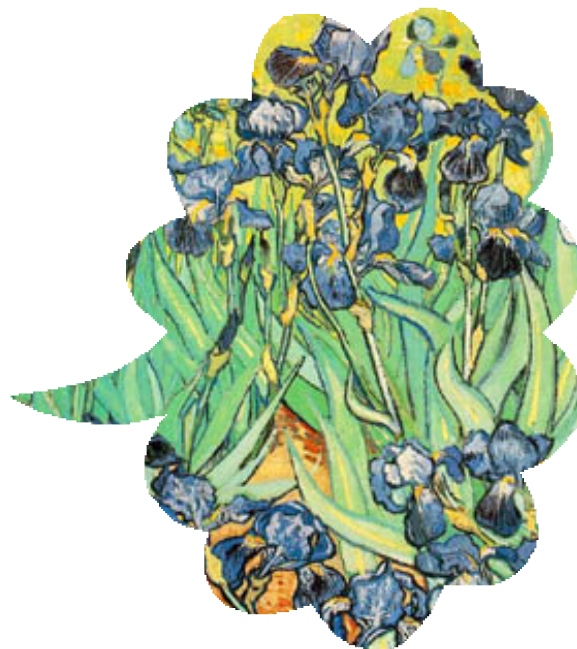
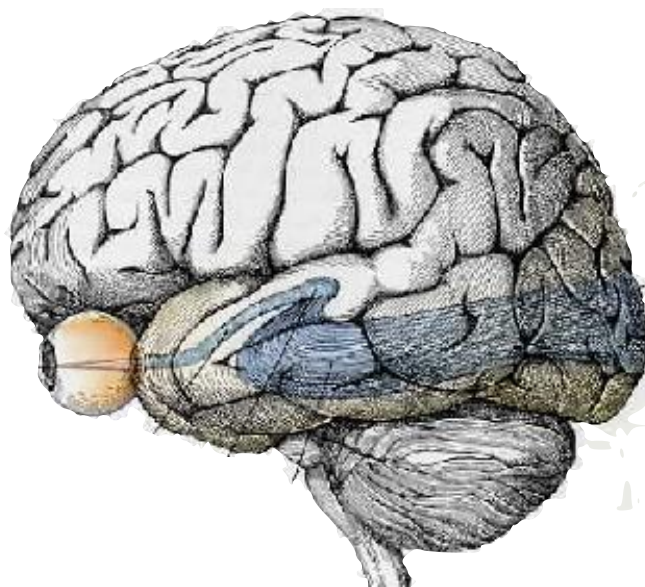
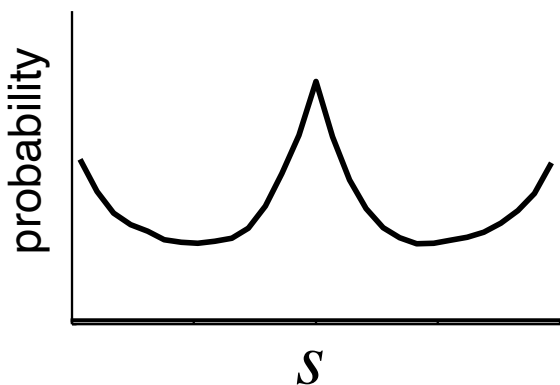


Perception

Optimal inference: Perception is a best guess as to what is in the world, given current sensory responses and prior experience

[Al Hazan, 1040; Helmholtz, 1866]

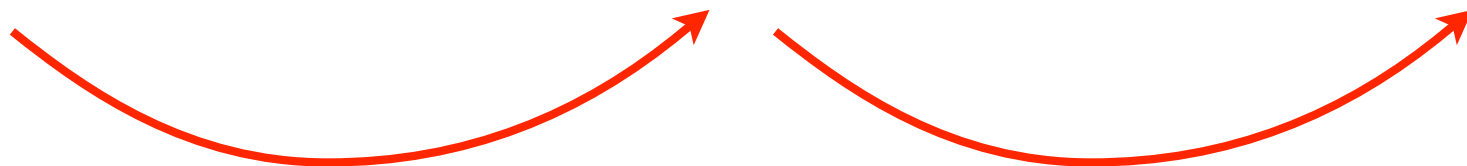
For today's talk:



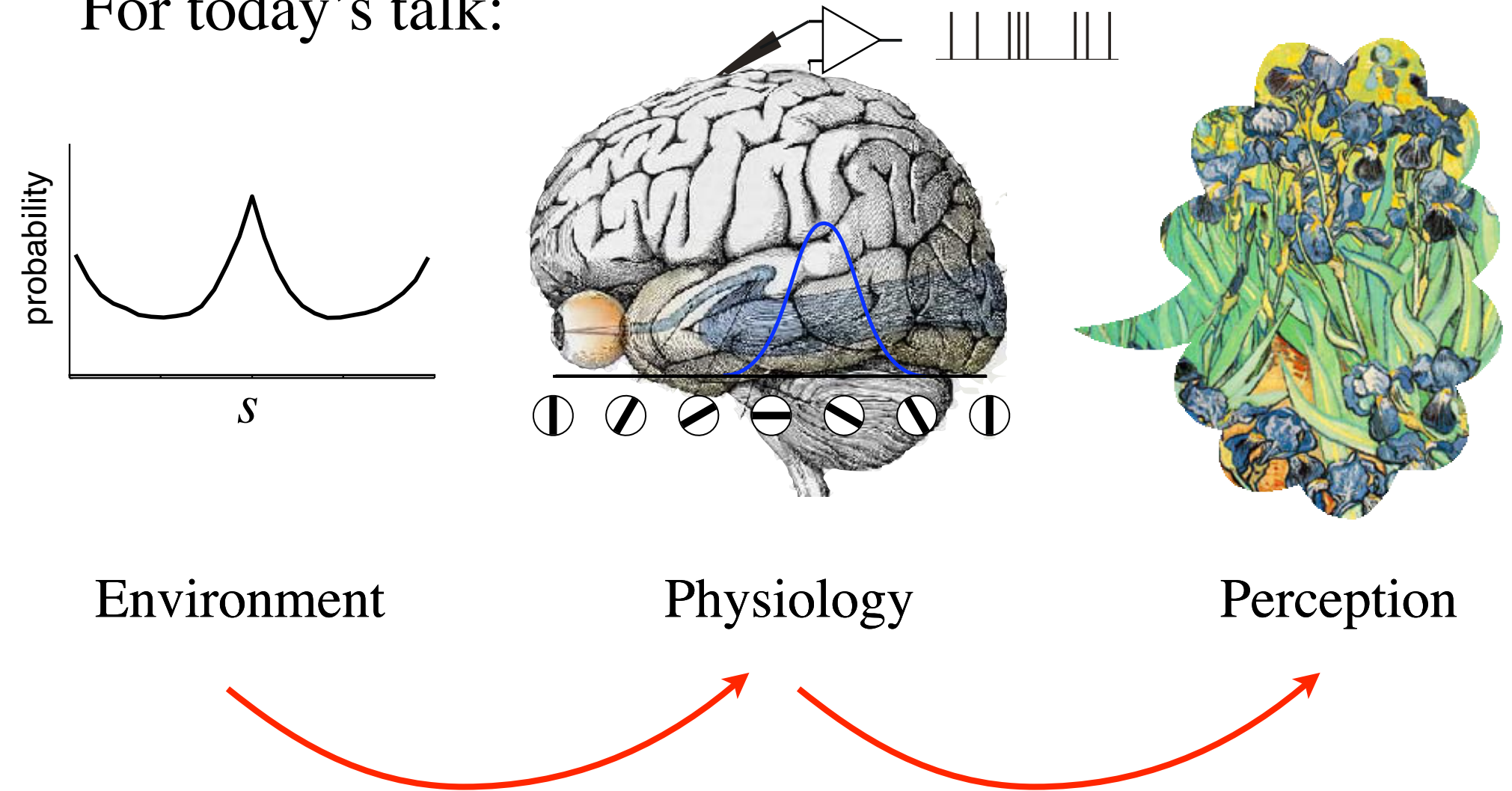
Environment

Physiology

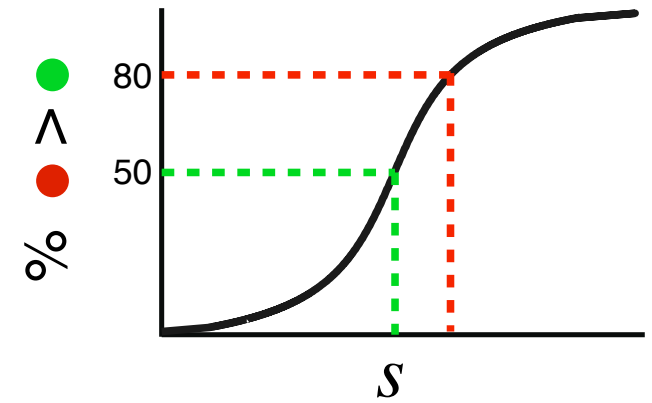
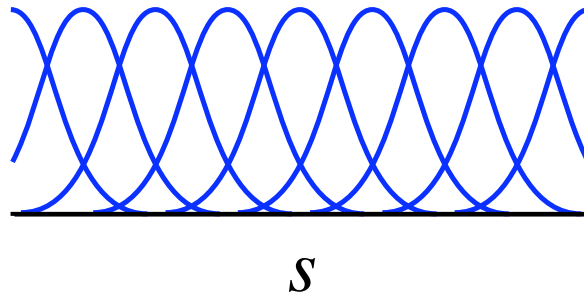
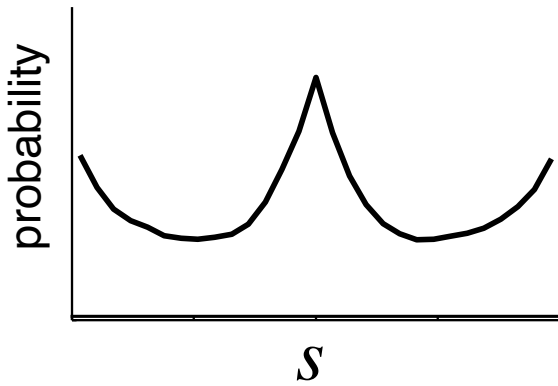
Perception



For today's talk:



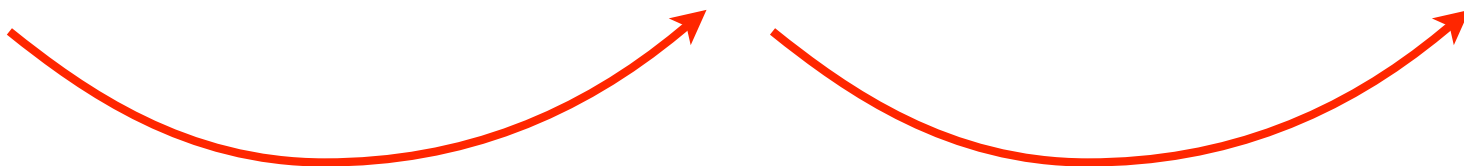
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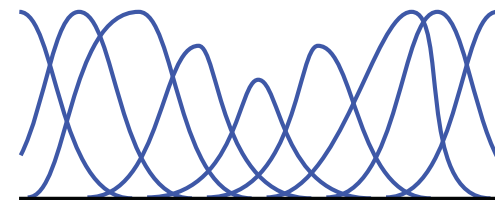
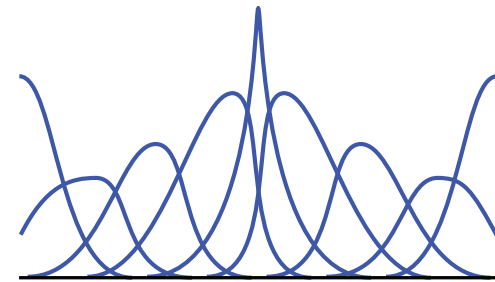
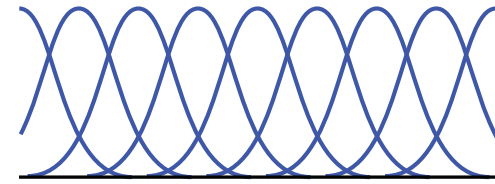
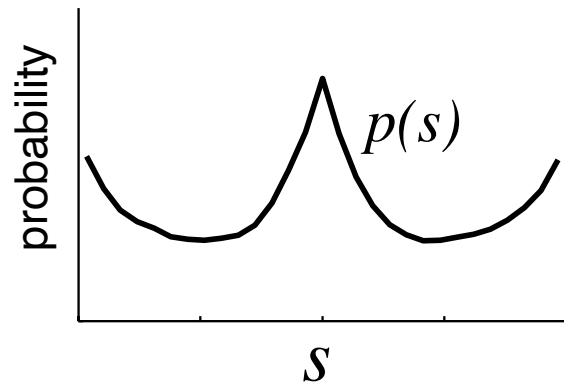


Environment

Physiology

Perception





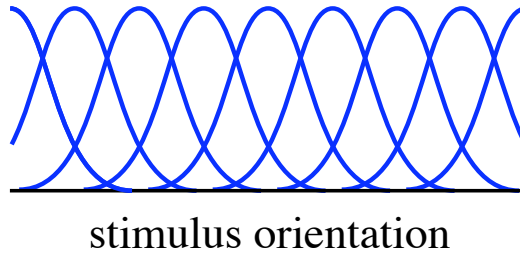
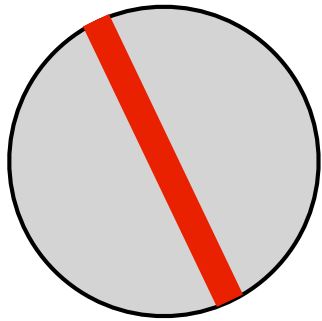
Given N neurons, with total average firing rate R

- what set of tuning curves transmits the most information about s ?
- what are the perceptual implications of this solution?

Oriented
stimulus

Homogeneous
population

(encode)



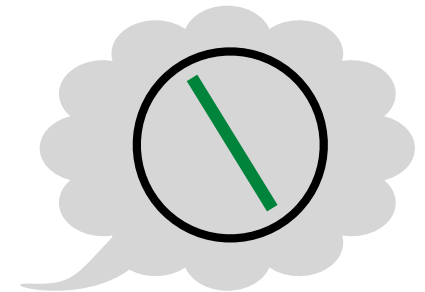
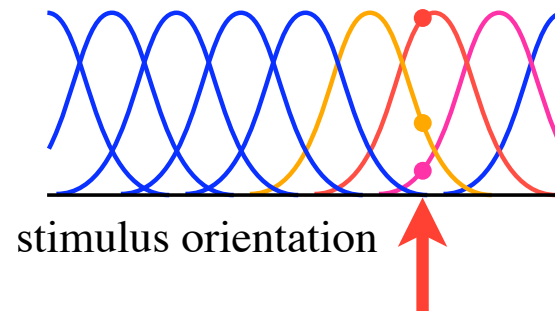
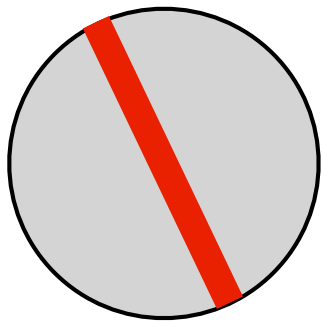
Oriented
stimulus

Homogeneous
population

“Perceived”
orientation

(encode)

(decode)



[Földiák, 1989;
Seung & Sompolinsky, 1993;
Salinas & Abbott, 1994;
Sanger, 1996;
Zemel, Dayan, Pouget, 1998;
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Brown & Bäckér, 2006;
Jazayeri & Movshon, 2006;
Ma et. al., 2006; etc]

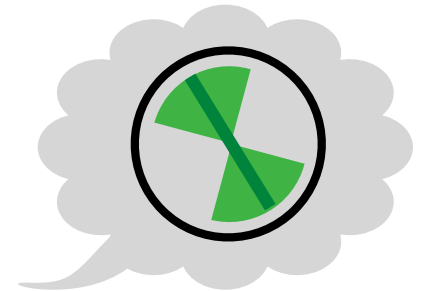
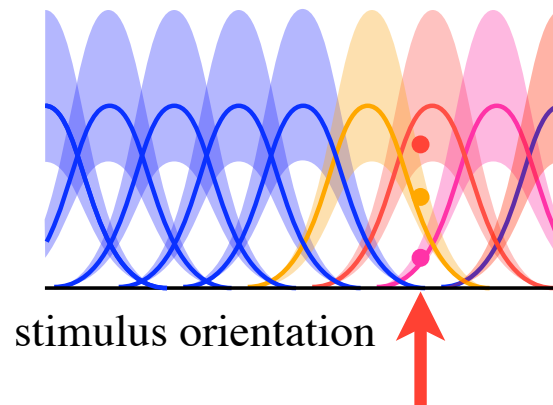
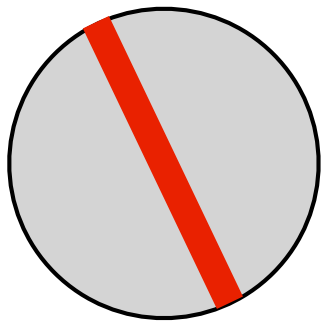
Oriented
stimulus

Homogeneous
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“Perceived”
orientation

(encode)

(decode)



Accuracy limited by noise ...

[Földiák, 1989;
Seung & Sompolinsky, 1993;
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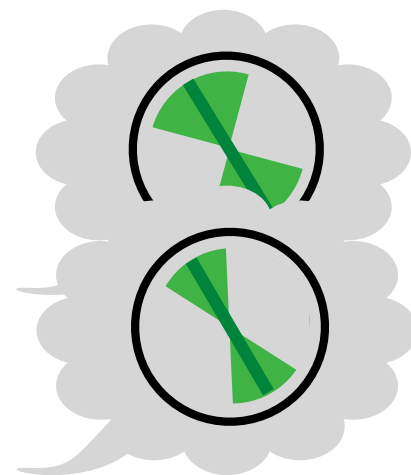
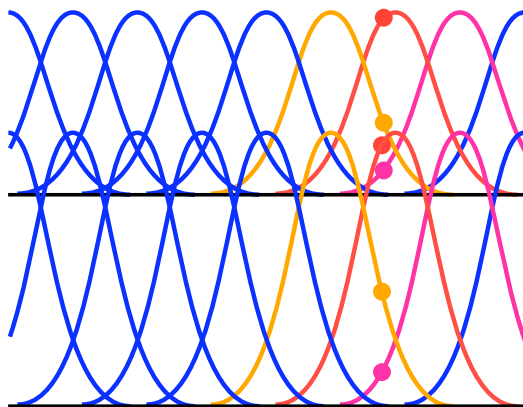
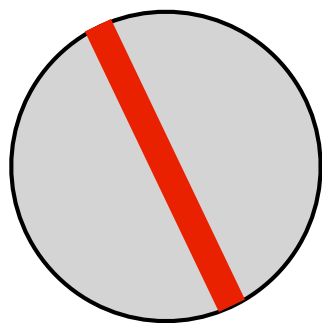
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(decode)



Accuracy limited by noise ...

... but improves with additional resources:

- Max firing rate

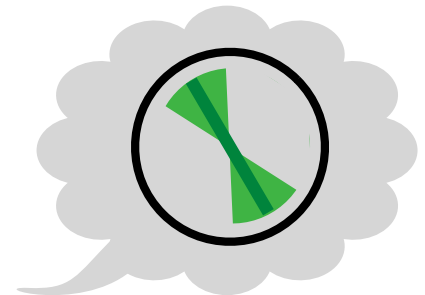
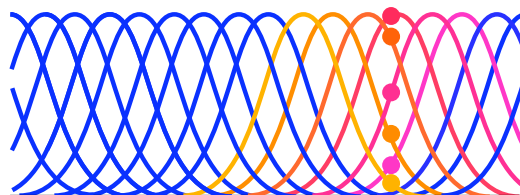
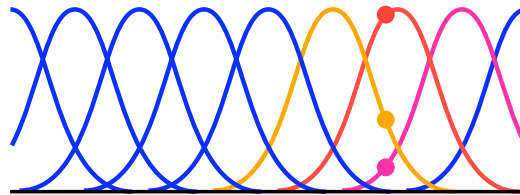
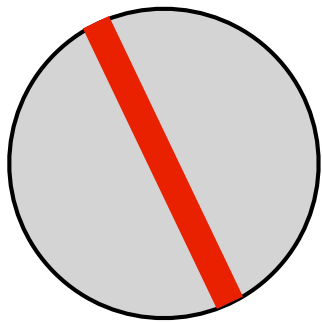
Oriented
stimulus

Homogeneous
population

“Perceived”
orientation

(encode)

(decode)



Accuracy limited by noise ...

... but improves with additional resources:

- Max firing rate
- Number of cells

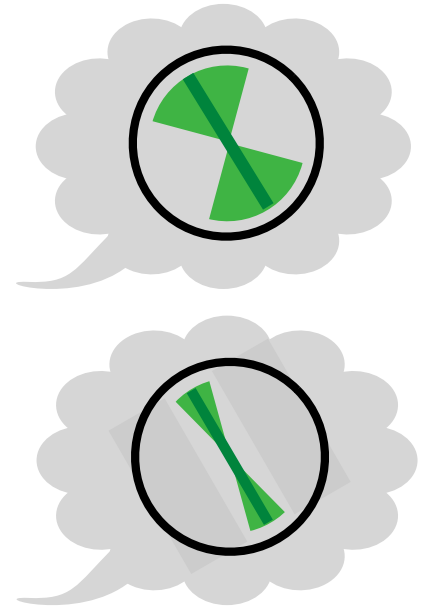
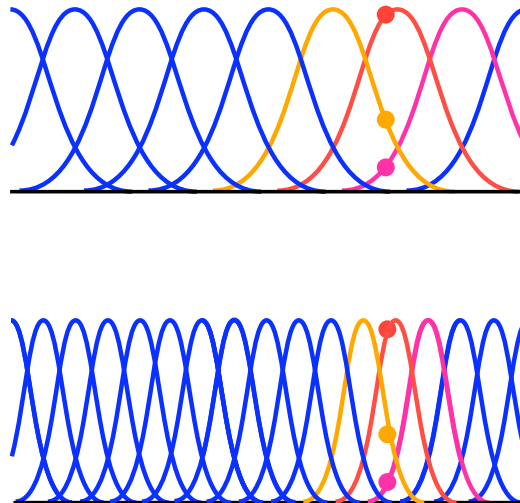
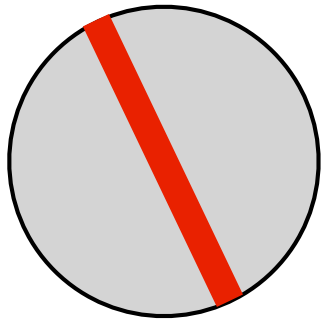
Oriented
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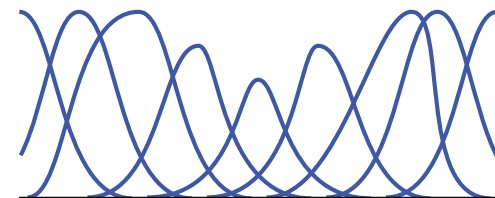
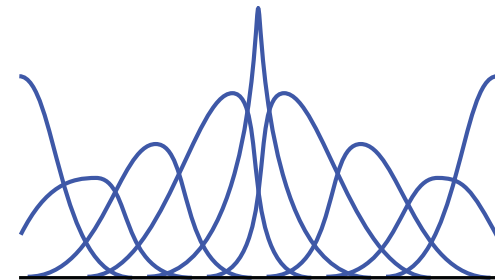
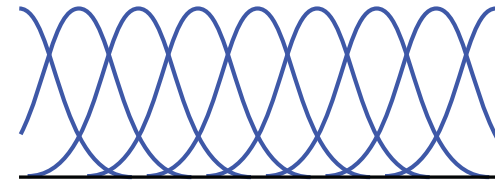
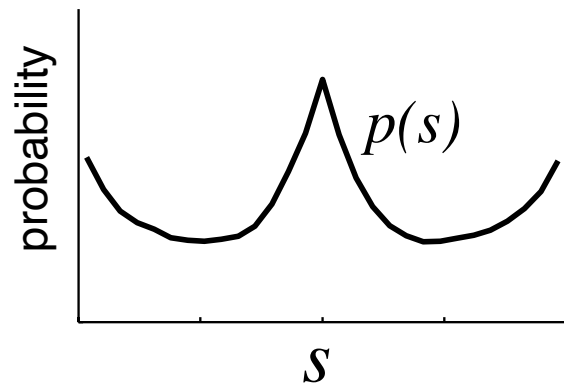
(decode)



Accuracy limited by noise ...

... but improves with additional resources:

- Max firing rate
- Number of cells (& tuning width)



Given N neurons, with total average firing rate R

- what set of tuning curves transmits the most information about s ?
- what are the perceptual implications of this solution?

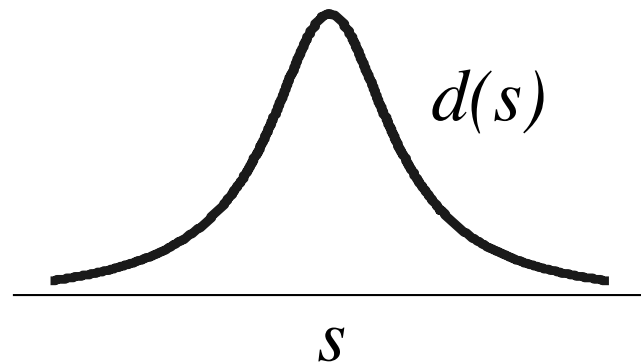
1. Independent Poisson responses [e.g., Seung & Sompolinsky, 1993]

$$p(\vec{r}|s) = \prod_{n=1}^N \frac{h_n(s)^{r_n} e^{-h_n(s)}}{r_n!}$$

(generalizes to exponential families, w/ local correlations)

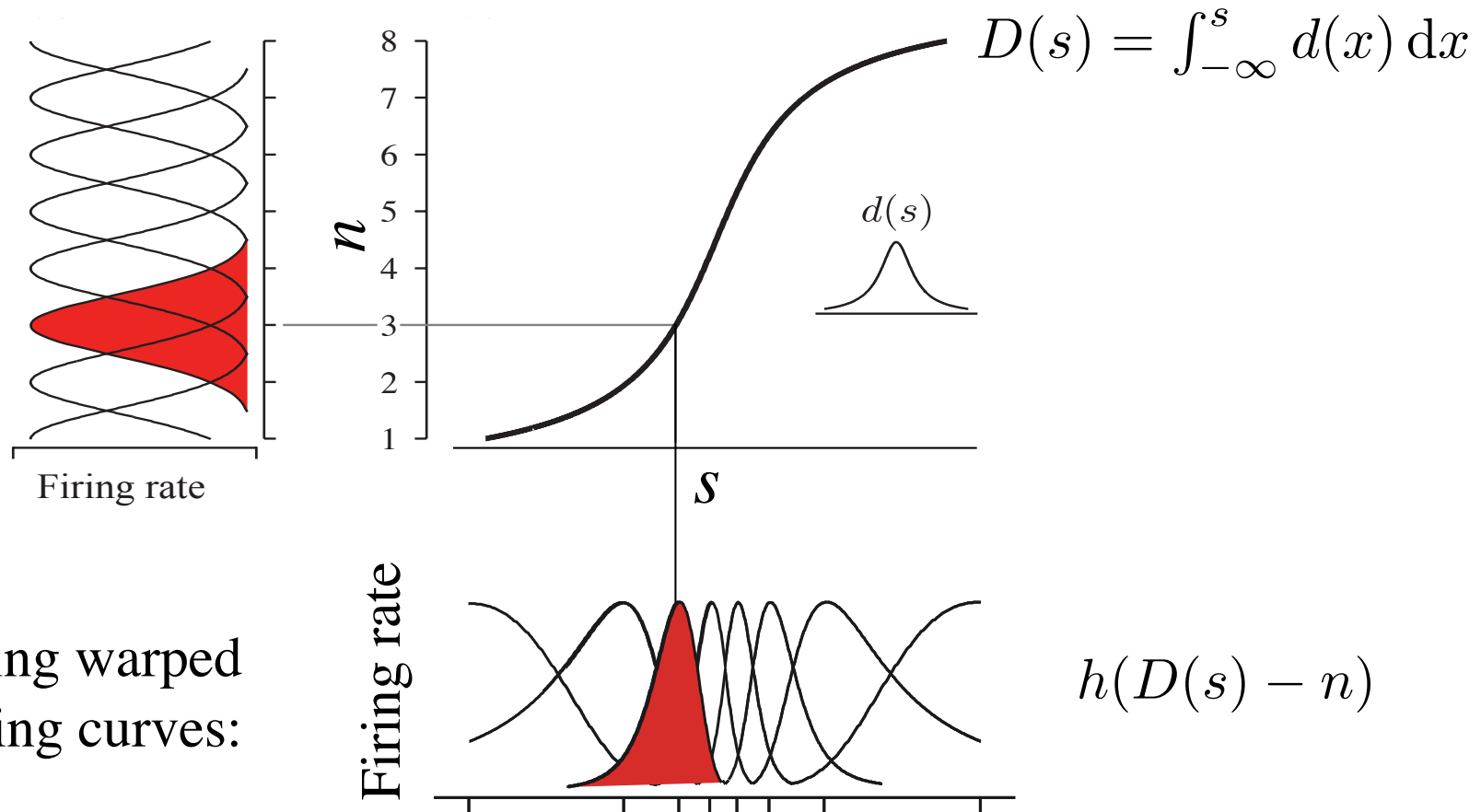
[cf., Jazayeri & Movshon, 2006; Ma et. al., 2006]

1. Independent Poisson responses
(generalizes to exponential families, w/ local correlations)
2. Population resource allocation parameterized by **density** and **gain**, with enforced “tiling”:



Tuning curve
density function

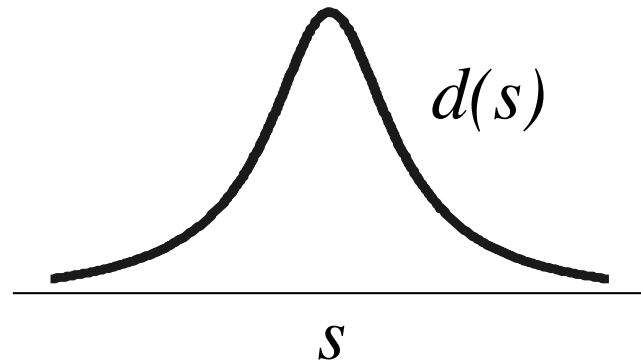
1. Independent Poisson responses
(generalizes to exponential families, w/ local correlations)
2. Population of tuning curves parameterized by **density** and **gain**, with enforced “tiling”:



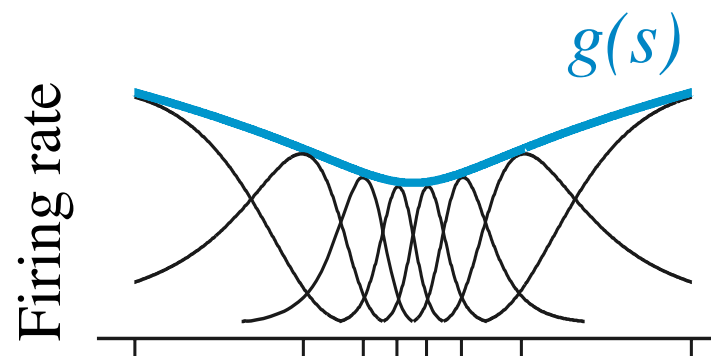
Resulting warped
tuning curves:

$$h(D(s) - n)$$

1. Independent Poisson responses
(generalizes to exponential families, w/ local correlations)
2. Population of tuning curves parameterized by **density** and **gain**, with enforced “tiling”:



Tuning curve
density function



Tuning curve
gain function

Resulting **warped**
and **modulated**
tuning curves:

$$h_n(s) = g(s) h(D(s) - n)$$

1. Independent Poisson responses
(generalizes to exponential families, w/ local correlations).
2. Parameterize tuning curve population in terms of **gain** and **density**, with enforced “tiling”.
3. Optimize (Fisher bound on) transmitted information, for N neurons with total average firing rate R [Brunel & Nadal ‘98]:

$$I_f(s) = \int p(\vec{r}|s) \frac{\partial^2}{\partial s^2} \log p(\vec{r}|s) d\vec{r}$$
$$\propto d^2(s)g(s) \quad \text{(tiling parameterization)}$$

1. Independent Poisson responses
(generalizes to exponential families, w/ local correlations).
2. Parameterize tuning curve population in terms of **gain** and **density**, with enforced “tiling”.
3. Optimize (Fisher bound on) transmitted information, for N neurons with total average firing rate R [Brunel & Nadal ‘98]:

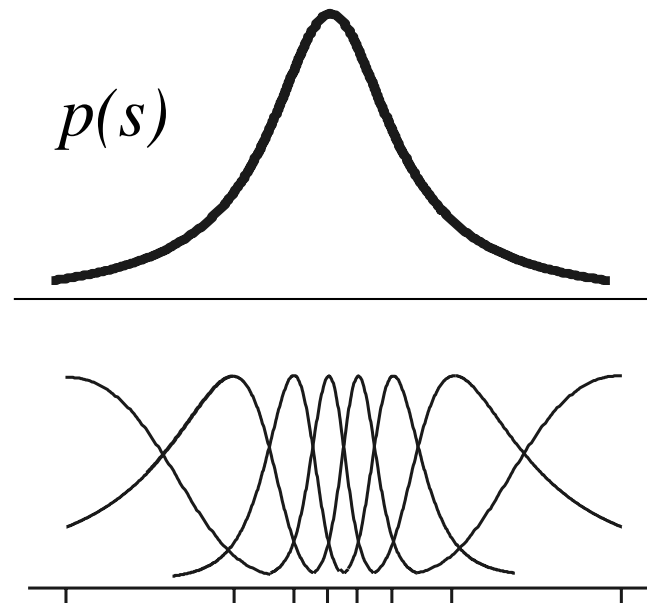
$$\arg \max_{d,g} \int p(s) \log (d^2(s)g(s)) \, ds$$

$$\text{such that} \quad \int d(s) \, ds = N, \quad \int p(s)g(s) \, ds = R$$

Closed-form optimal solution

$$d(s) = Np(s), \quad g(s) = R$$

- More cells, with narrower tuning, in higher probability regions of stimulus space
- All neurons have same gain (max. firing rate)



Closed-form optimal solution

$$d(s) = Np(s), \quad g(s) = R \quad \text{physiological prediction}$$

- More cells, with narrower tuning, in higher probability regions of stimulus space
- All neurons have same gain (max. firing rate)
- All neurons have same **mean** firing rate
- Bonus: limit on perceptual discrimination thresholds:

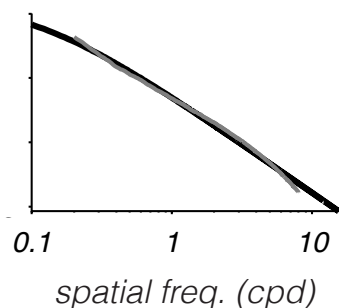
[Seriés, Stocker & Simoncelli 2009]

$$\delta(s) \geq \frac{\alpha}{\sqrt{R} N p(s)} \quad \text{perceptual prediction}$$

Example: local spatial frequency

Environment

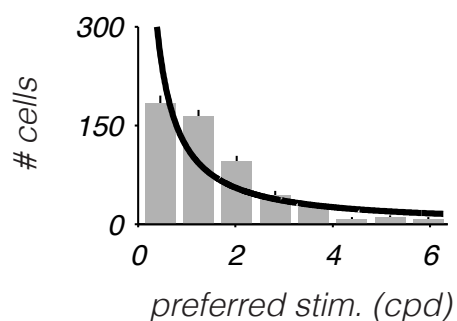
$p(s)$



(photographs)
[van Hateren et. al. 98]
[Doi et. al. 02]
[Olmos et. al. 05]

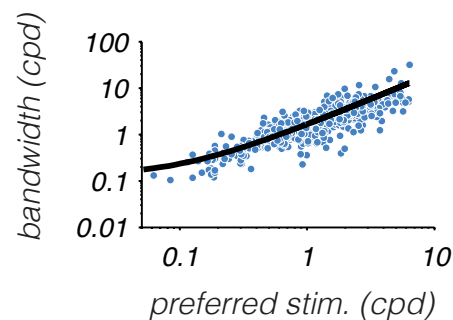
Physiology

density



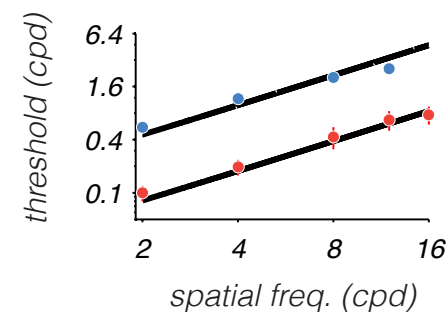
(anesthetized macaque, V1)
[Cavanaugh et. al, 02]

tuning width



Perception

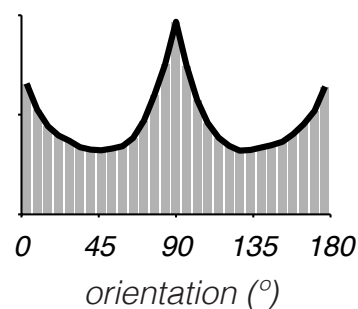
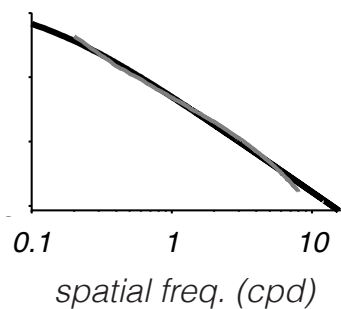
discrim. thresh.



(human)
[Caelli et. al, 83]
[Regan et. al, 82]

Environment

$p(s)$

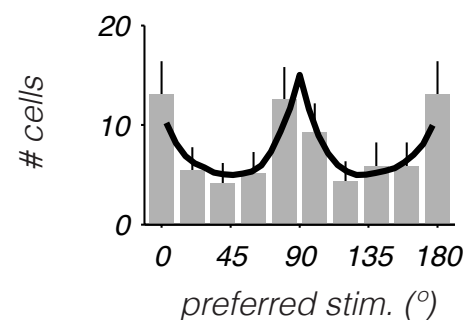
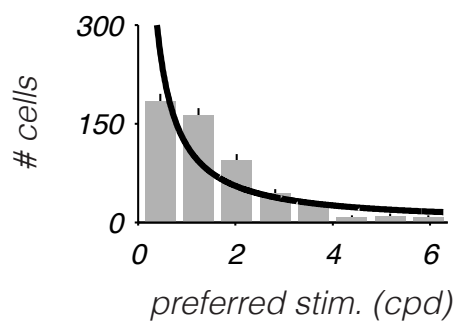


(photographs)

[Ganguli & Simoncelli, 2011]

Physiology

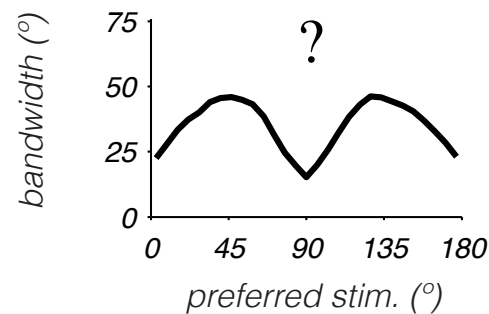
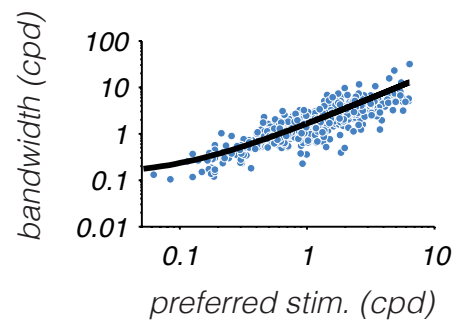
density



(anesthetized macaque, V1)

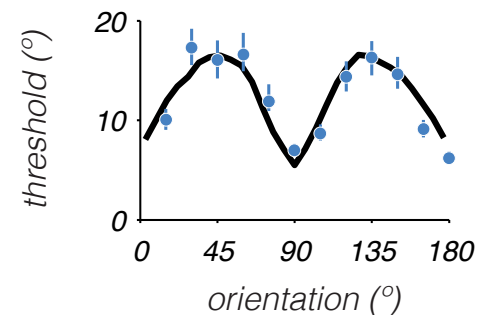
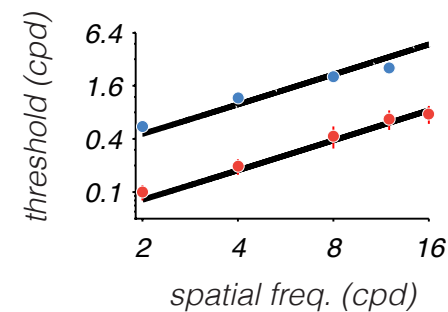
[Mansfield, 74]

tuning width



Perception

discrim. thresh.



(human)

[Girshick et. al, 11]

[Ganguli & Simoncelli, Arxiv 2016]

Environment

Physiology

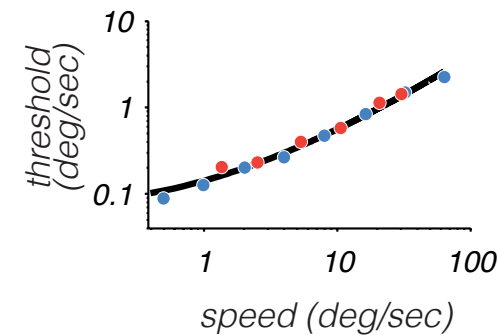
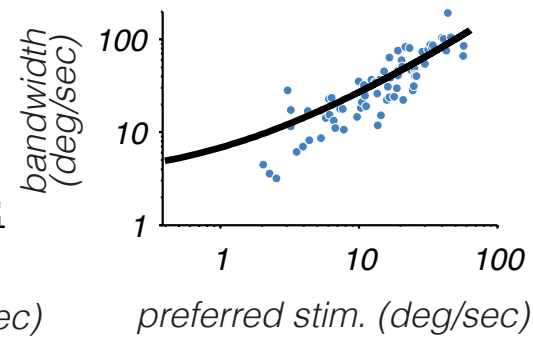
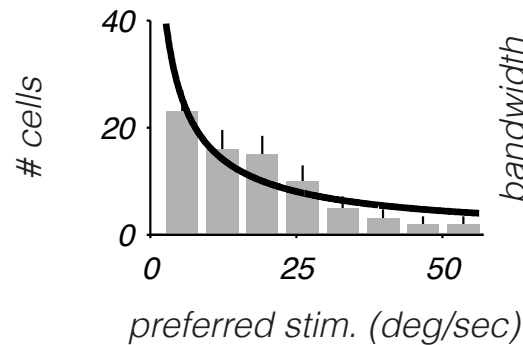
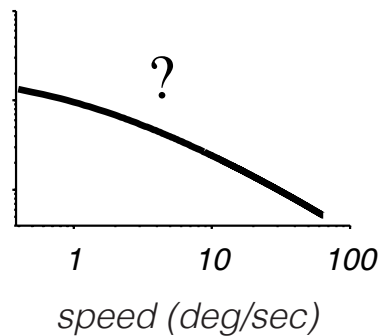
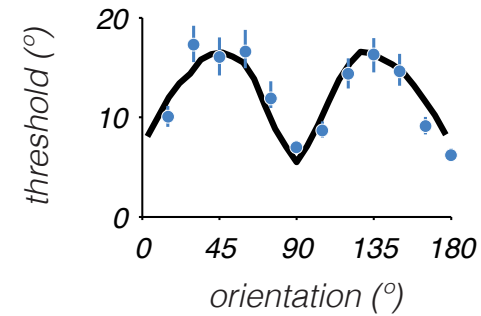
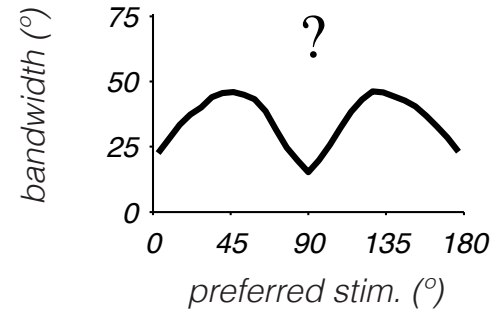
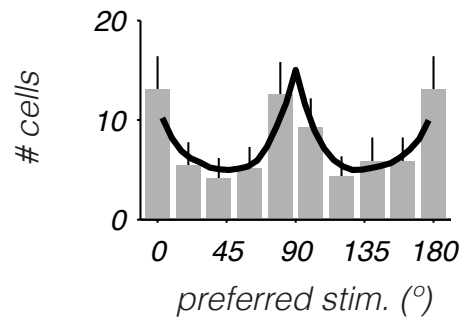
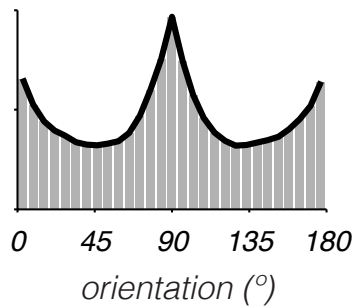
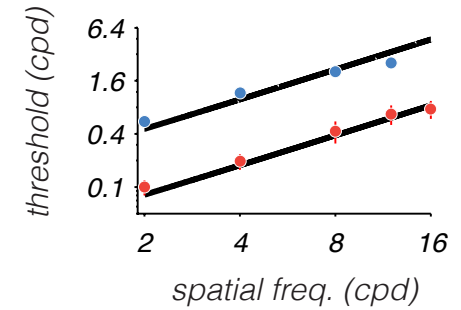
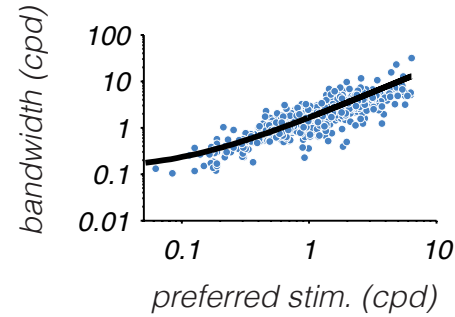
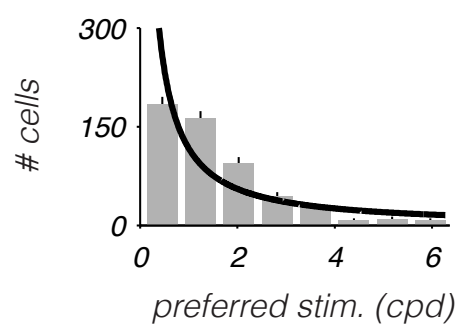
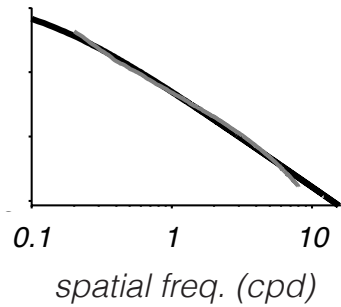
Perception

$p(s)$

density

tuning width

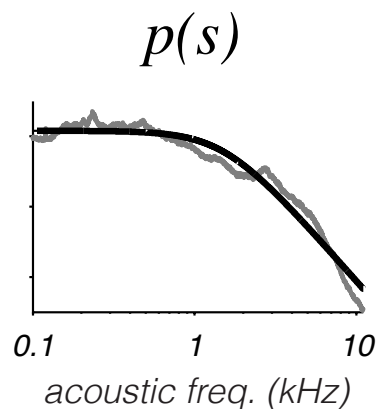
discrim. thresh.



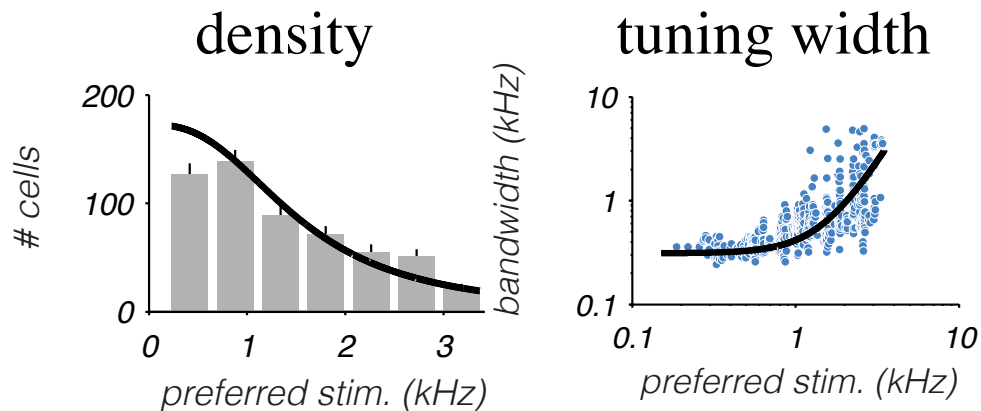
(anesthetized macaque, MT)
[Movshon, unpublished]

[De Bruyn et. al, 88]
[McKee et. al, 84]

Environment

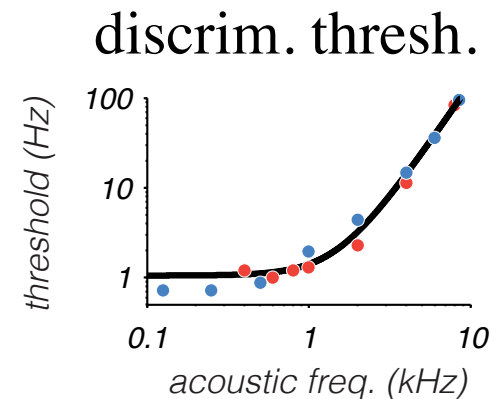


Physiology

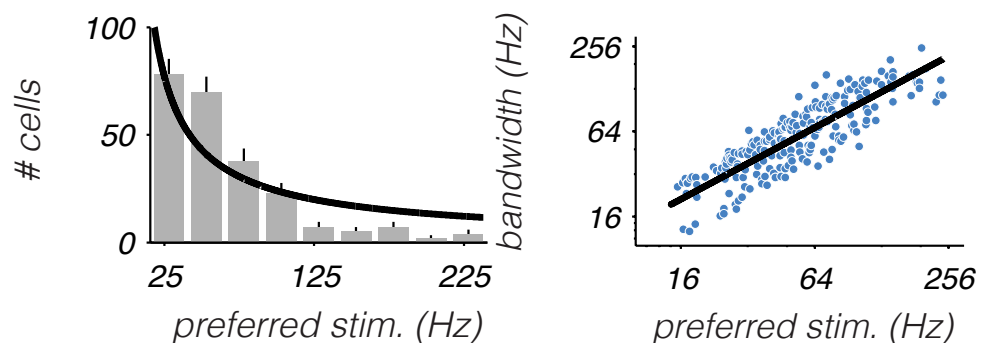
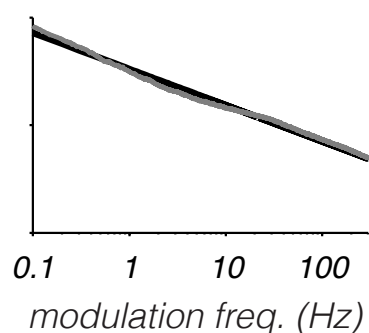


(anesthetized cat)
[Carney et. al, 99]

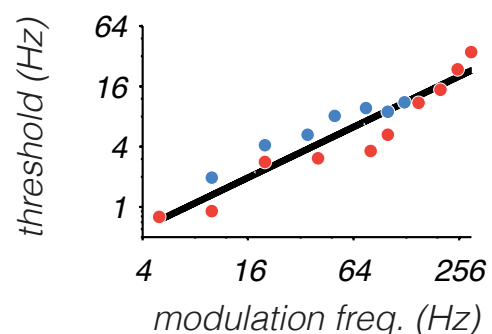
Perception



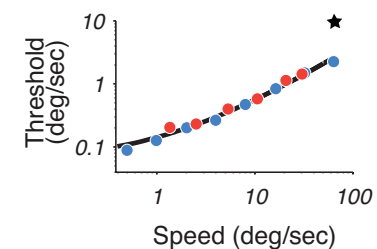
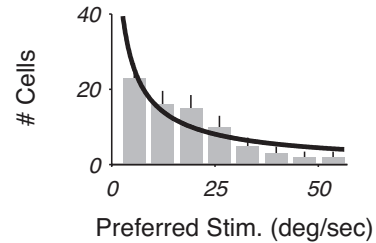
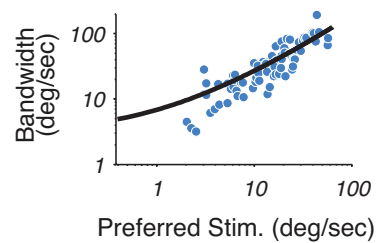
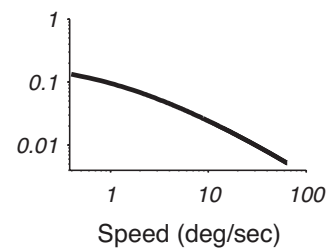
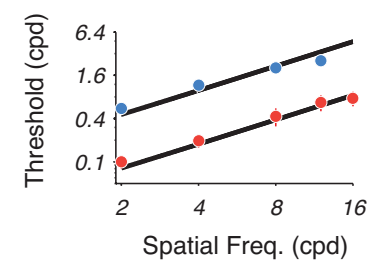
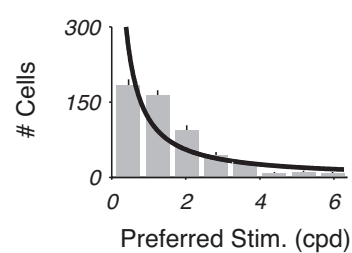
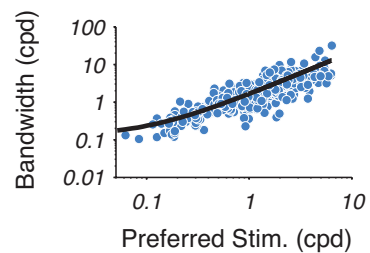
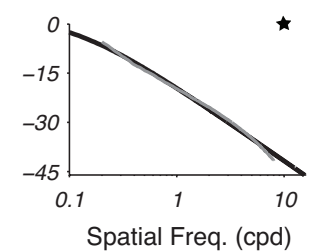
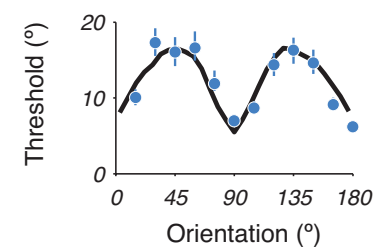
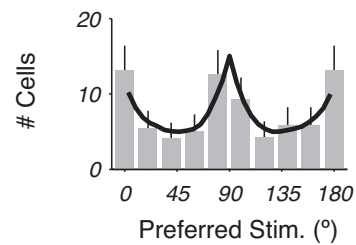
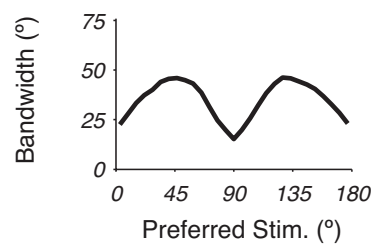
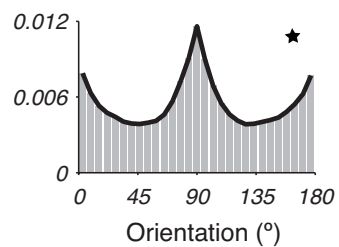
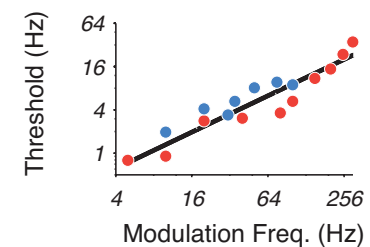
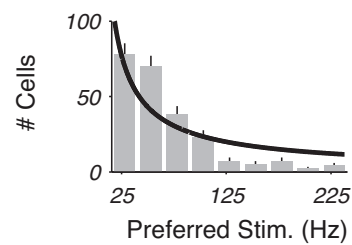
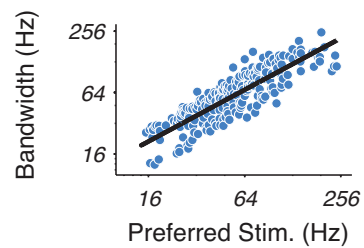
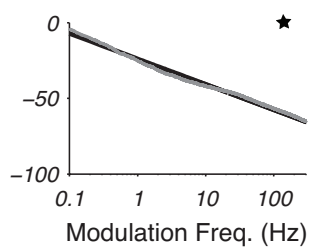
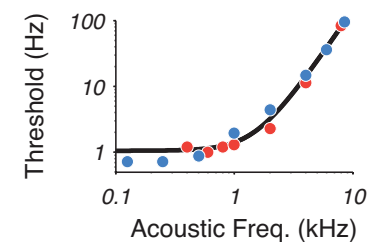
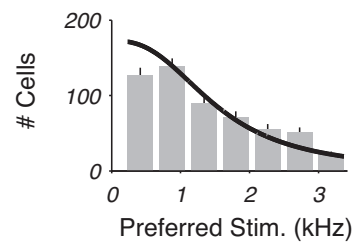
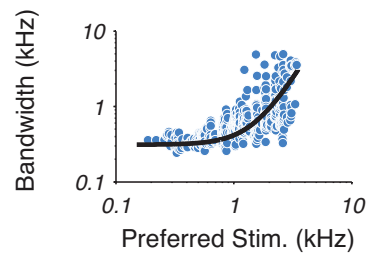
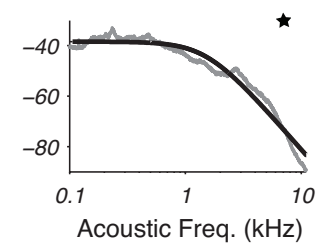
(human)
[Moore et. al, 73]
[Weir et. al, 76]



(anesthetized cat)
[Rodríguez et. al, 10]



(human)
[Lemanska et. al, 02]
[Formby, 85]

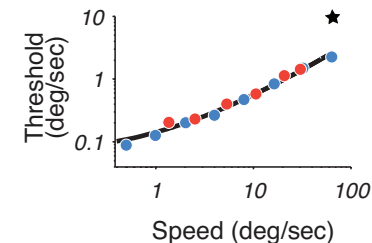
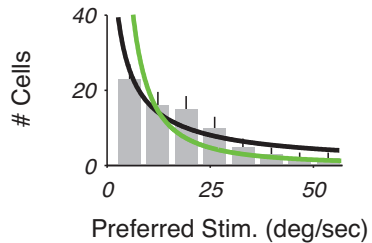
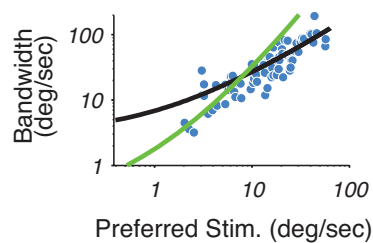
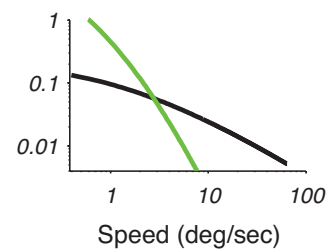
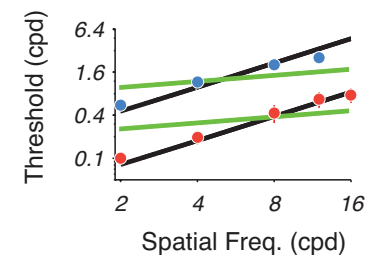
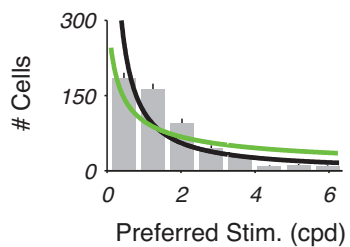
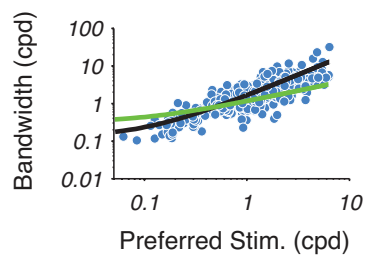
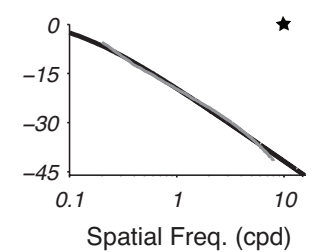
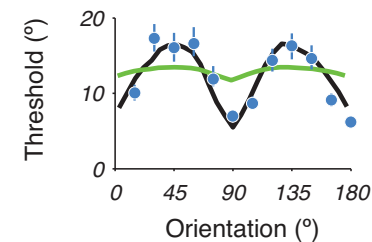
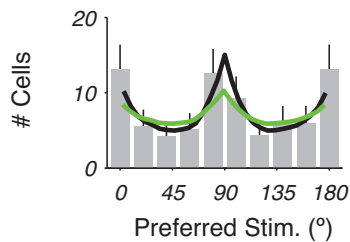
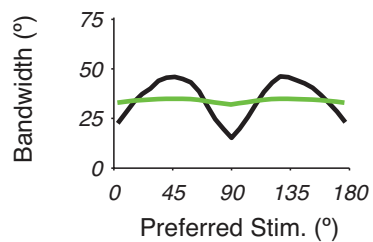
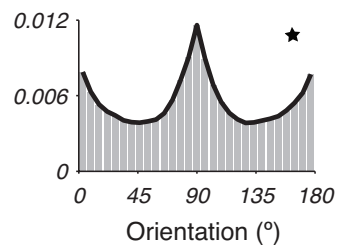
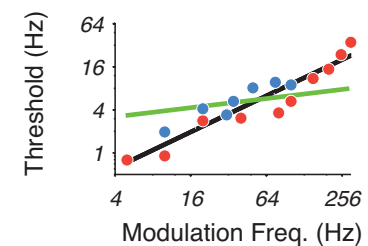
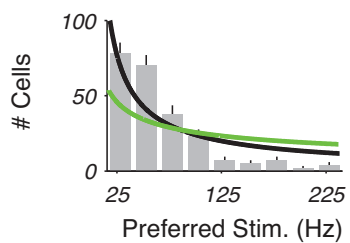
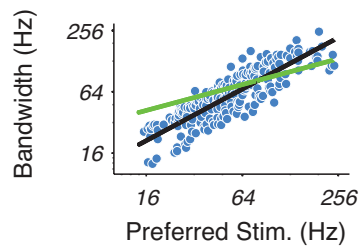
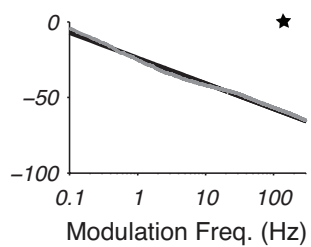
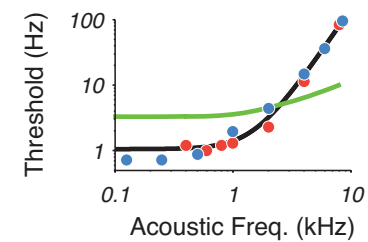
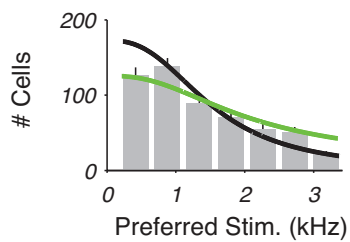
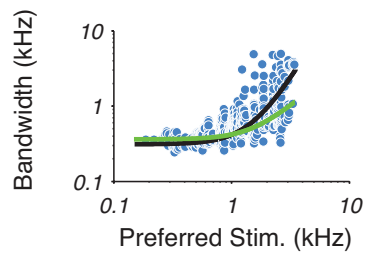
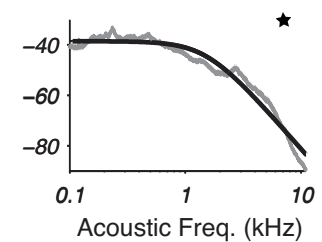


More generally:

$$\arg \max_{d(s), g(s)} \int p(s) f(d^2(s)g(s)) \, ds$$

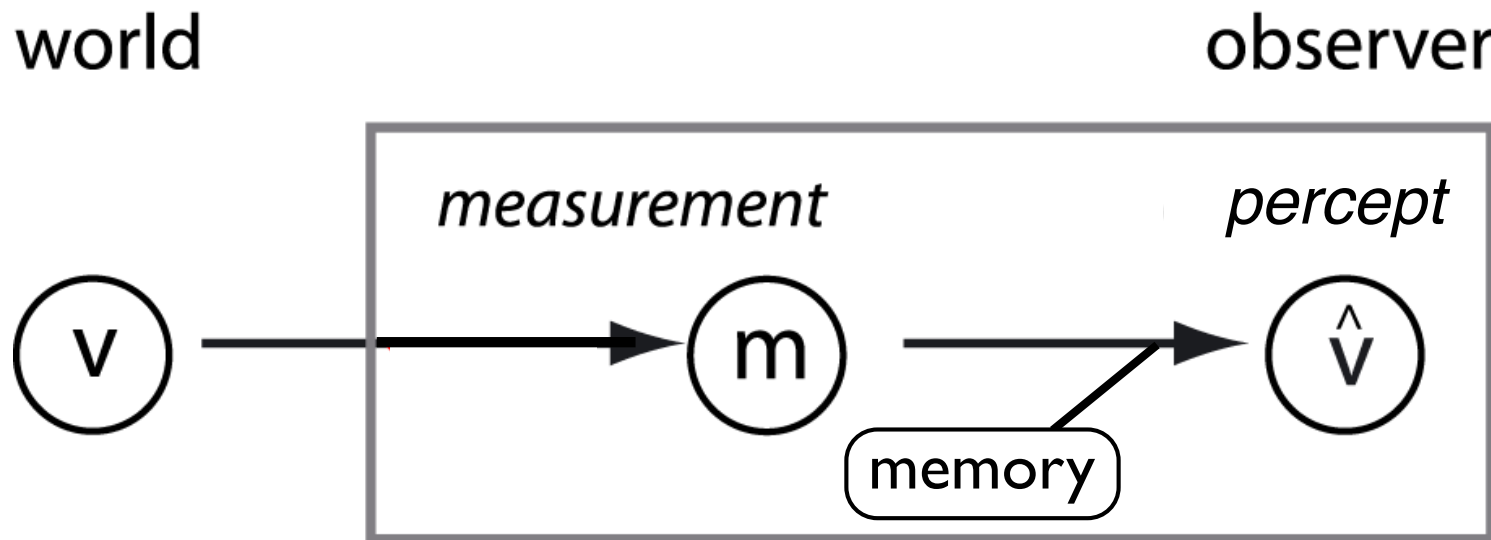
$$\text{s.t.} \quad \int d(s) \, ds = N, \quad \int p(s)g(s) \, ds = R$$

		Infomax	Discrimax	Power law
Optimized function:		$f(x) = \log x$	$f(x) = -x^{-1}$	$f(x) = -x^\alpha, \alpha < \frac{1}{3}$
Density (Tuning width) ⁻¹	$d(s)$	$Np(s)$	$\propto Np^{\frac{1}{2}}(s)$	$\propto Np^{\frac{\alpha-1}{3\alpha-1}}(s)$
Gain	$g(s)$	R	$\propto Rp^{-\frac{1}{2}}(s)$	$\propto Rp^{\frac{2\alpha}{1-3\alpha}}(s)$
Fisher information	$I_f(s)$	$\propto RN^2p^2(s)$	$\propto RN^2p^{\frac{1}{2}}(s)$	$\propto RN^2p^{\frac{2}{1-3\alpha}}(s)$
Discriminability bound	$\delta_{\min}(s)$	$\propto p^{-1}(s)$	$\propto p^{-\frac{1}{4}}(s)$	$\propto p^{\frac{1}{3\alpha-1}}(s)$

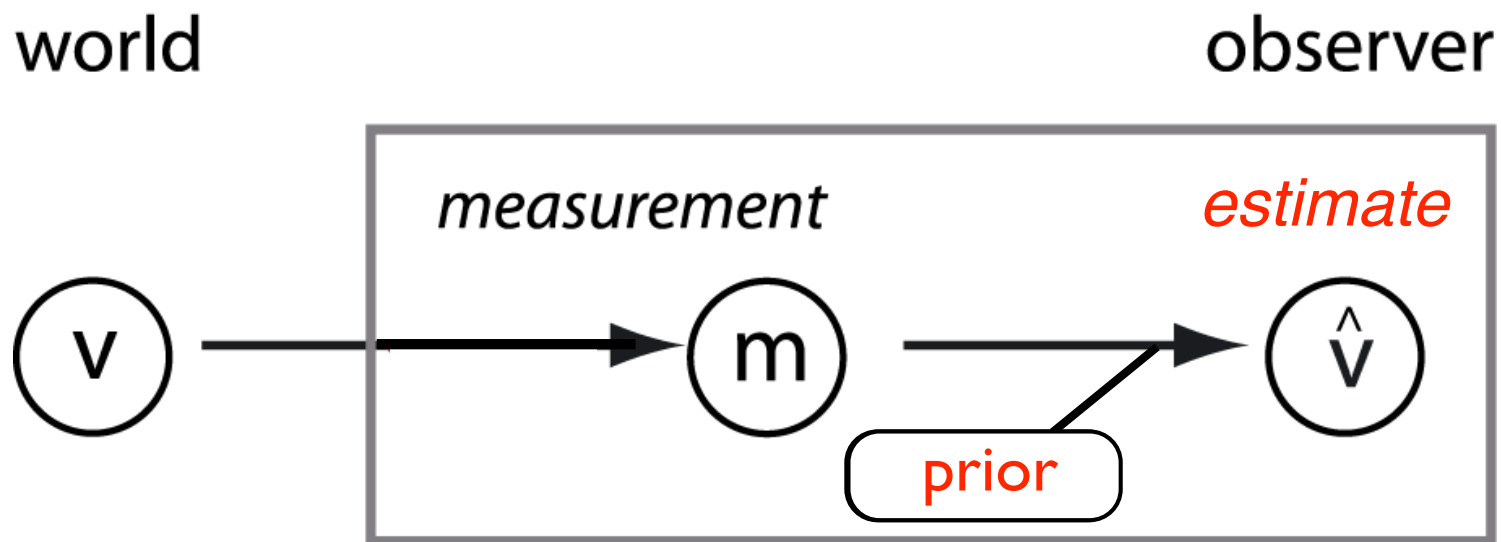


Helmholtz (1866)

Perception is our best guess as to what is in the world, given our current sensory input and our prior experience [paraphrased]



Bayes (1750)

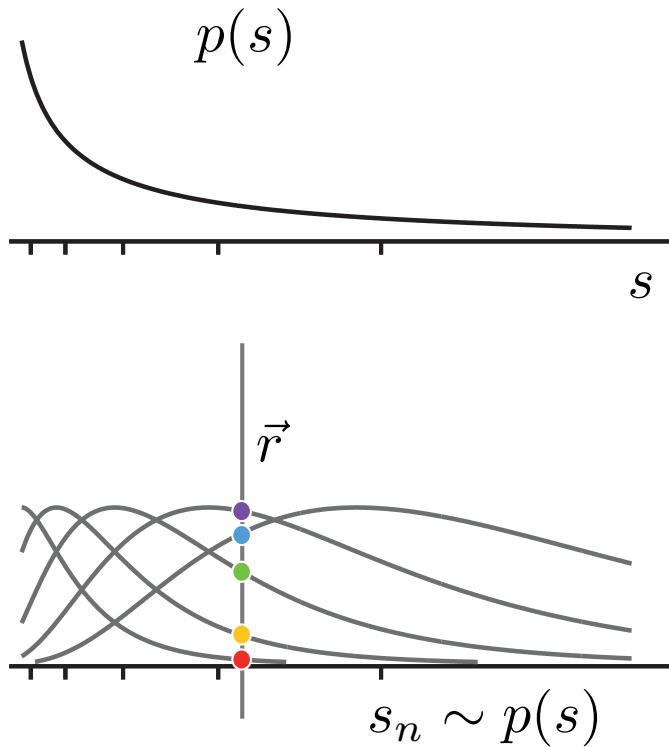


Bayesian perception

- Shading/lighting
[Kersten 90; Knill, Kersten, Yuille 96; Mamassian, Landy, Maloney 01]
- Retinal speed/velocity
[Simoncelli et. al. 91; Heeger & Simoncelli 93; Weiss et al. 02; Stocker & Simoncelli 06]
- Surface orientation [Bülthoff & Yuille 96; Saunders & Knill 01]
- Color constancy [Brainard & Freeman 97]
- Contours [Geisler, Perry, Super 01]
- Sensory-motor tasks [Körding & Wolpert 04]
- 2D orientation [Girshick, Landy & Simoncelli 11]
- Acceleration (vestibular) Laurens & Droulez 08

Physiological instantiation of priors?

- Weighting in “readout” population
[eg: Georgopoulos 1982; Salinas & Abbott 1994; ...]
- Modulatory feedback signals
[eg: Lee & Mumford 2003]
- Spiking activity in a separate population of cells
[eg: Ma et. al., 2009]
- Dynamic network property (responses are samples)
[eg: Tkacik et. al. 2010; Berkes et. al. 2011]
- Population inhomogeneities: baseline rate, gain, tuning width, and cell density
[Stocker & Simoncelli 2006; Simoncelli, 2009; Ganguli & Simoncelli, 2010; Fischer & Pena 2011; Girshick, et. al. 2011]

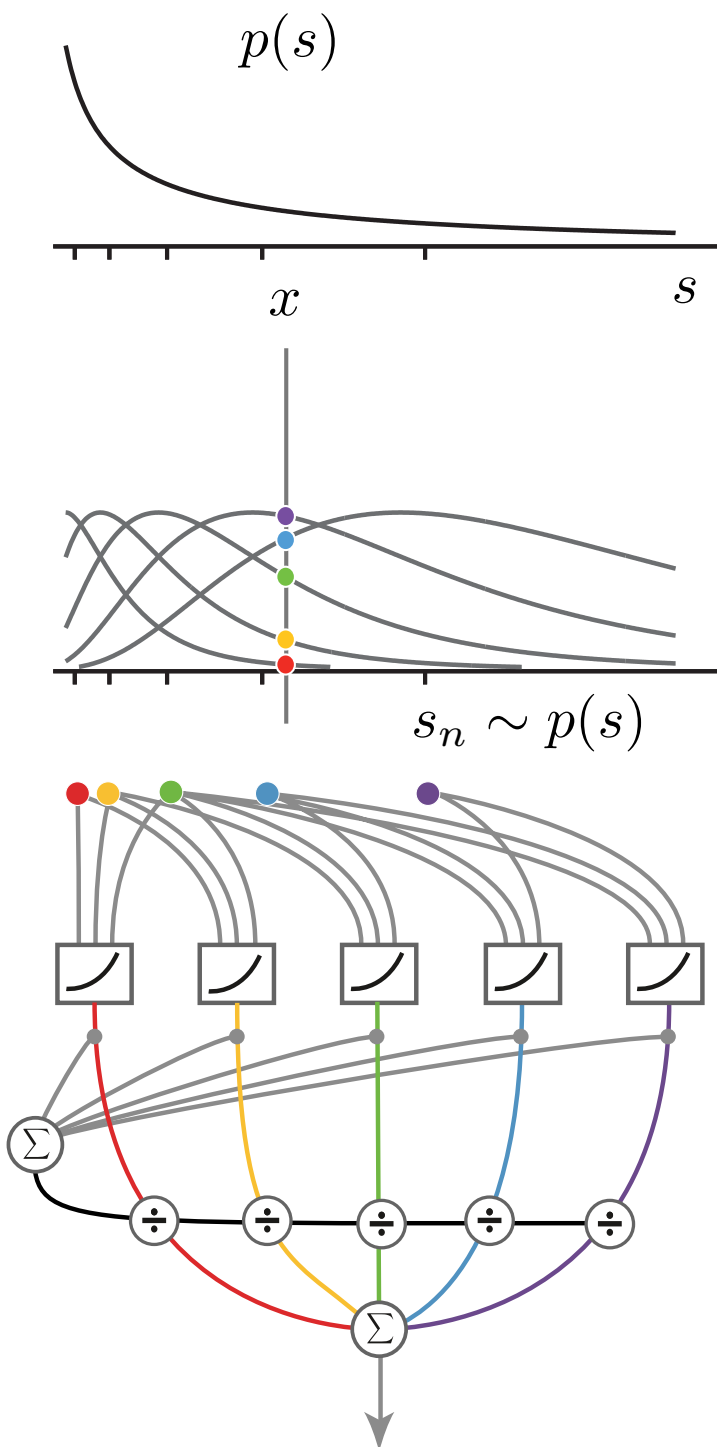


Bayes least squares estimator:

$$\hat{s}_{\text{BLS}}(\vec{r}) = \frac{\int s p(\vec{r}|s) p(s) \, ds}{\int p(\vec{r}|s) p(s) \, ds}$$

Discrete (Riemann) approximation:

$$\begin{aligned} \hat{s}_{\text{BLS}}(\vec{r}) &\approx \frac{\sum_{n=1}^N s_n p(\vec{r}|s_n) p(s_n) \Delta_n}{\sum_{n=1}^N p(\vec{r}|s_n) p(s_n) \Delta_n} \\ &= \frac{\sum_{n=1}^N s_n p(\vec{r}|s_n)}{\sum_{n=1}^N p(\vec{r}|s_n)} \end{aligned}$$



$$\hat{s}_{\text{BLS}}(\vec{r}) \approx \frac{\sum_{n=1}^N s_n p(\vec{r}|s_n)}{\sum_{n=1}^N p(\vec{r}|s_n)}$$

$$= \frac{\sum_{n=1}^N s_n \exp\left(\sum_{m=1}^N r_m \cdot w_{m-n}\right)}{\sum_{n=1}^N \exp\left(\sum_{m=1}^N r_m \cdot w_{m-n}\right)}$$

Similar to the “population vector”

[Georgopoulos et. al. 86]

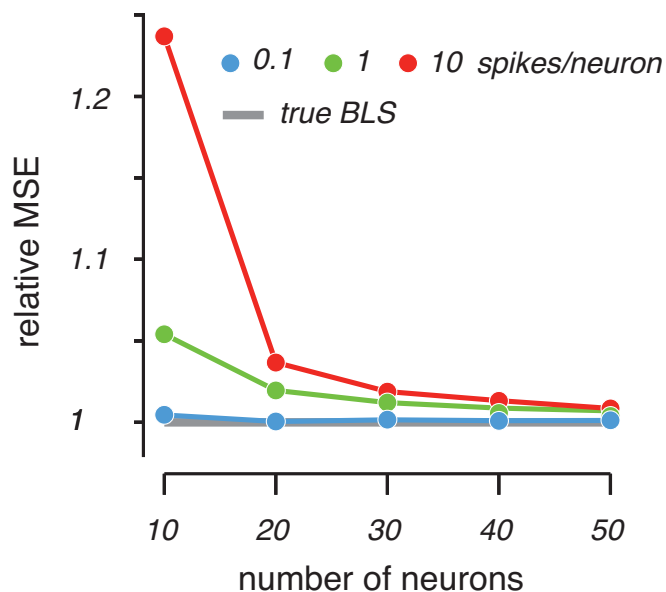
$$\hat{s}_{\text{PV}}(\vec{r}(x)) \approx \frac{\sum_{n=1}^N s_n r_n}{\sum_{n=1}^N r_n}$$

... which has been previously proposed
as an approximate Bayes estimator

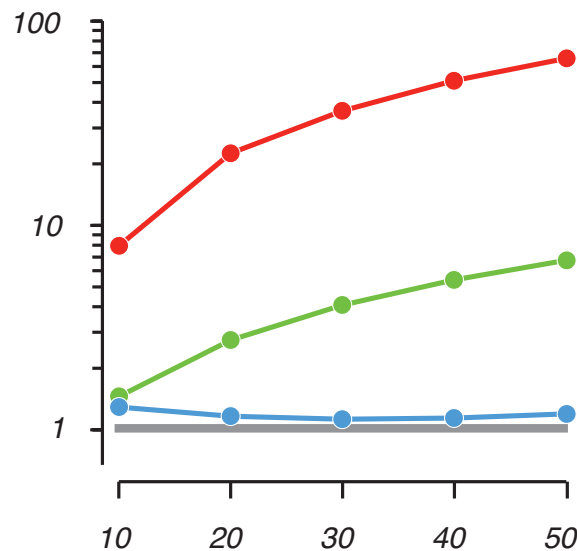
[Shi & Griffiths 09; Fischer & Pena 11]

Example (power law stimulus distribution)

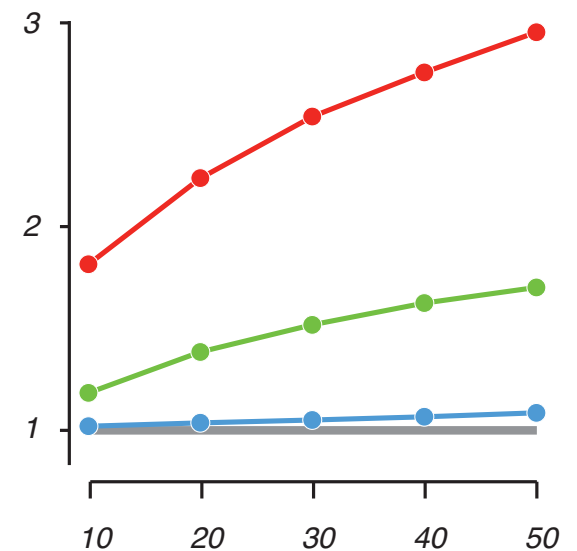
BLS-modified
population vector



Conventional
population vector



Optimized
population vector



● 0.1 ● 1 ● 10 spikes/neuron
— true BLS

Optimally efficient populations...

- provide a direct link between **measurable** quantities: environmental distribution, density/tuning of neurons, and perceptual discriminability
- suggest that **information maximization** is more consistent with physiological/perceptual data than **estimation/discrimination accuracy**
- provide an embedding of environmental probabilities, readily incorporated into Bayesian decoders
- Missing:
 - Multi-dimensional stimulus variables
 - Feature learning
 - Biological optimization (development, adaptation)