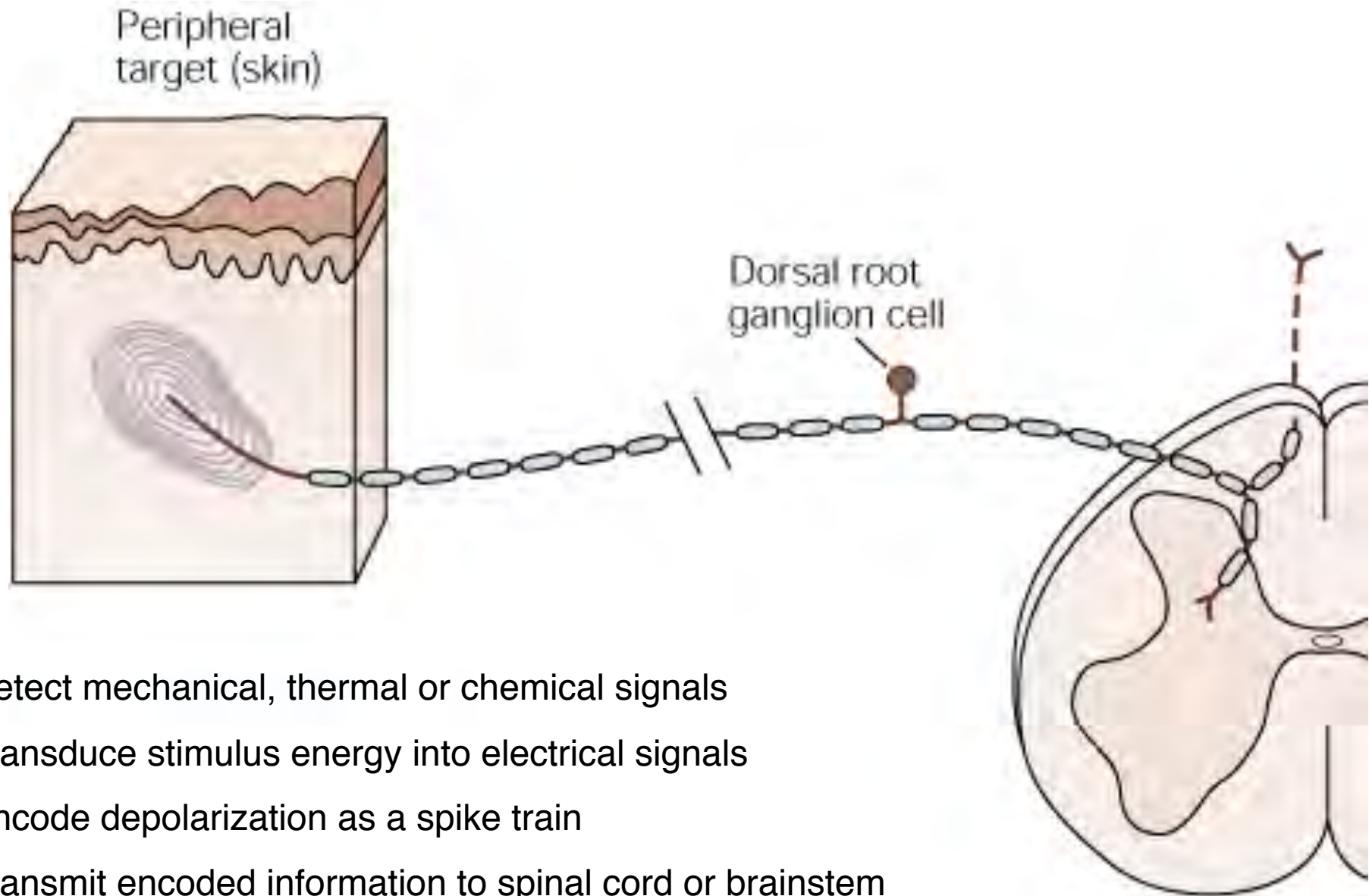


Somatosensory modalities

- The somatosensory system codes five major sensory modalities:
 1. Discriminative touch
 2. Proprioception (body position and motion)
 3. Nociception (pain and itch)
 4. Temperature
 5. Visceral function
- Senses external objects contacting the body
- Provides self-awareness of our bodies

Dorsal root ganglion neurons mediate somatic sensation



- Detect mechanical, thermal or chemical signals
- Transduce stimulus energy into electrical signals
- Encode depolarization as a spike train
- Transmit encoded information to spinal cord or brainstem

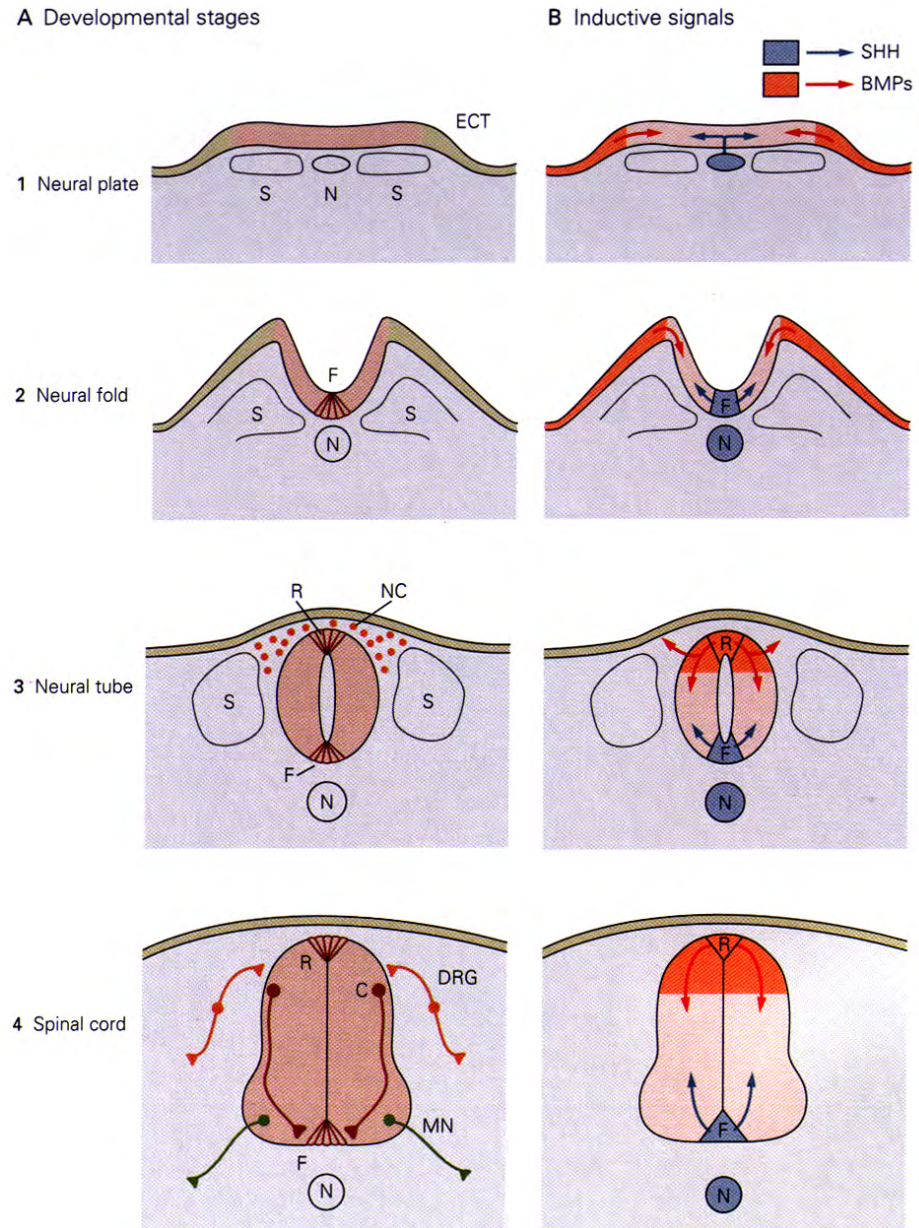
Common properties of DRG neurons

- Sensory transduction occurs in the nerve endings, not in the DRG or trigeminal cell bodies
- Sensory modality determined by the receptor proteins expressed in the nerve terminals, and anatomical structures enclosing these endings
- DRGs often express receptor proteins in their somas allowing transduction mechanisms to be studied *in vitro*

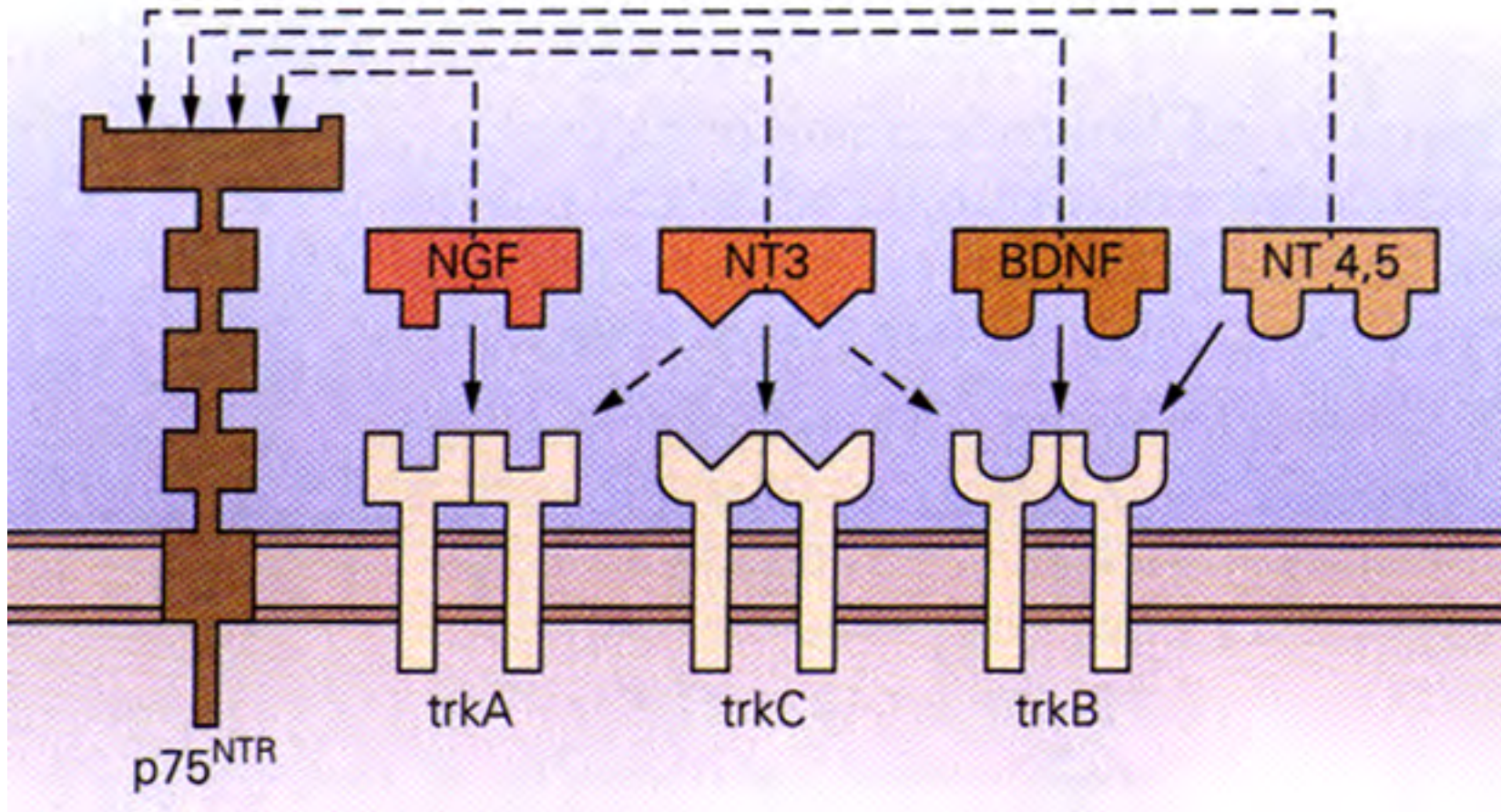
Dorsal root ganglion neurons differ in:

- Cell body *size*
- *Morphology* and sensitivity of nerve terminal
- *Sensations* mediated
- Body *region* innervated
- Axon *conduction velocity* and fiber diameter
- Spinal and brainstem *termination sites*
- Ascending *pathways* to higher brain centers
- Sensitivity to *neurotrophins* during development

DRGs develop from neural crest cells



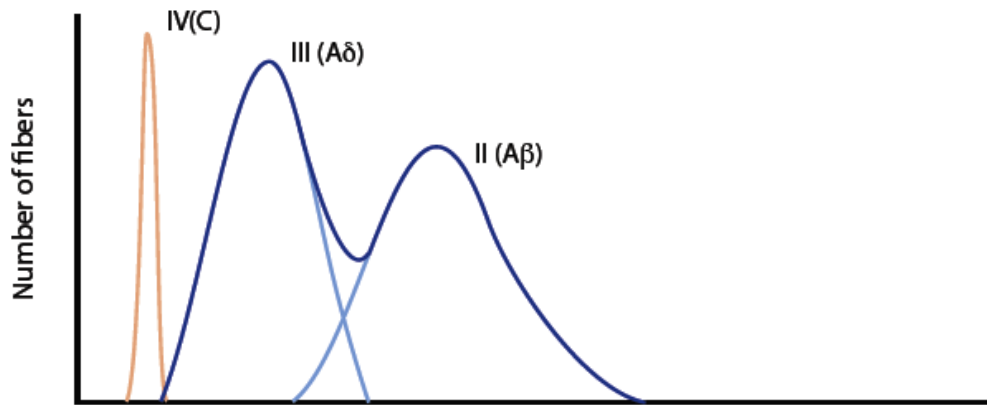
DRGs express neurotrophin receptors



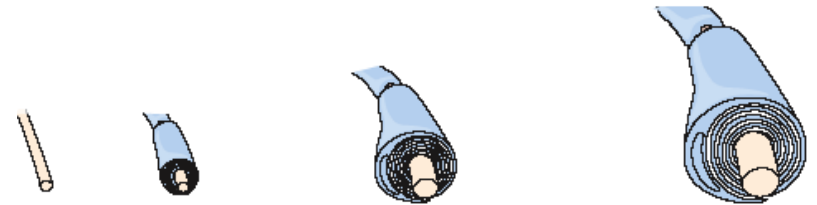
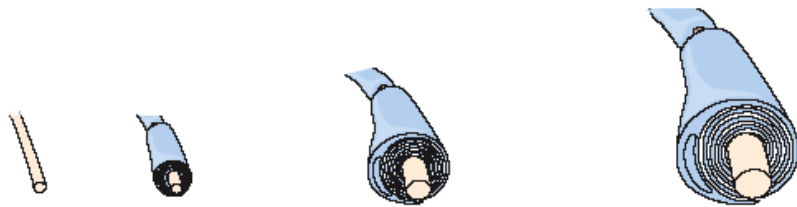
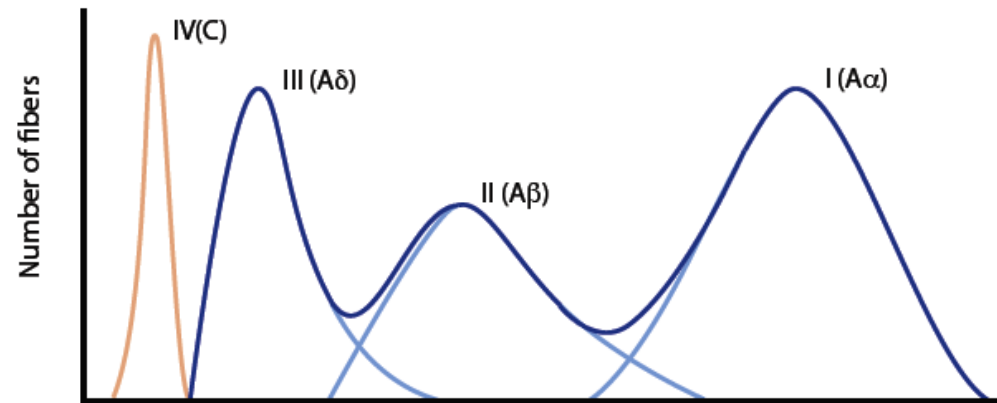
- trkA: free nerve endings (pain and temperature)
- trkB: mechanoreceptors in skin, muscle, joints
- trkC: muscle spindles and tendon organs

Fiber diameter profile for different modalities

Cutaneous nerve



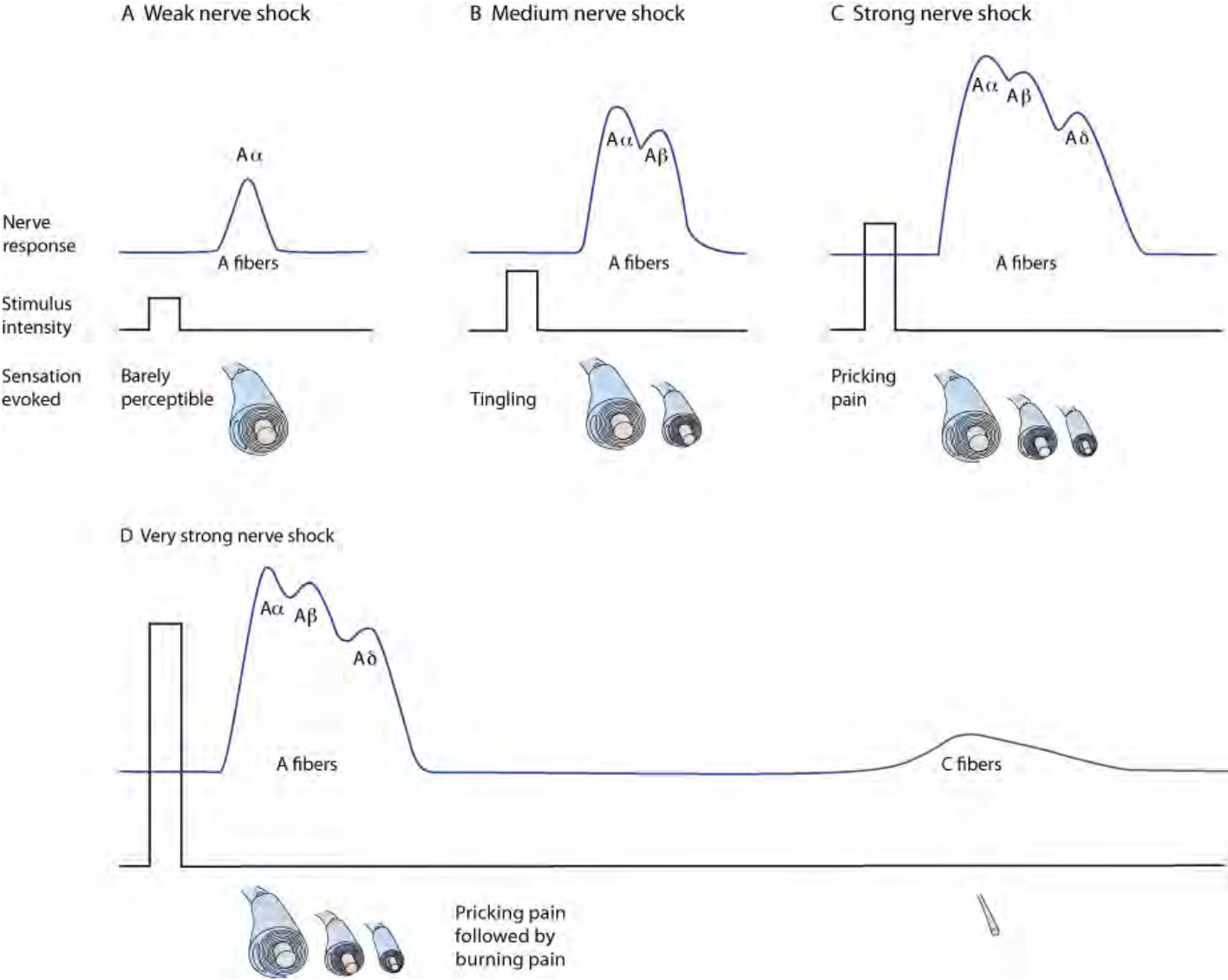
Muscle nerve



Axon diameter (μm)	1	5	12	20
Conduction velocity (m/s)	6	30	72	120

Axon diameter (μm)	1	5	12	20
Conduction velocity (m/s)	6	30	72	120

Compound action potential reflects whole nerve activity



Conduction velocity classification

$A\alpha$	72–120 m/s	α motor neurons to muscle Group I muscle sensory Cutaneous mechanoreceptors
$A\beta$	30–96 m/s	Cutaneous mechanoreceptors Secondary muscle receptors
$A\gamma$	12–48 m/s	γ motor neurons
$A\delta$	4–30 m/s	Group III sensory nerves
B	3–15 m/s	Autonomic preganglionics
C	0.5–2 m/s	Unmyelinated sensory nerves Autonomic postganglionics

The Sense of Touch



Jusepe de Ribera
c. 1615-16

Norton Simon Museum
Pasadena CA

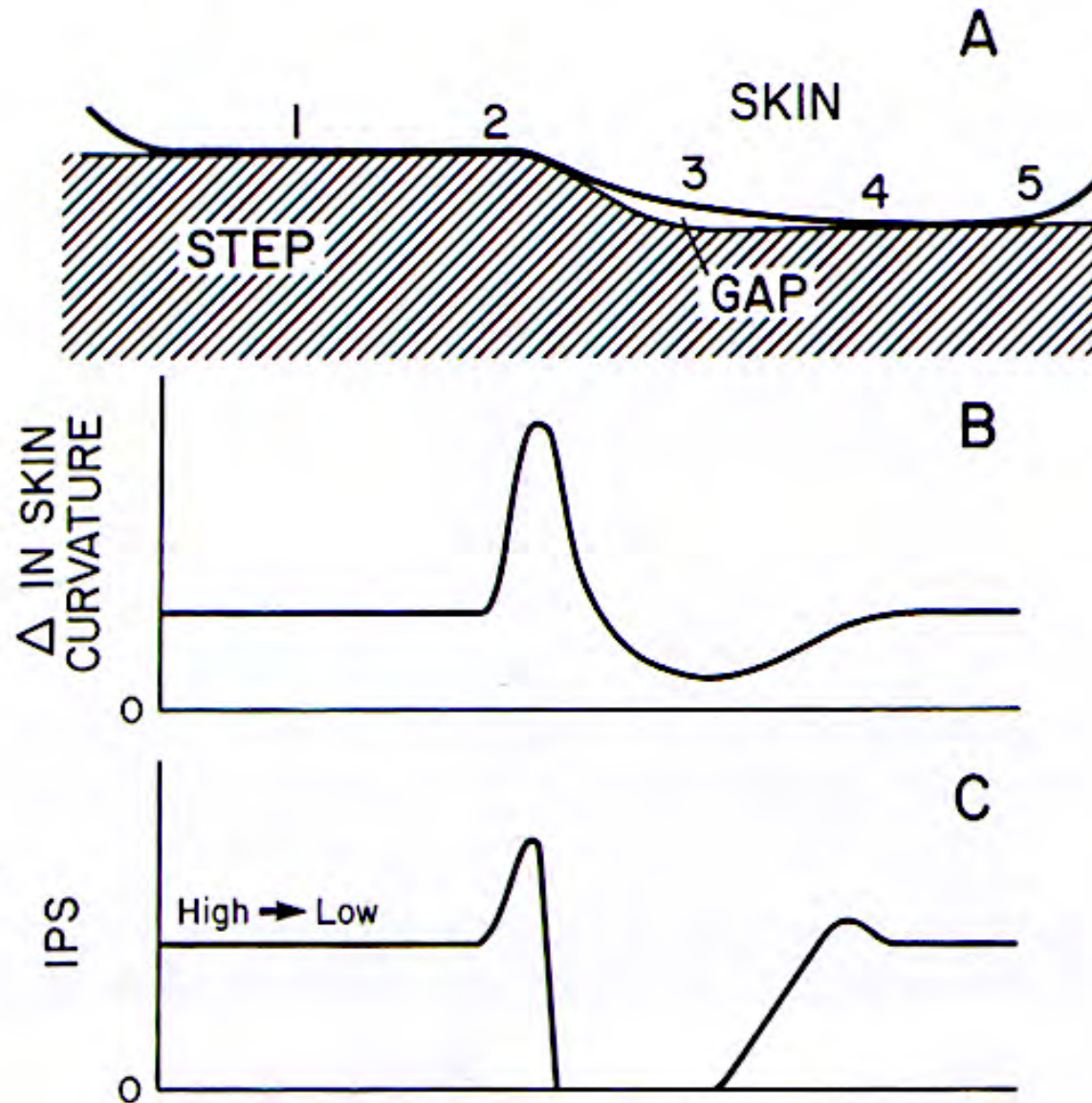
The sense of touch

- Touch is the special sense by which contact with the body is perceived in the conscious mind
- Touch allows us to recognize objects held in the hand and use them as tools
- Touch enables the blind to perceive the three dimensional form of objects, and to read Braille with their fingers
- Touch guides skilled hand movements of the surgeon, the sculptor, the musician, the pitcher, and the chef
- Touch is mediated by mechanoreceptors in the skin

Properties coded by the sense of touch

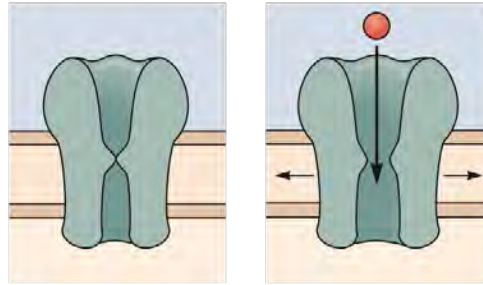
- Spatial dimensions (size, shape, weight)
- Surface compliance (hard or soft)
- Surface texture (smooth or rough, regular or irregular)
- Temperature (hot, warm, cool, cold)
- Motion (active or passive, velocity, direction)
- Cognitive function (object recognition)

The sense of touch is mediated by skin indentation

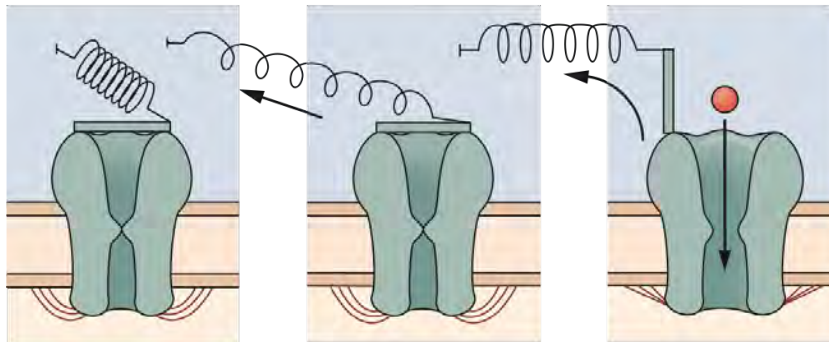


Mechanoreceptors detect tissue deformation

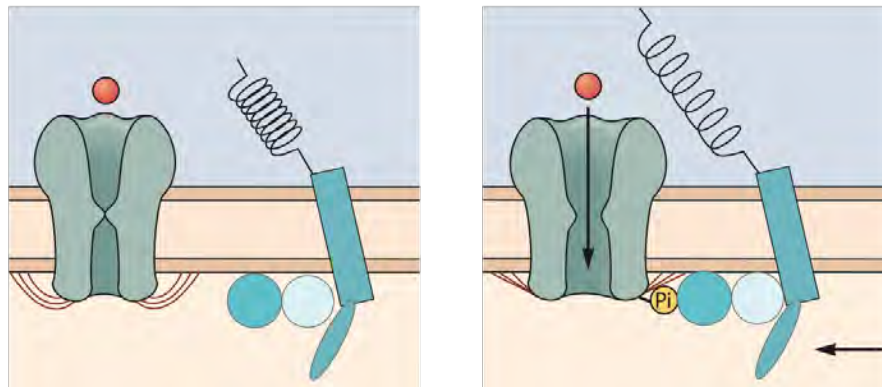
A Direct activation through lipid tension



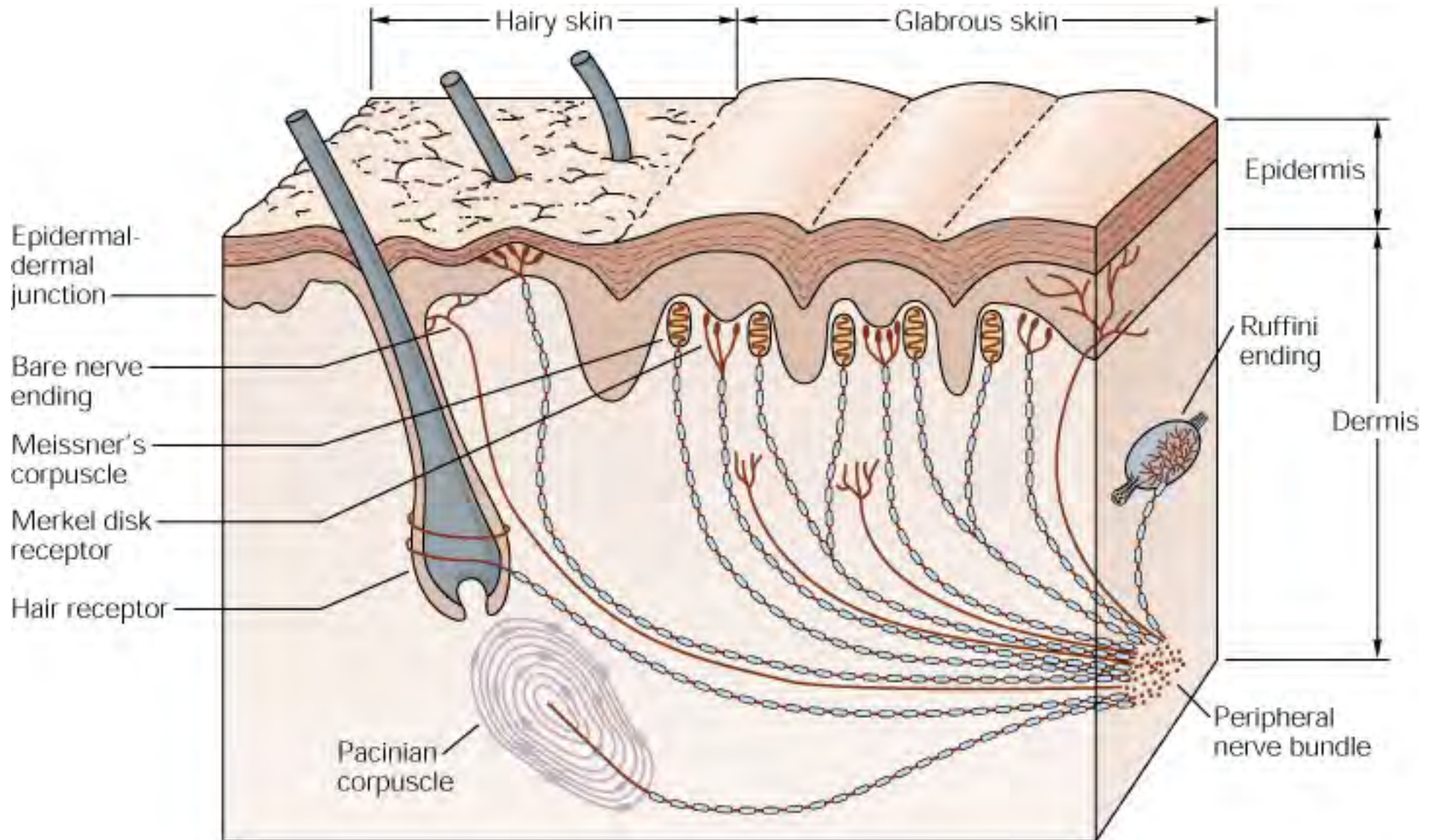
B Direct activation through structural proteins



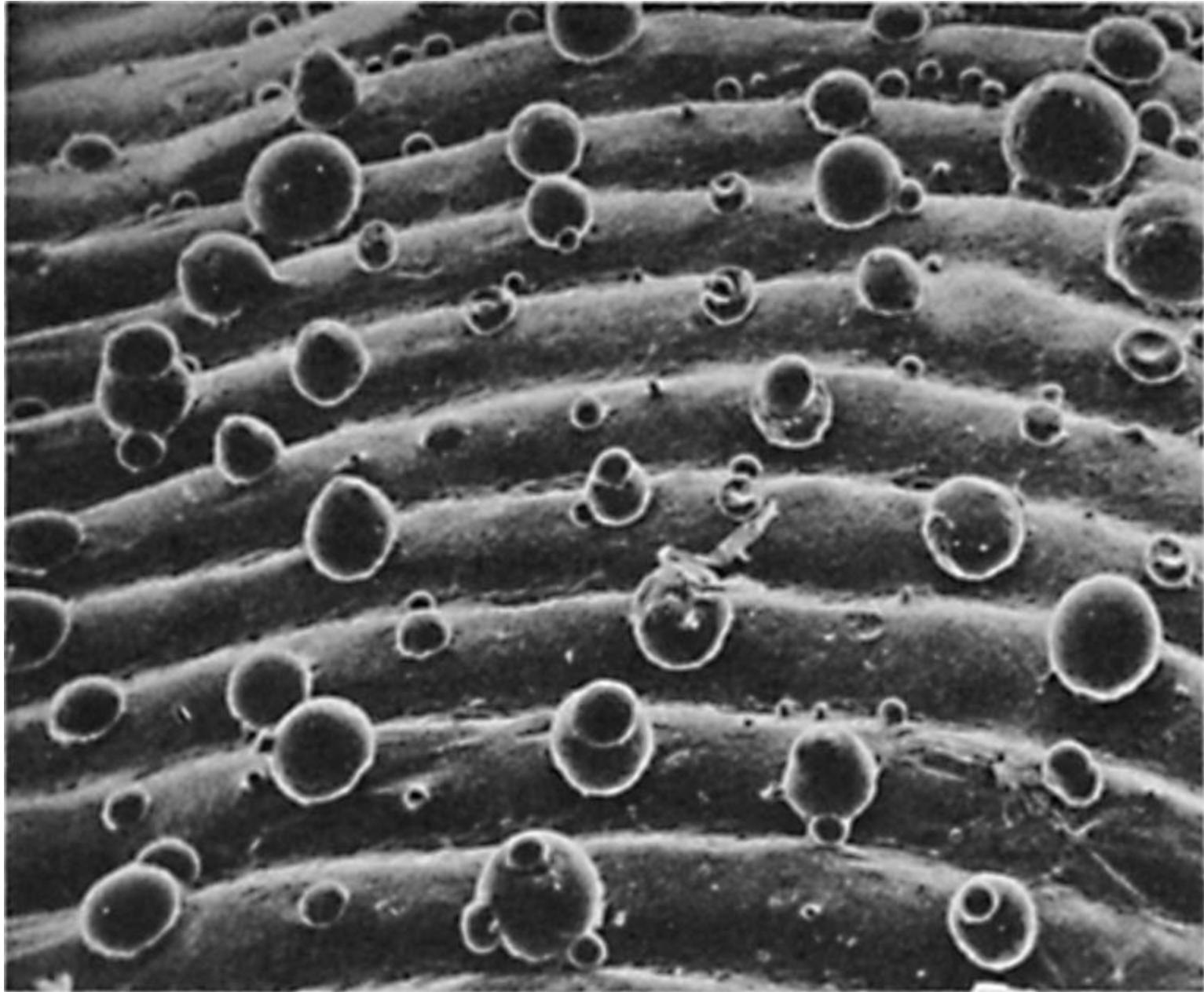
C Indirect action through membrane structural proteins



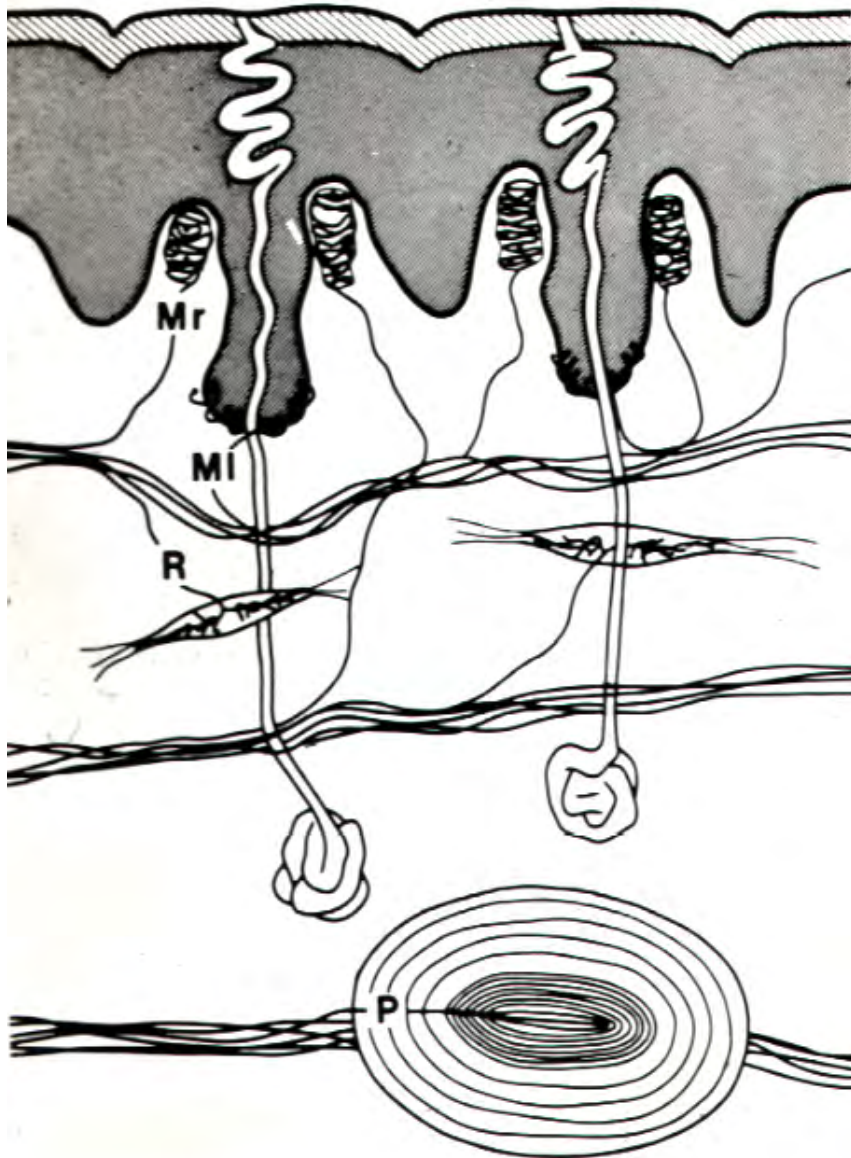
Multiple receptor types in the skin



Scanning EM of fingerprint ridges in glabrous skin



Four types of mechanoreceptors in glabrous skin



Meissner's corpuscles (RA1)

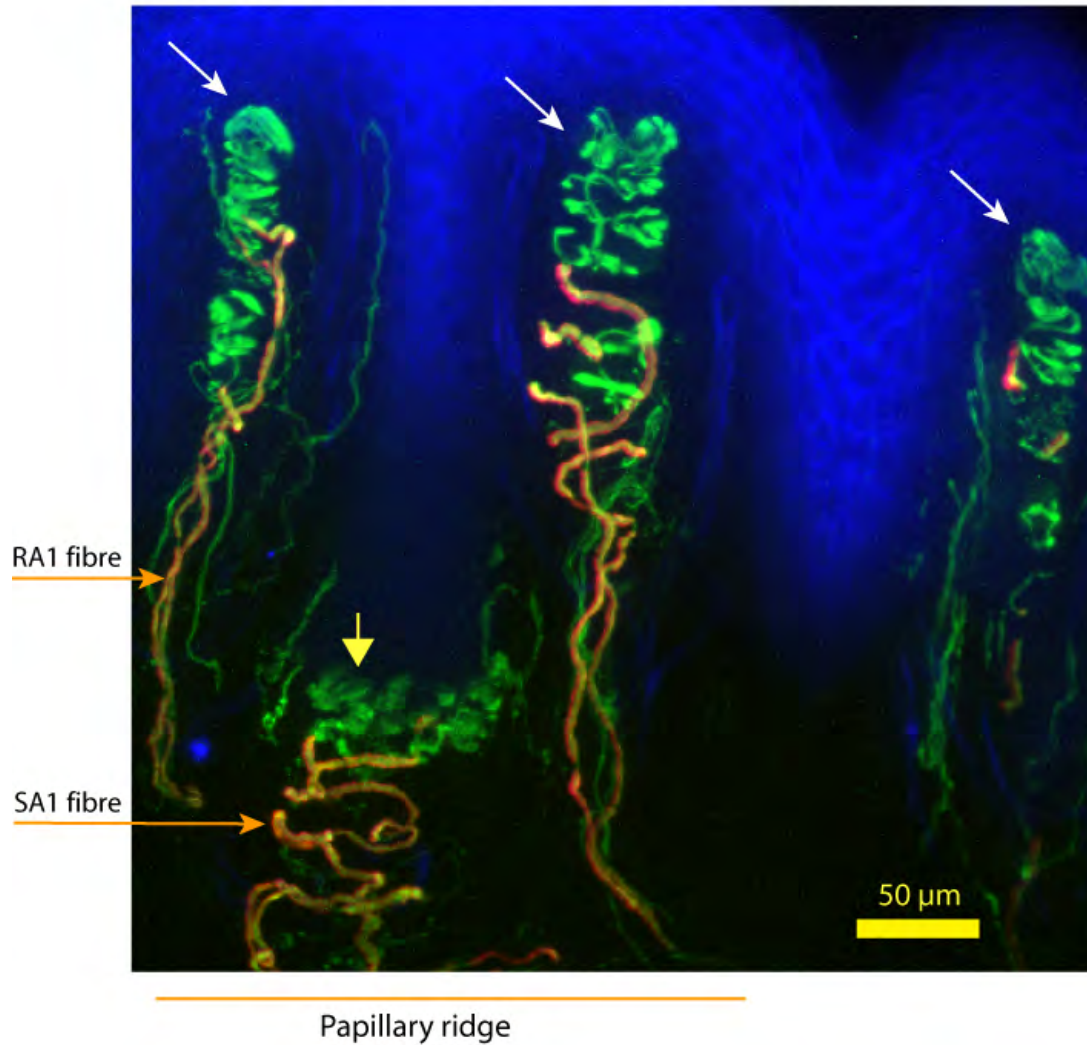
Merkel cells (SA1)

Ruffini endings (SA2)

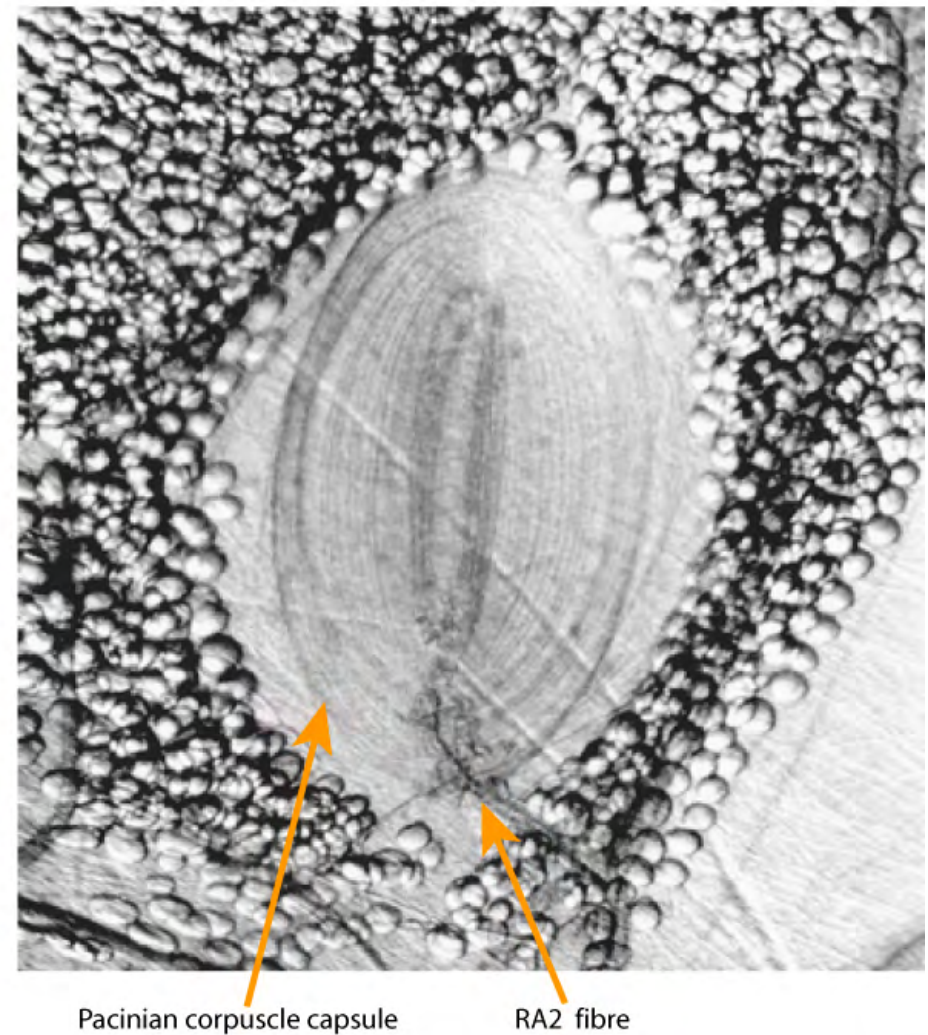
Pacinian corpuscles (RA2)

Touch receptors in the glabrous skin

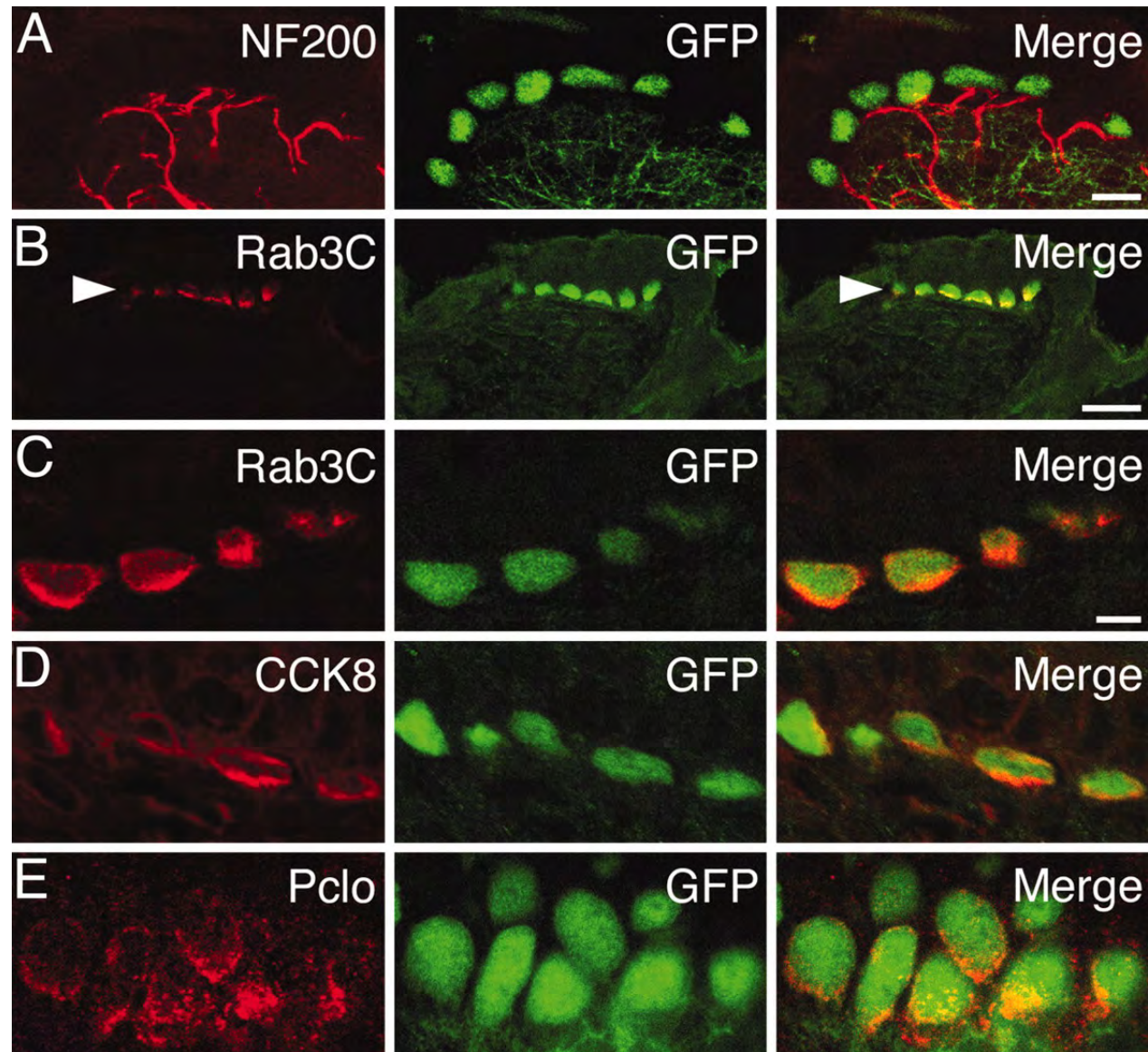
A Meissner corpuscles and Merkel cell receptors



B Pacinian corpuscle

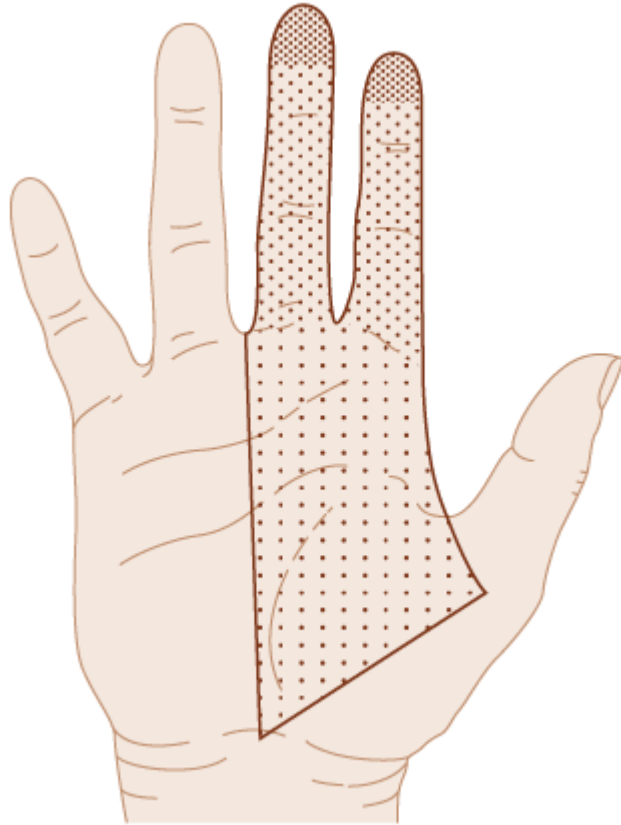


SA1 fibers innervate clusters of Merkel cells

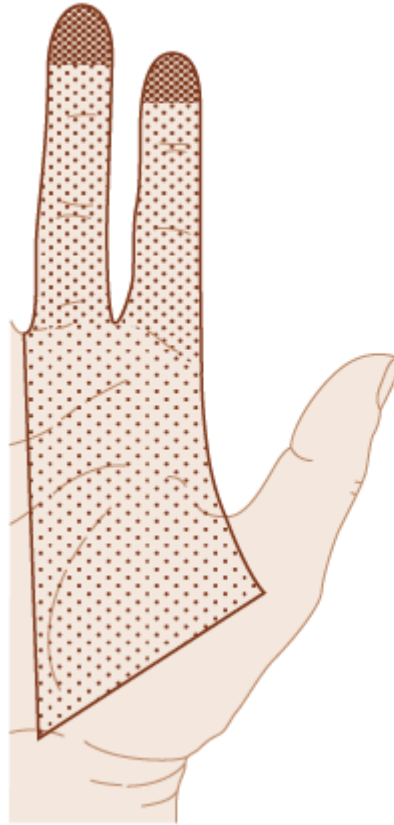


Receptor density in glabrous skin

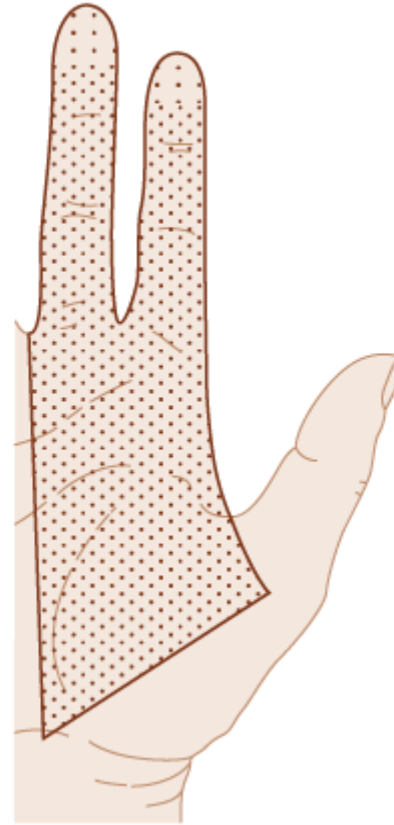
SA I (Merkel)



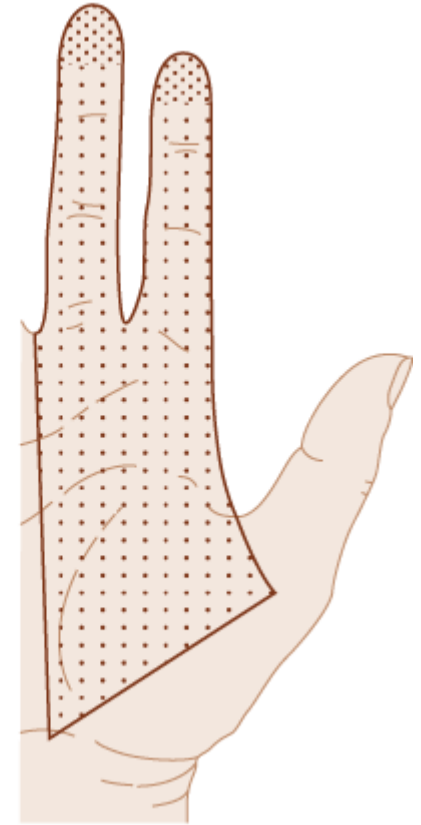
RA (Meissner's)



SA II (Ruffini)



PC (Pacini)



• Fingertip

- RA = 141 /cm² SA I = 70 /cm²
- PC = 21 /cm² SA II = 9 /cm²

• Palm

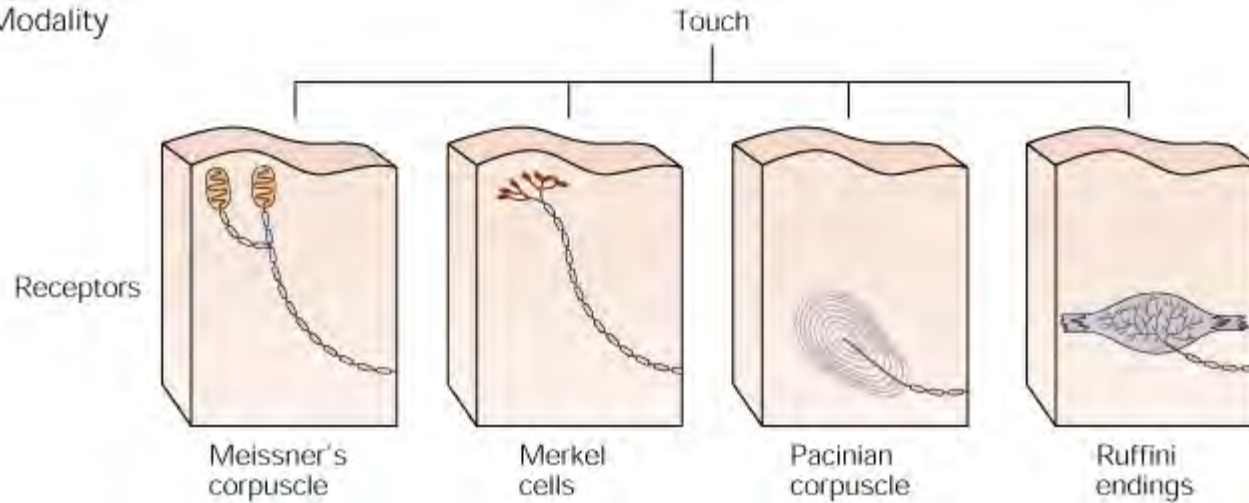
- RA = 25 /cm² SA I = 8 /cm²
- PC = 9 /cm² SA II = 16 /cm²

Why have multiple touch receptors?

- Specialize for dynamic and static sensitivity
 - **Motion** sensors (RA1 and RA2)
 - **Pressure** sensors (SA1 and SA2)
- Different sensory **thresholds** extend range of intensities encoded ($RA2 < RA1 < SA1 < SA2$)
- Different **receptive field** areas encode fine (RA1 and SA1) and broad (RA2 and SA2) spatial information

Phasic and tonic responses to touch

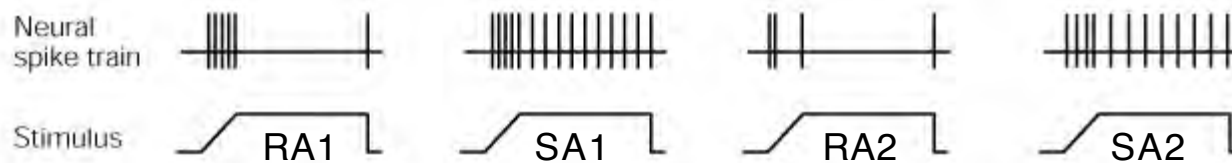
A Modality



B Location

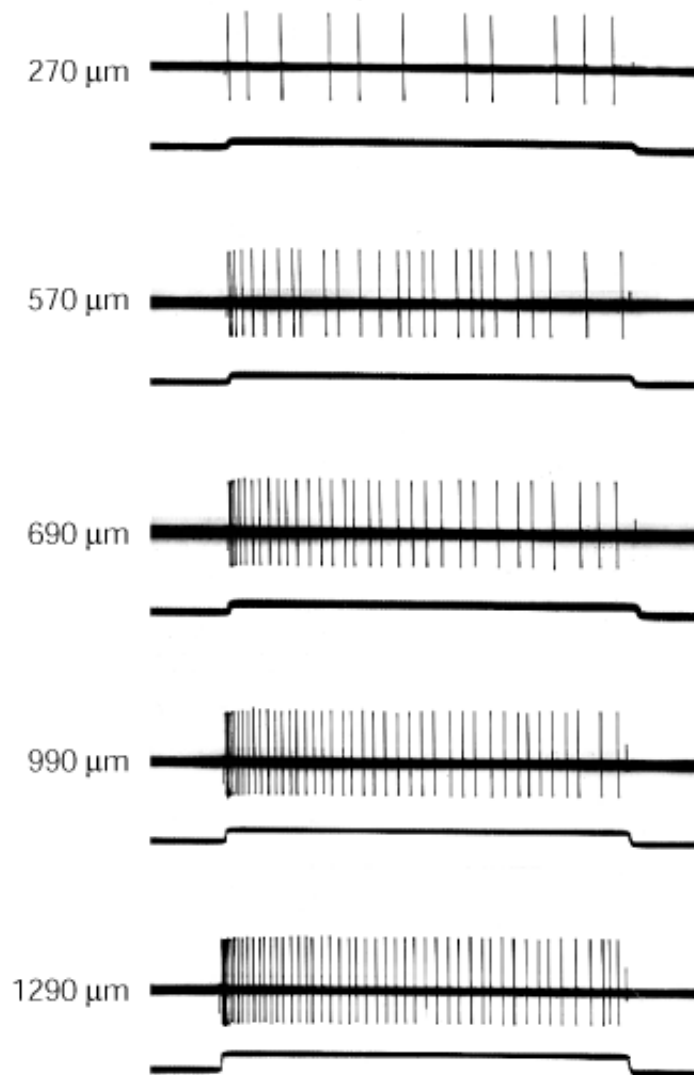


C Intensity and time course

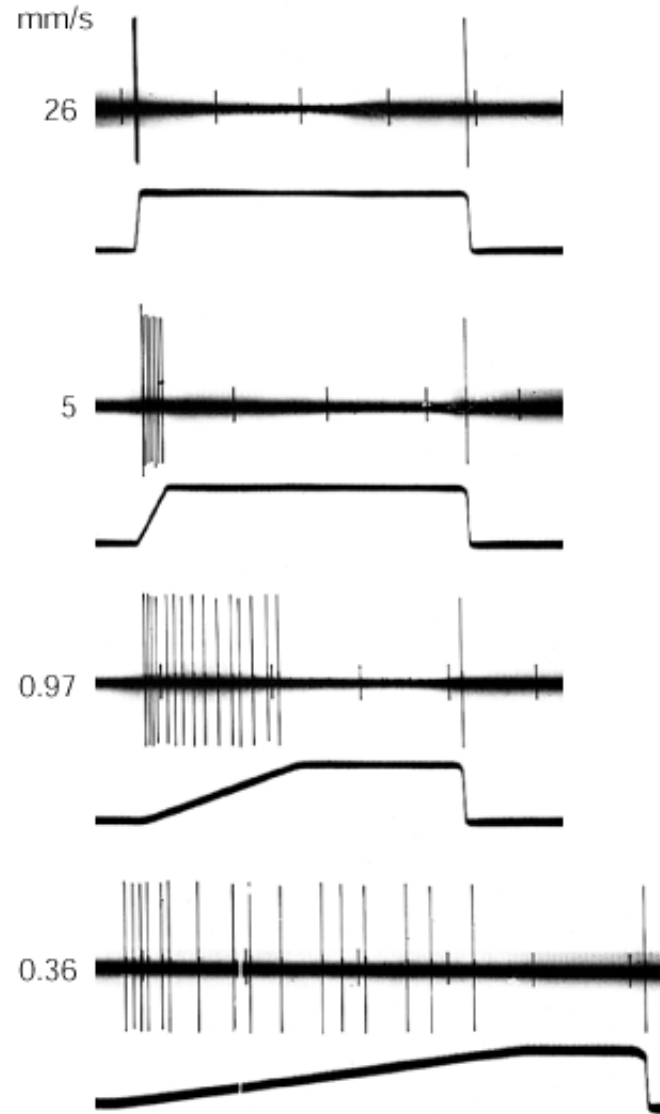


Slow and rapid adaptation of touch receptors

A Slowly adapting receptor

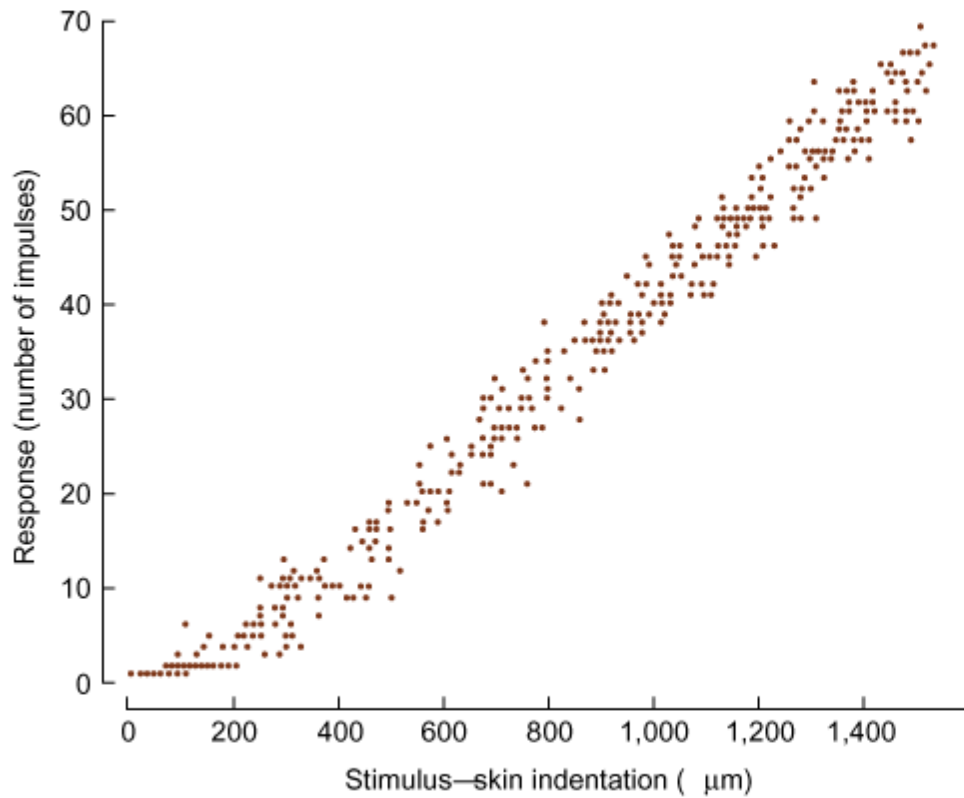


B Rapidly adapting receptor

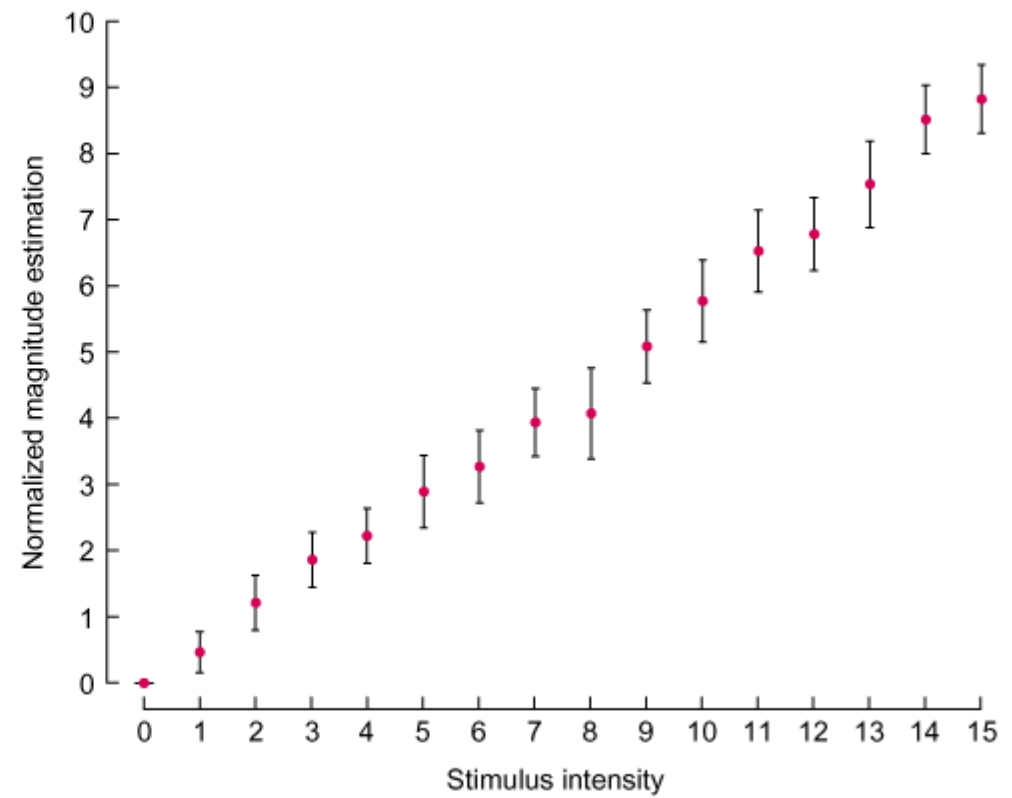


Neural firing rate codes stimulus intensity

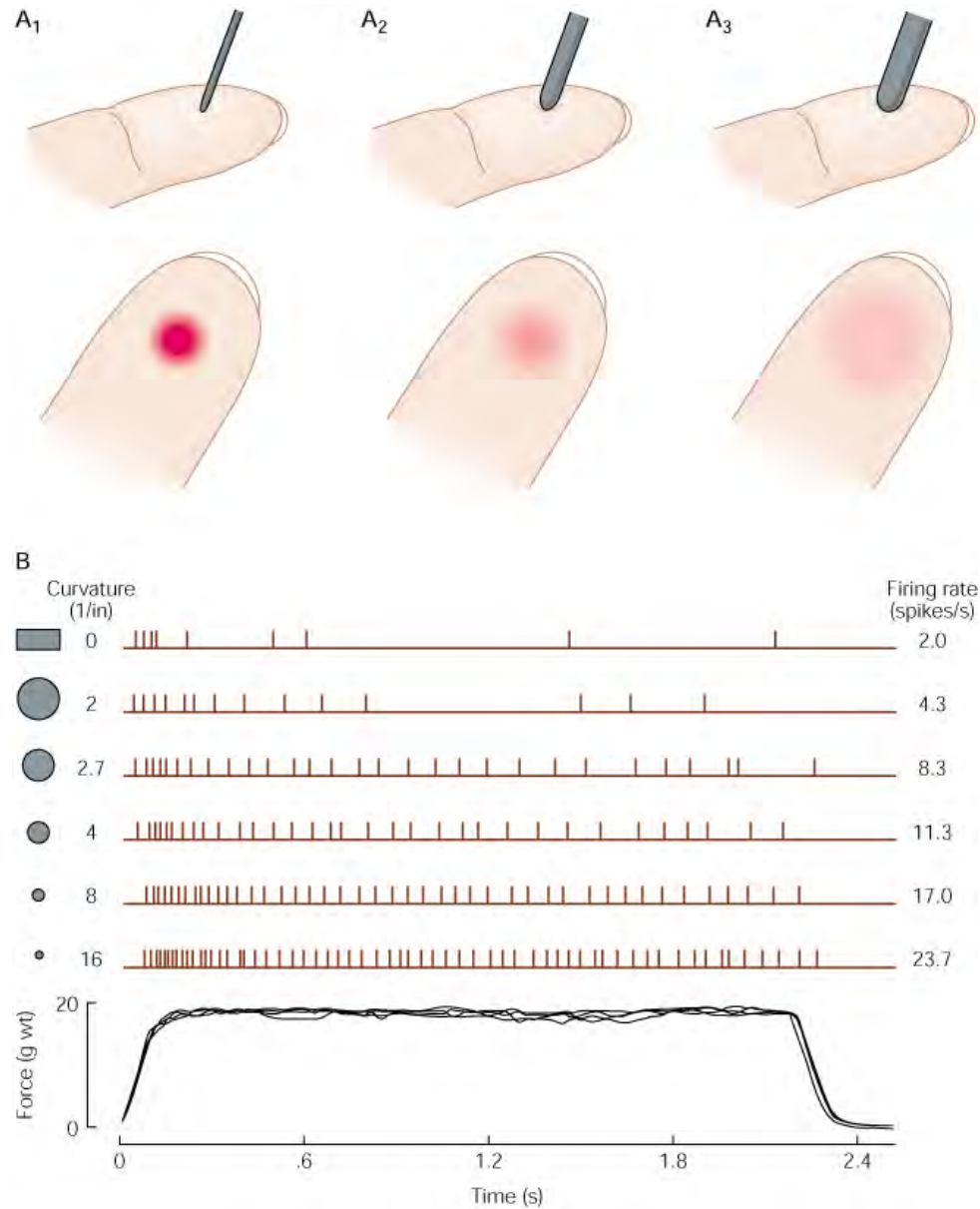
A Neural code of stimulus magnitude



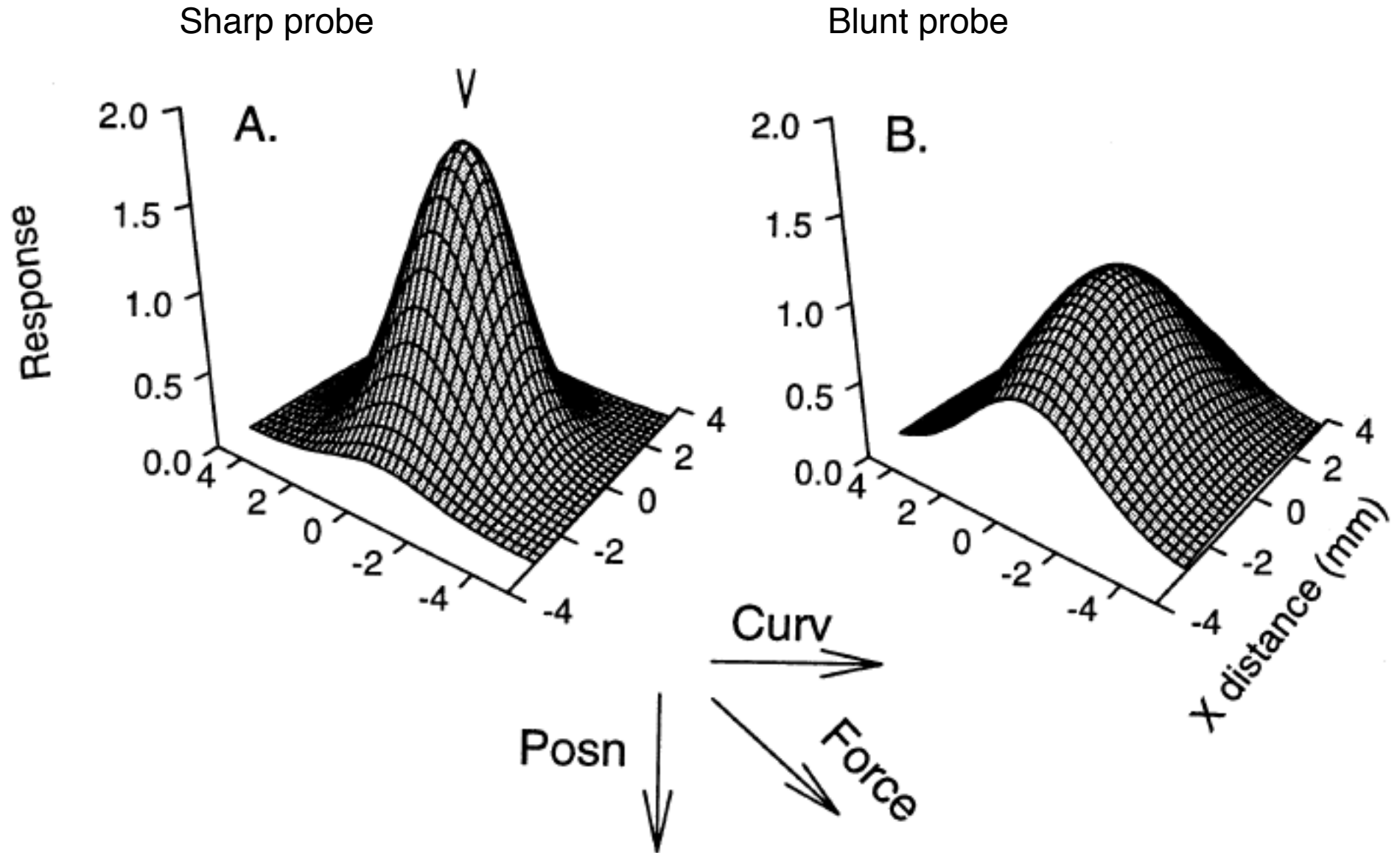
B Perceived sensation intensity



Merkel cells (SA1 fibers) signal shape and pressure



Fingertip SA1 responses to object curvature



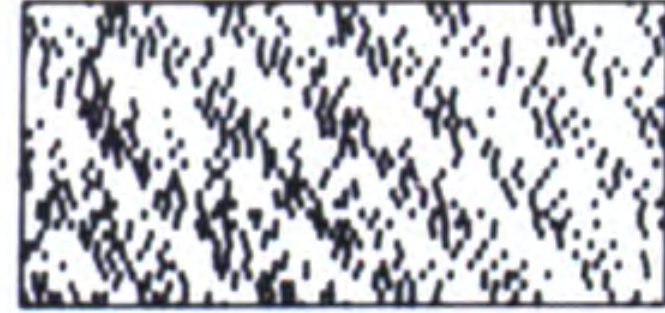
Merkel cells are used to read Braille dots



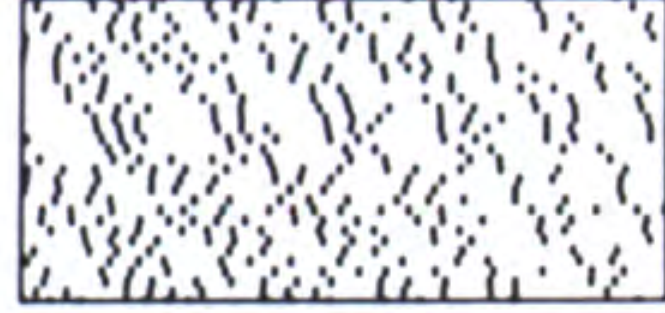
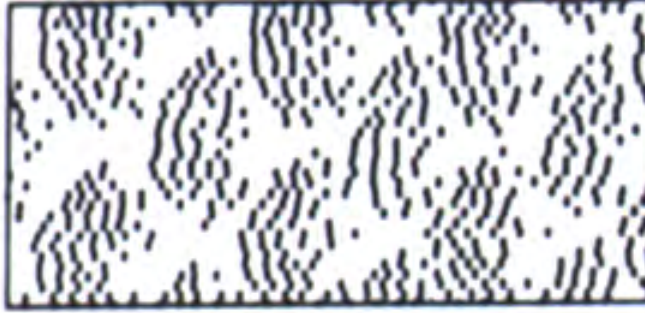
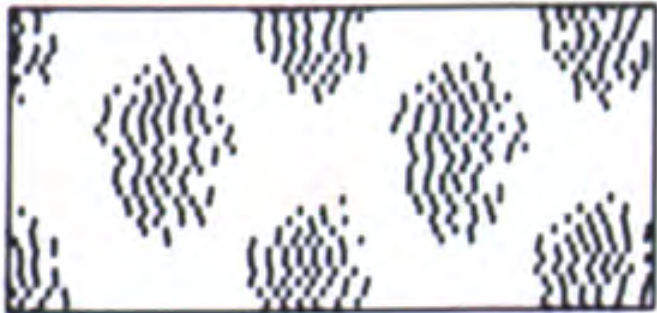
4.0 mm dot spacing



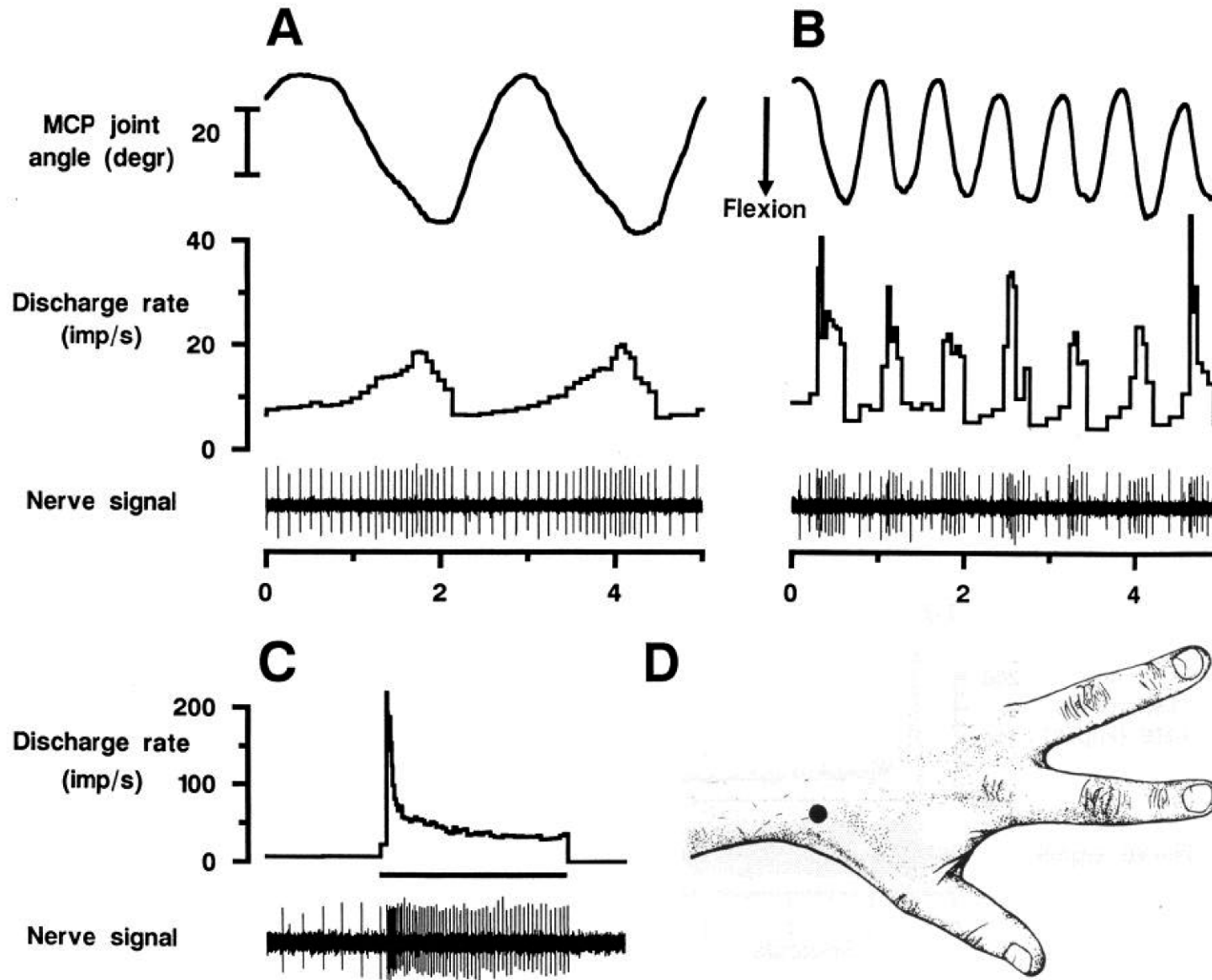
2.8 mm dot spacing



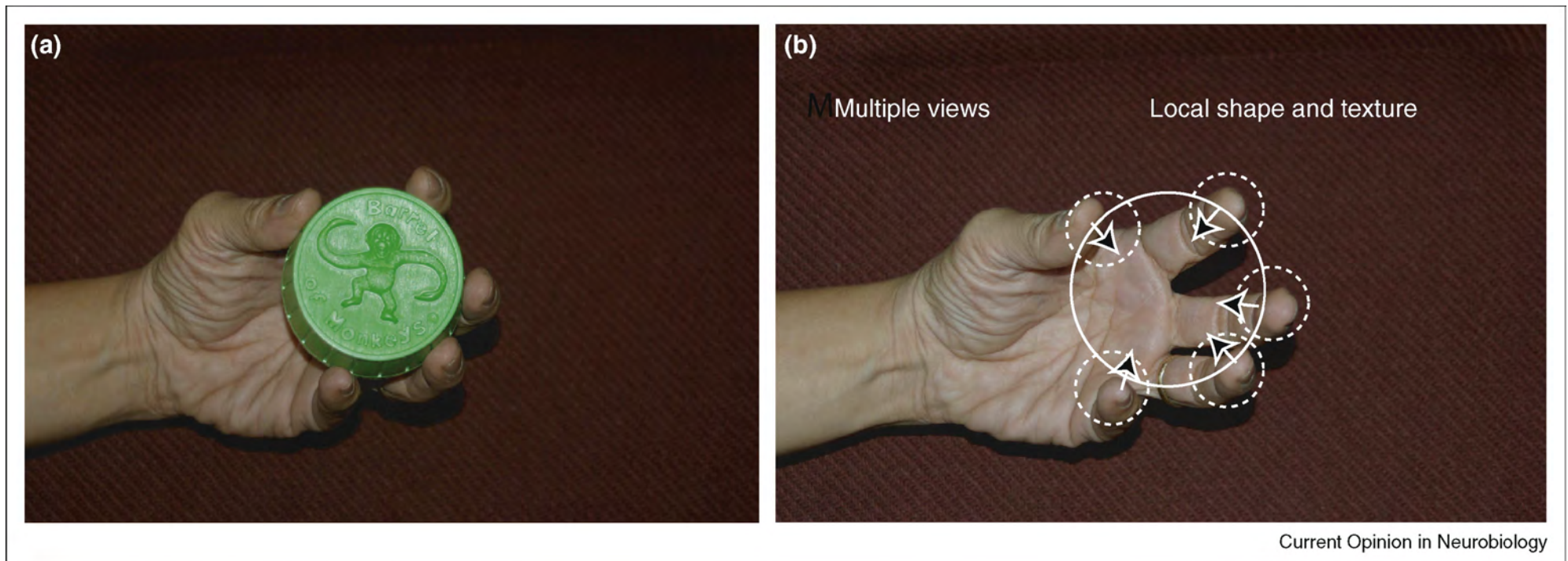
1.7 mm dot spacing



Ruffini endings (SA2 fibers) respond to skin stretch



Hand posture and skin stretch codes object shape

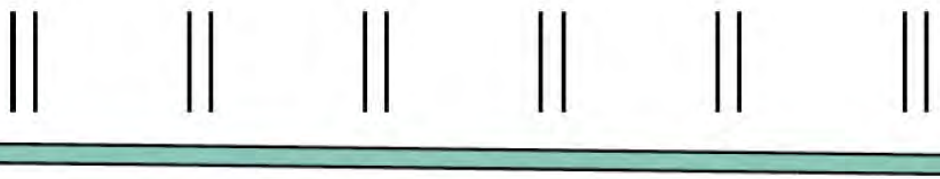
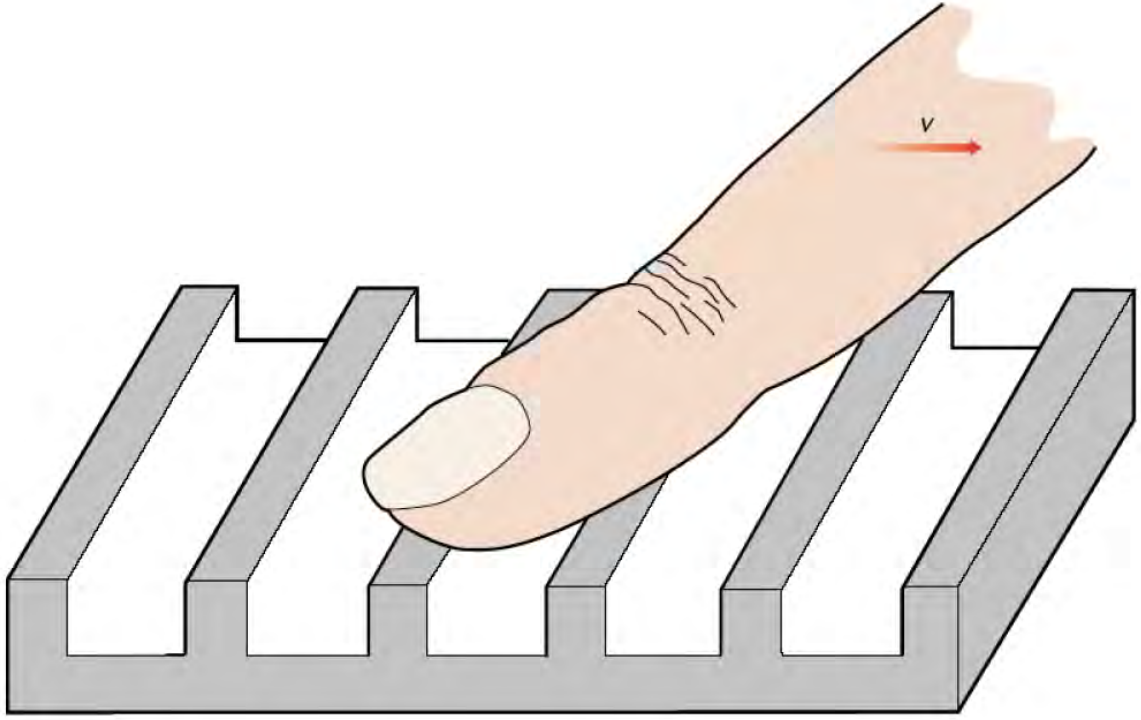


Hsiao SS (2008)

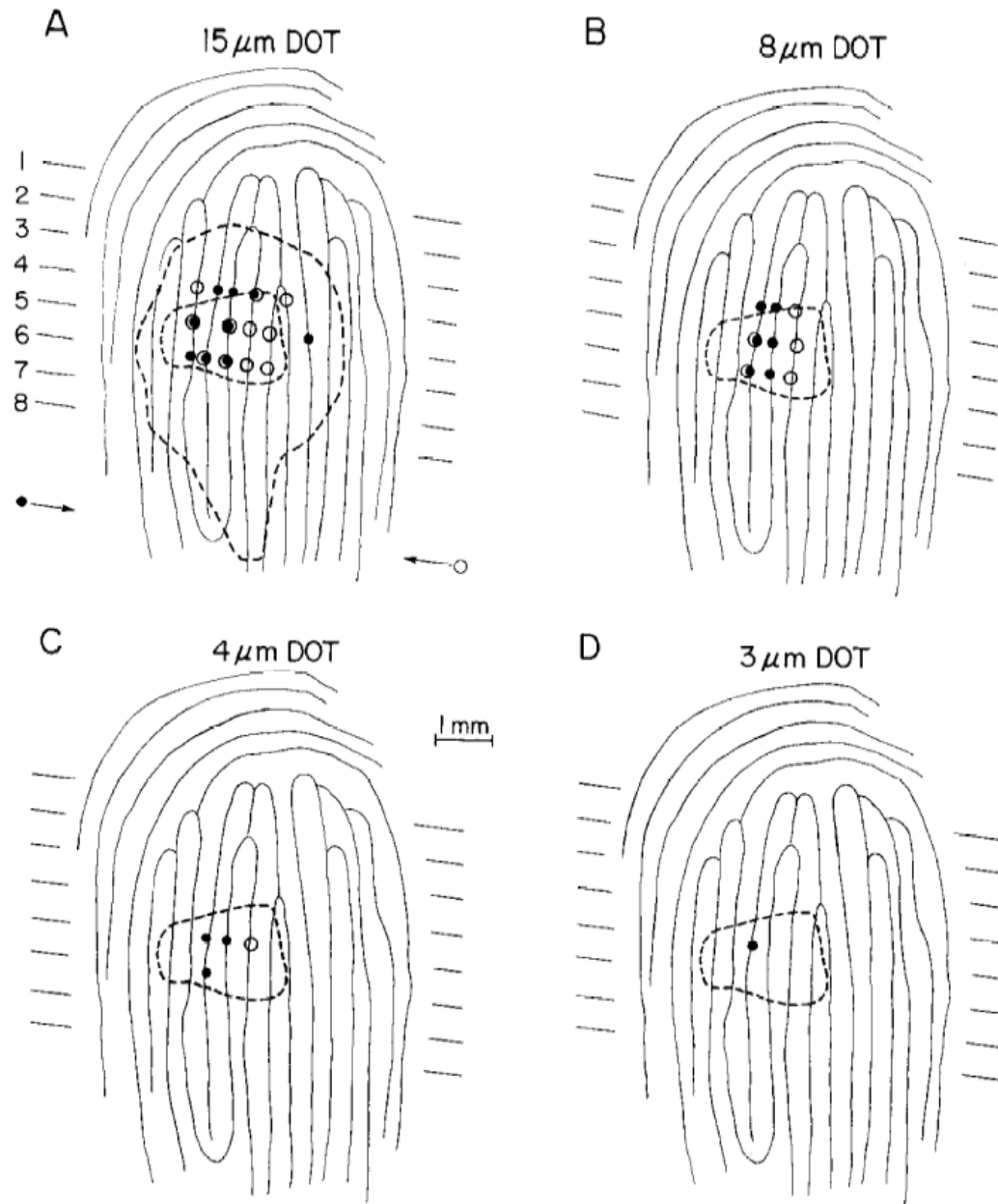
Slowly-Adapting Receptor Function

- **Merkel** cell (SA1 fiber):
 - Pressure, object weight
 - Precision grip force
 - Small object shape discrimination
 - Braille reading and texture discrimination
- **Ruffini** ending (SA2 fiber):
 - Whole hand grip
 - Hand posture and skin stretch
 - Large object shape discrimination

Meissner's corpuscles sense hand motion on surfaces

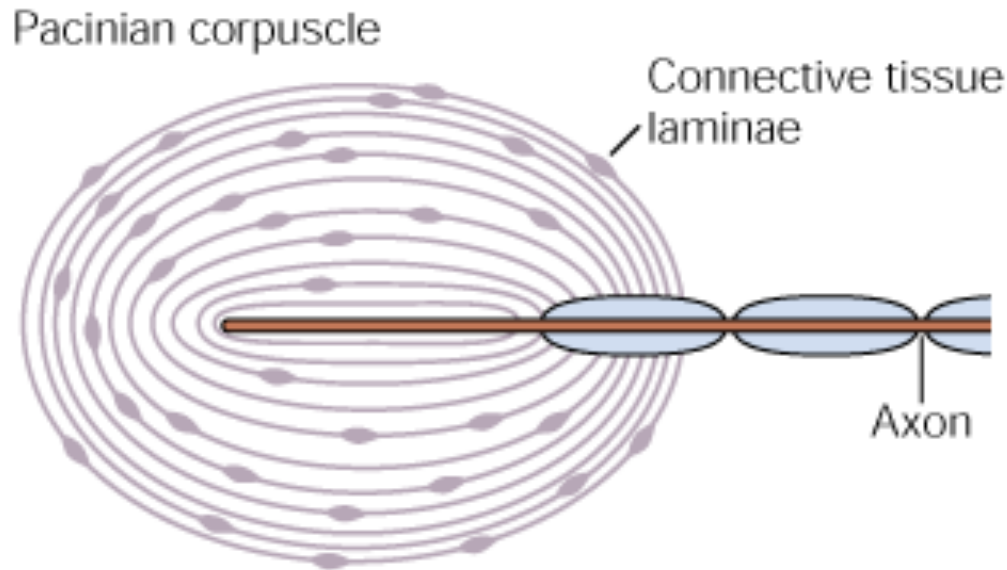


Meissner's corpuscles detect motion of a small dot

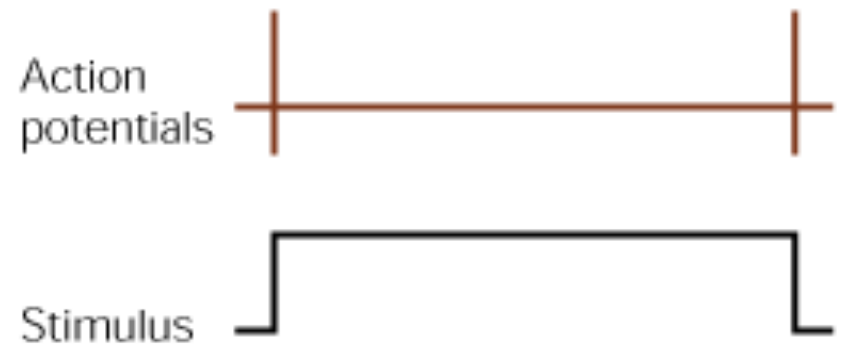


LaMotte RH, Whitehouse J.
J Neurophysiol 1986

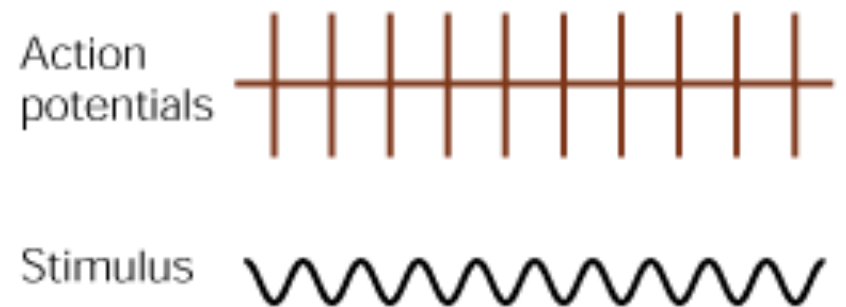
RA spike trains code motion and vibration



A Steady pressure

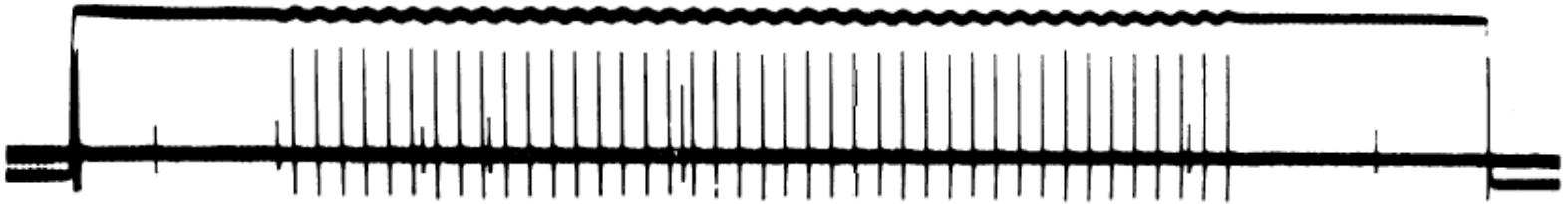


B 110 Hz vibration



RA1 and RA2 fibers detect low and high frequencies

RA1 40 Hz
(Meissner)

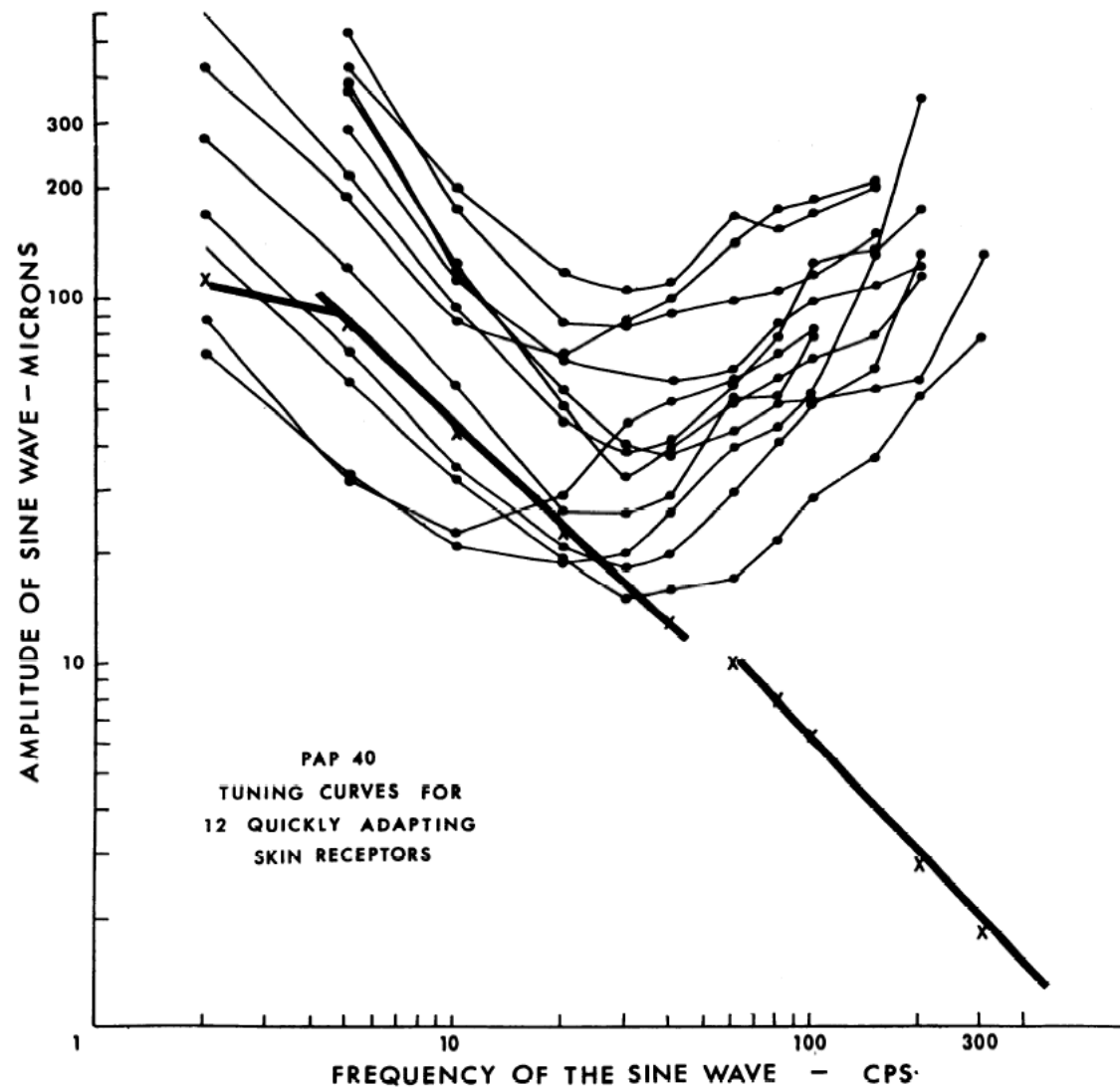


RA2 200 Hz
(Pacinian)



Tuning curves quantify vibratory threshold

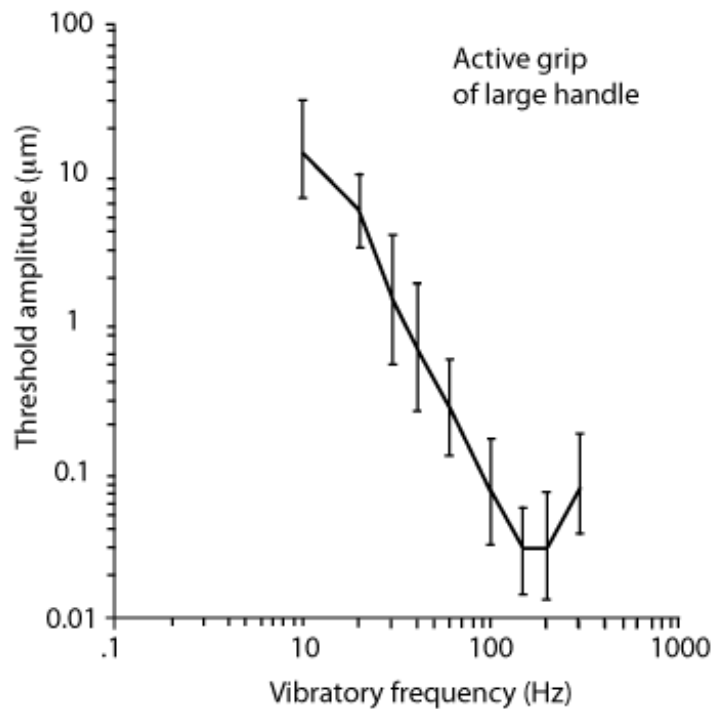
RA1 fibers



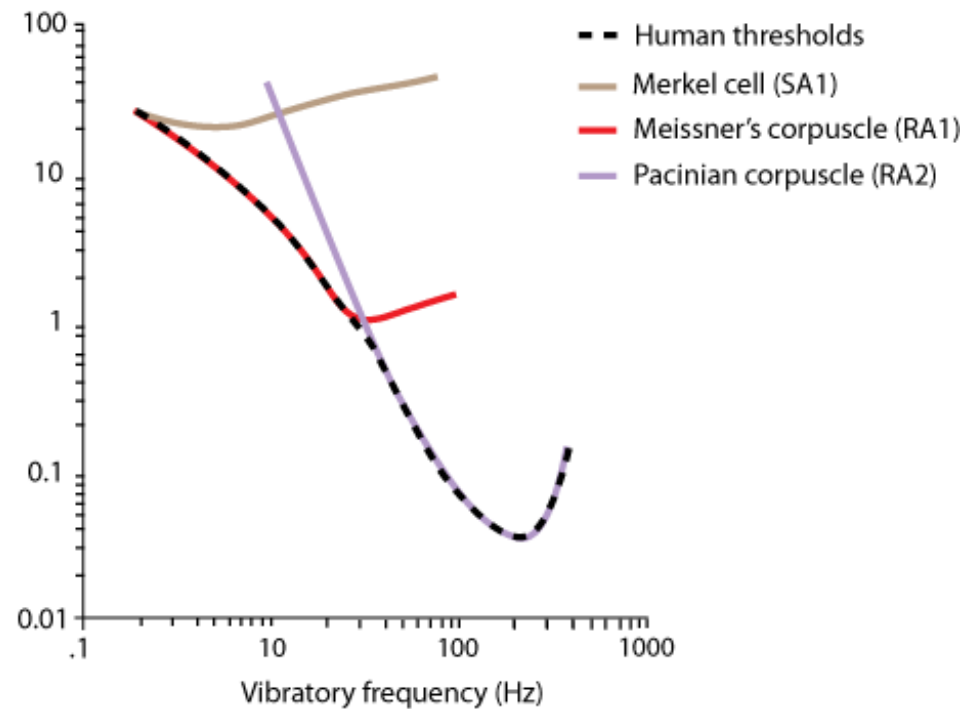
Vibration thresholds are frequency dependent

Thresholds for detection of vibration

1 Human perceptual thresholds



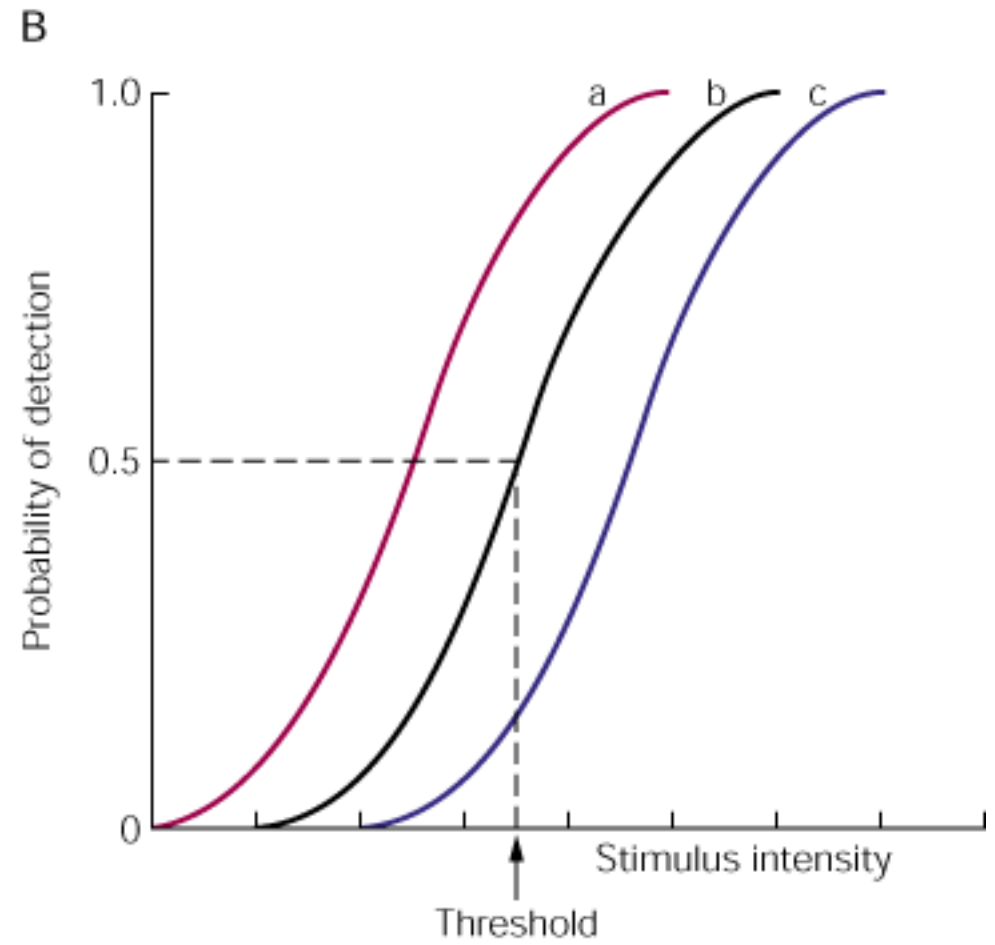
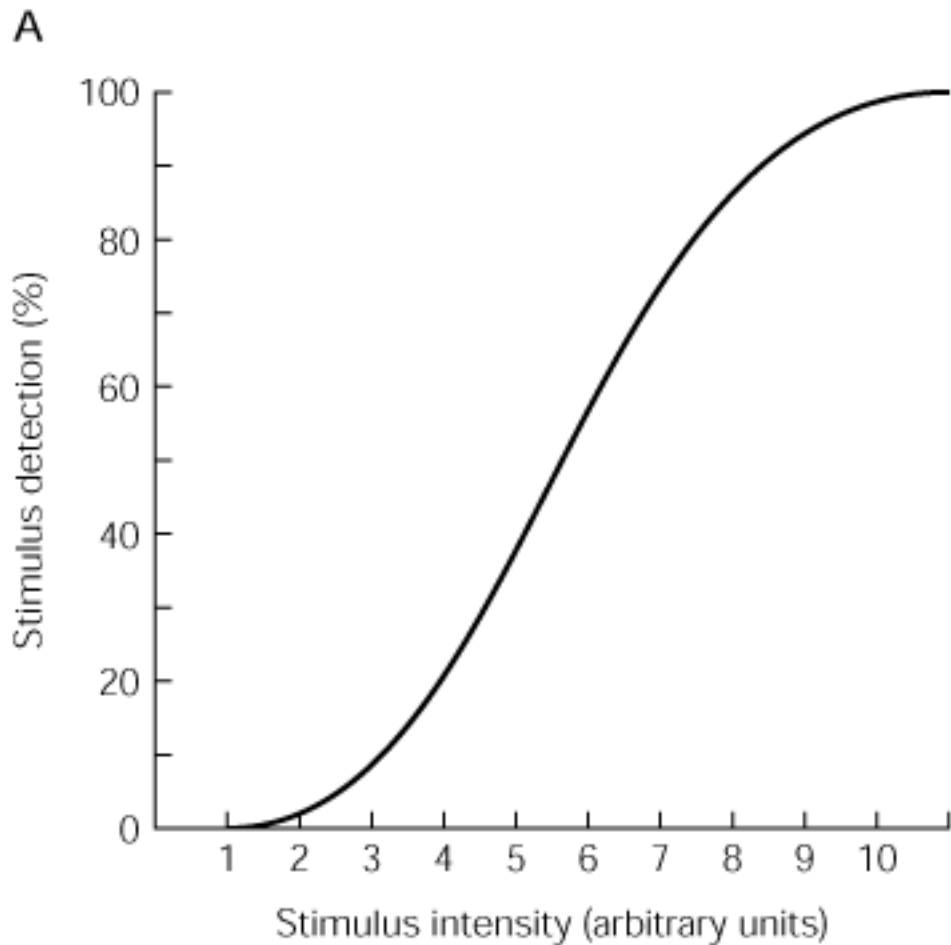
2 Neural thresholds



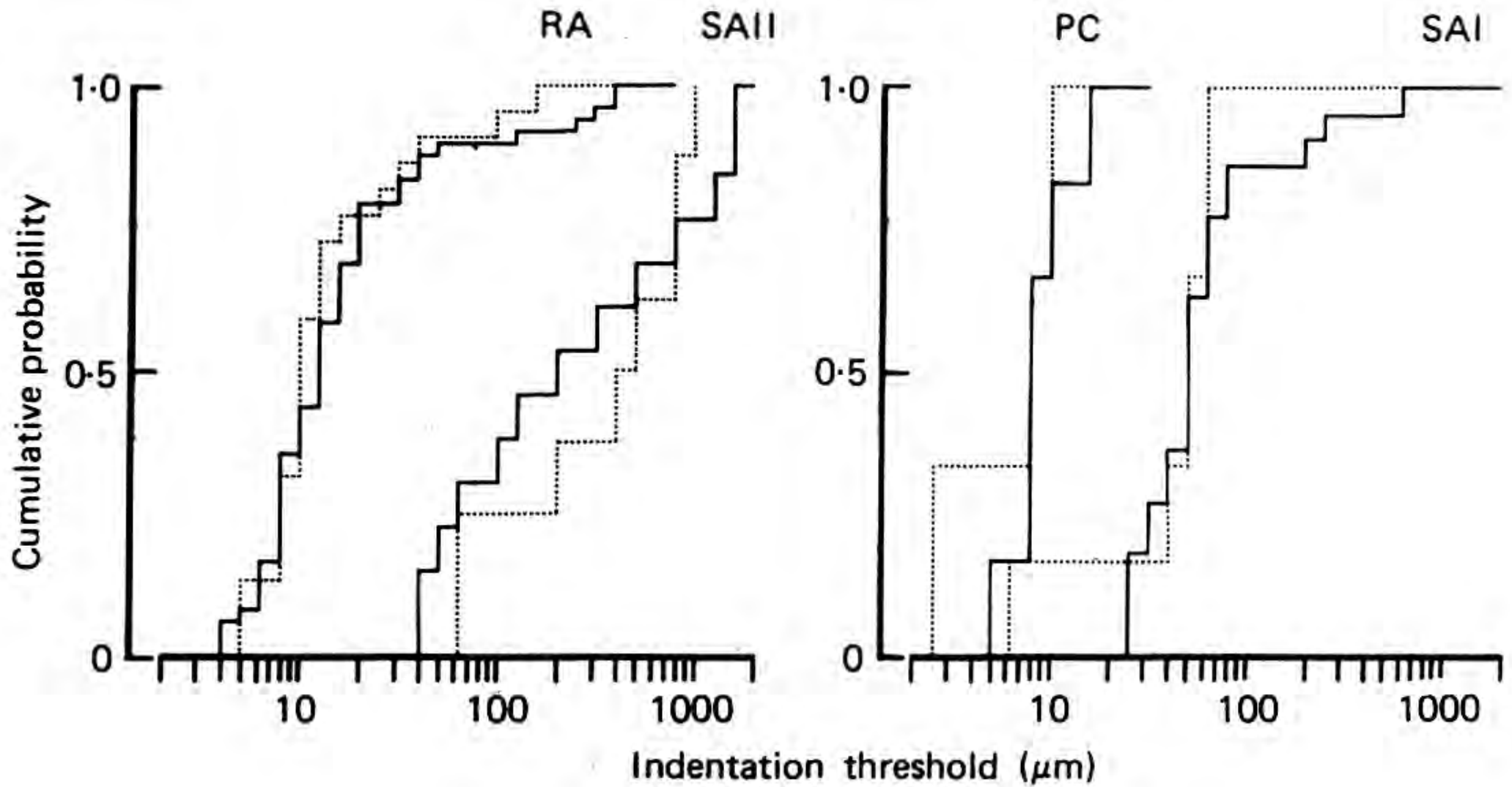
Rapidly-Adapting Receptor Function

- **Meissner's** corpuscle (RA1):
 - Motion
 - Texture
 - Edges
 - Flutter (low-frequency vibration)
- **Pacinian** corpuscle (RA2):
 - Vibration (tool use)
 - Contact and release

Threshold diversity extends dynamic range



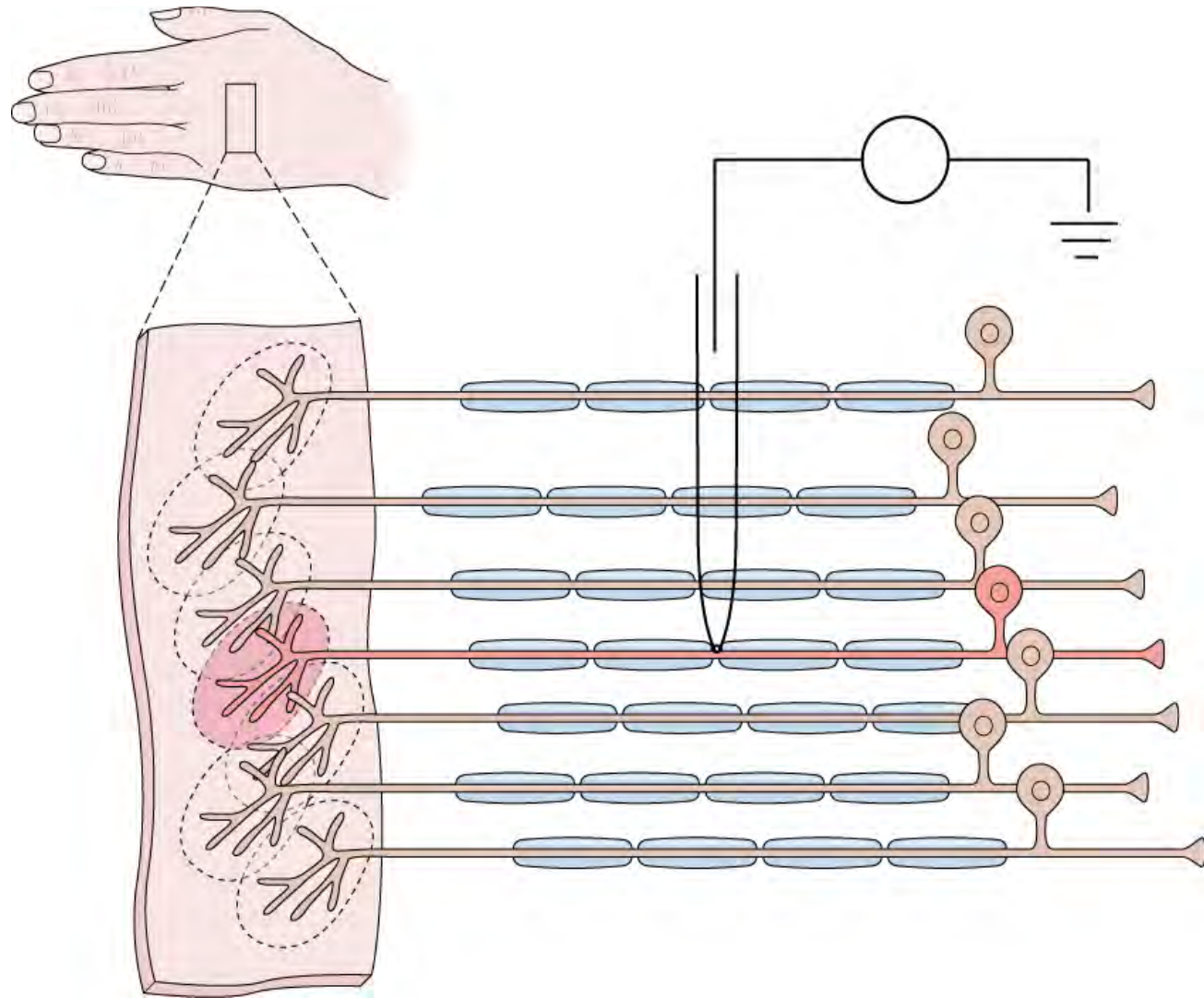
Touch receptor thresholds differ



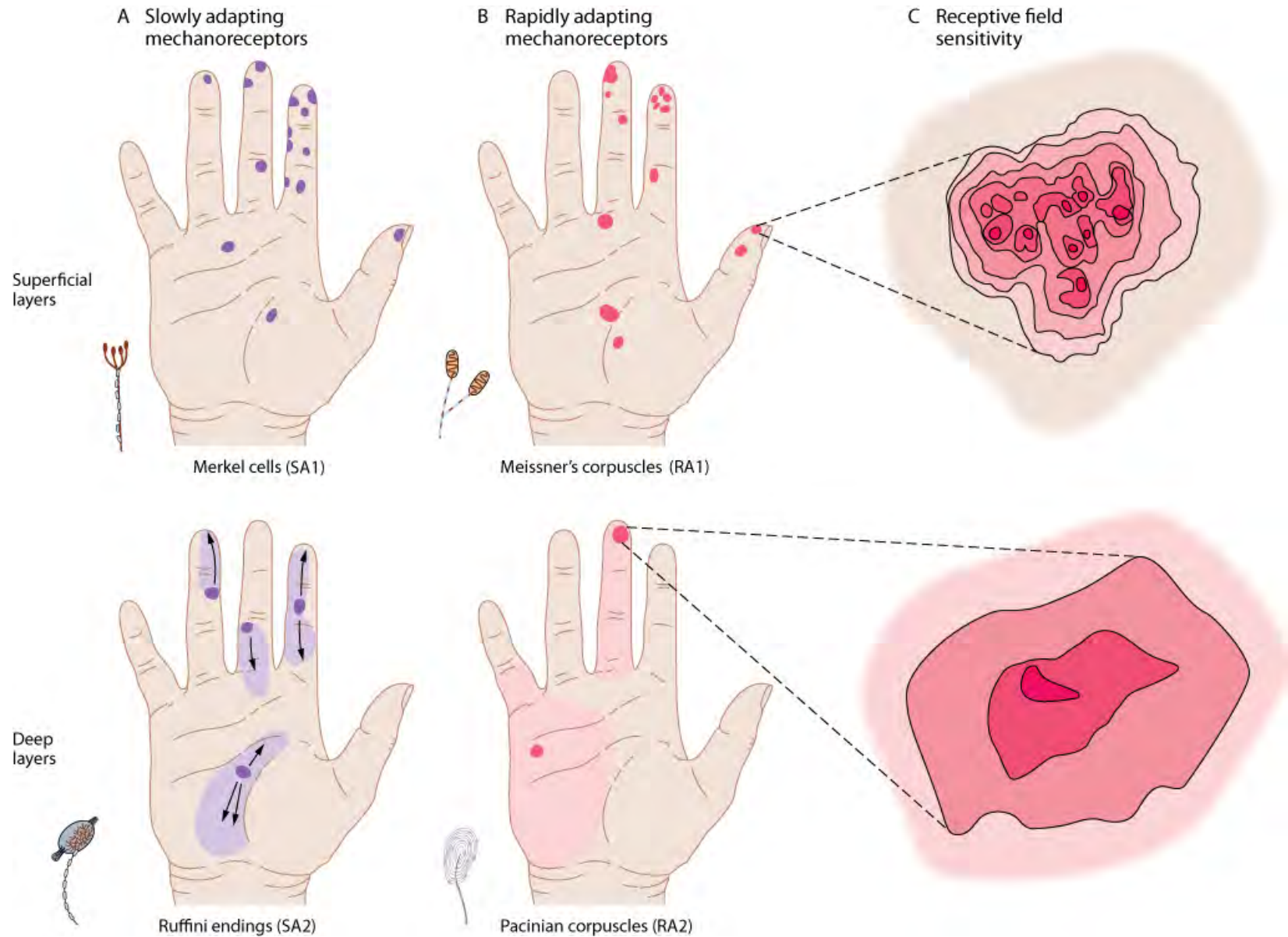
Receptive fields determine spatial properties

- The *receptive field* of a sensory neuron defines the spatial location where it responds to stimuli of the appropriate energy
- Spatial position of a receptor within the sense organ localizes the stimulus in space
- Where we are touched is coded by which specific touch fibers are activated

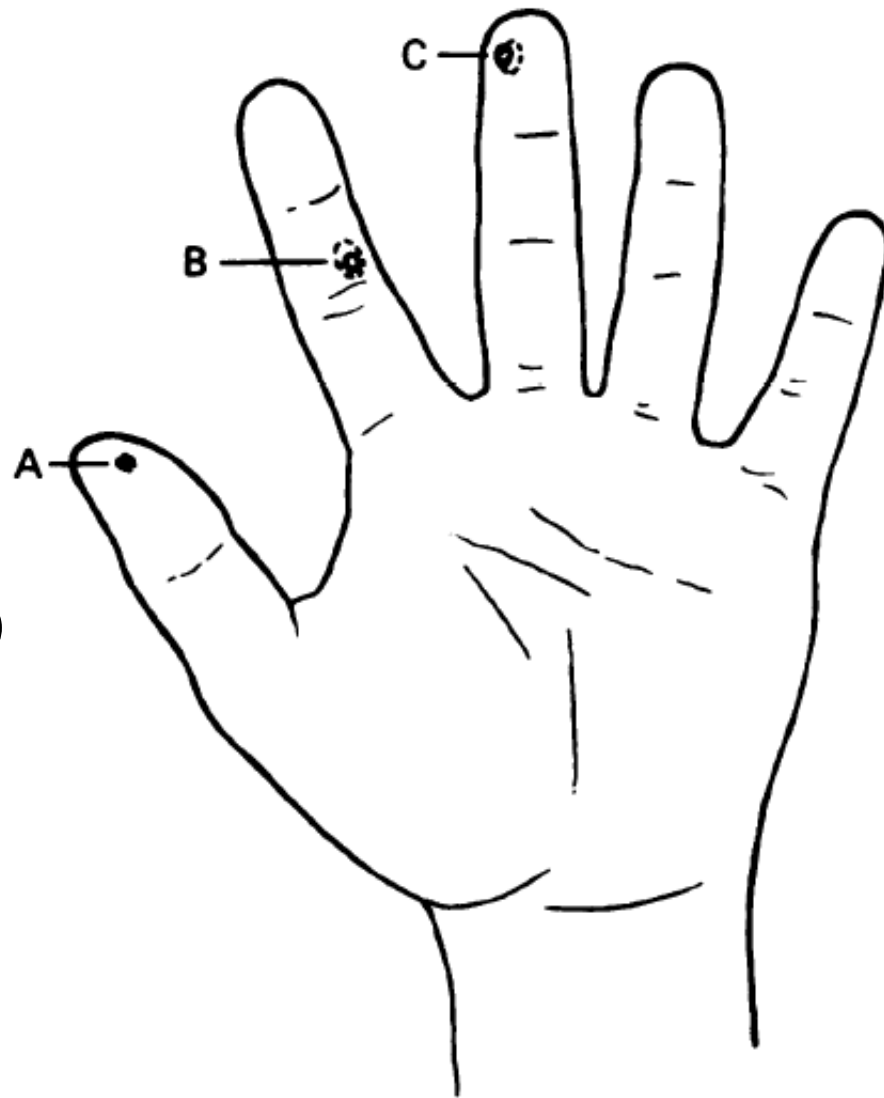
Nerve branch patterns define receptive fields



Receptive fields of touch receptors differ in size



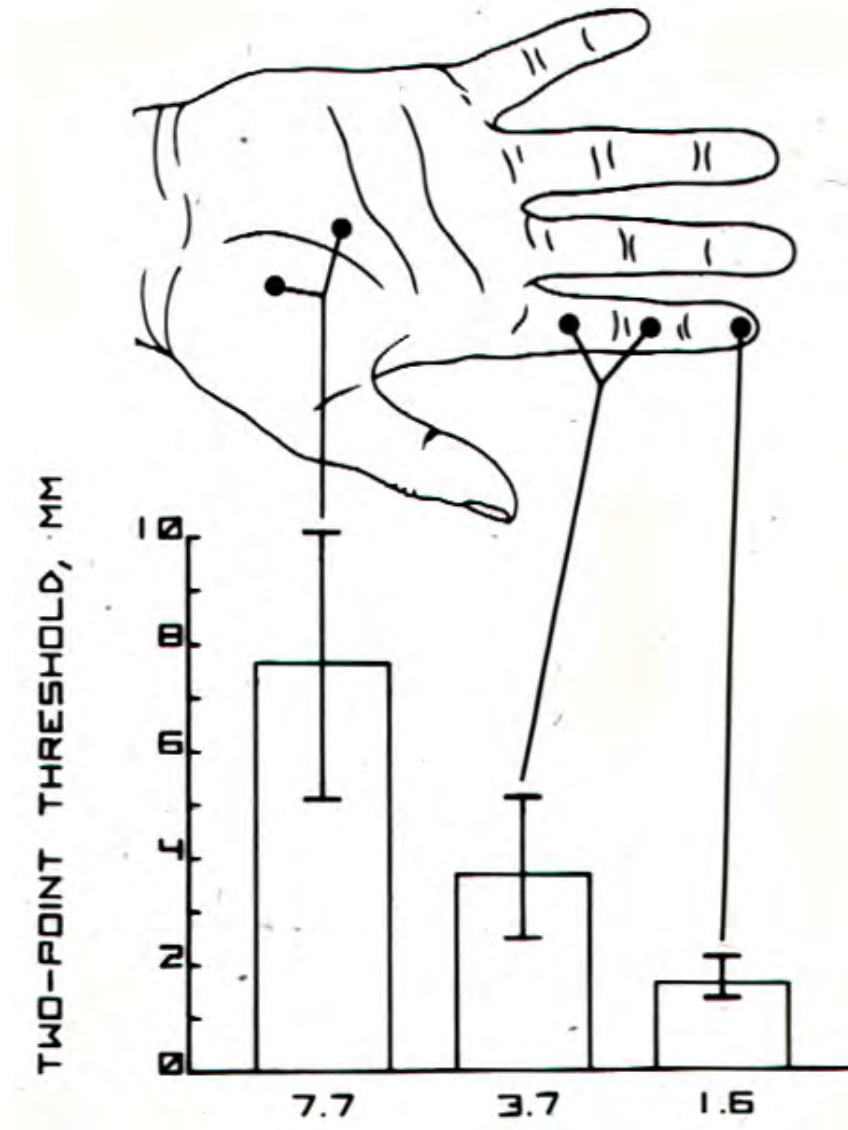
Receptive and perceptive fields coincide



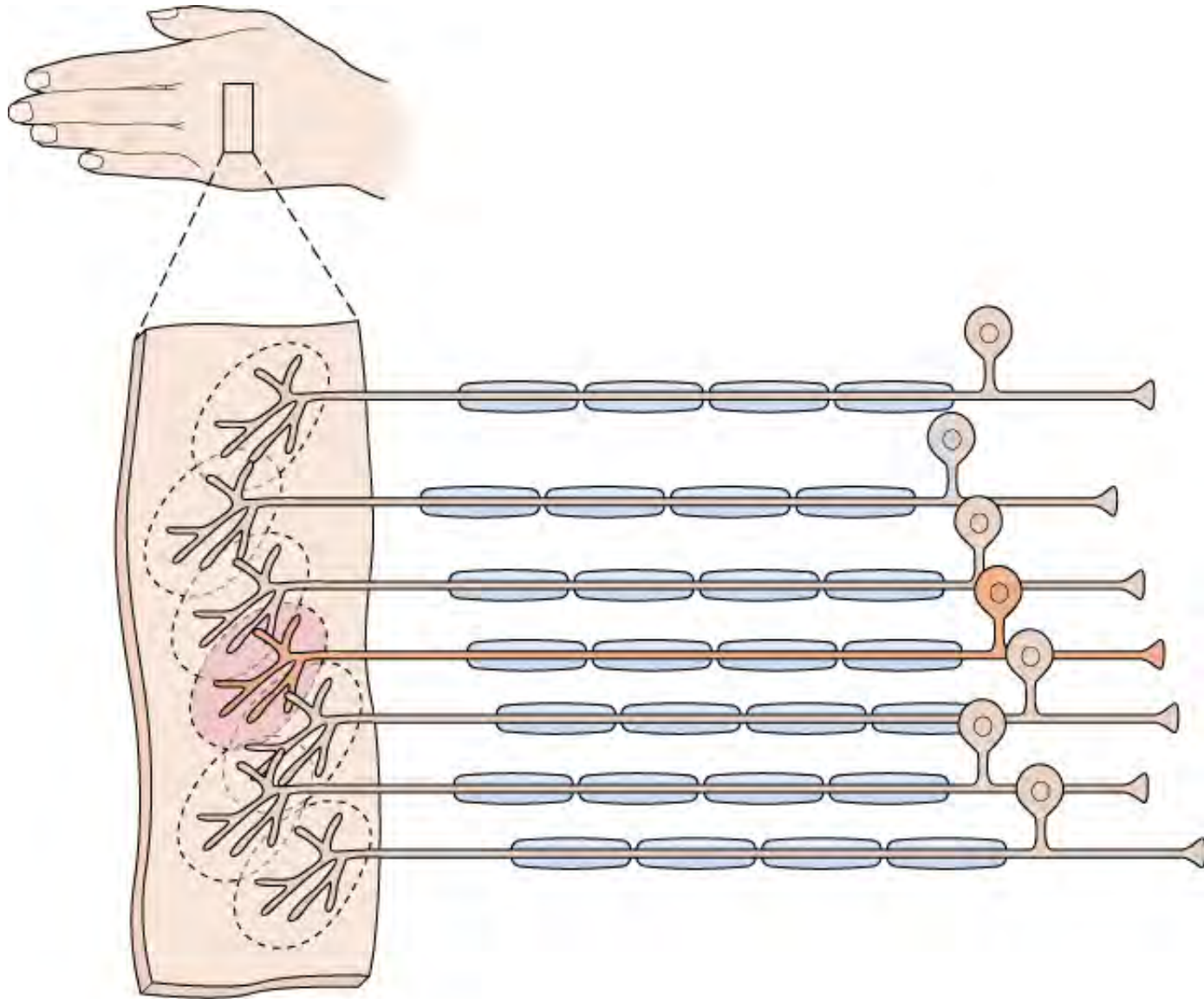
A = RA1 fiber:
(Tap or vibration)

B, C = SA1 fiber:
(Pressure)

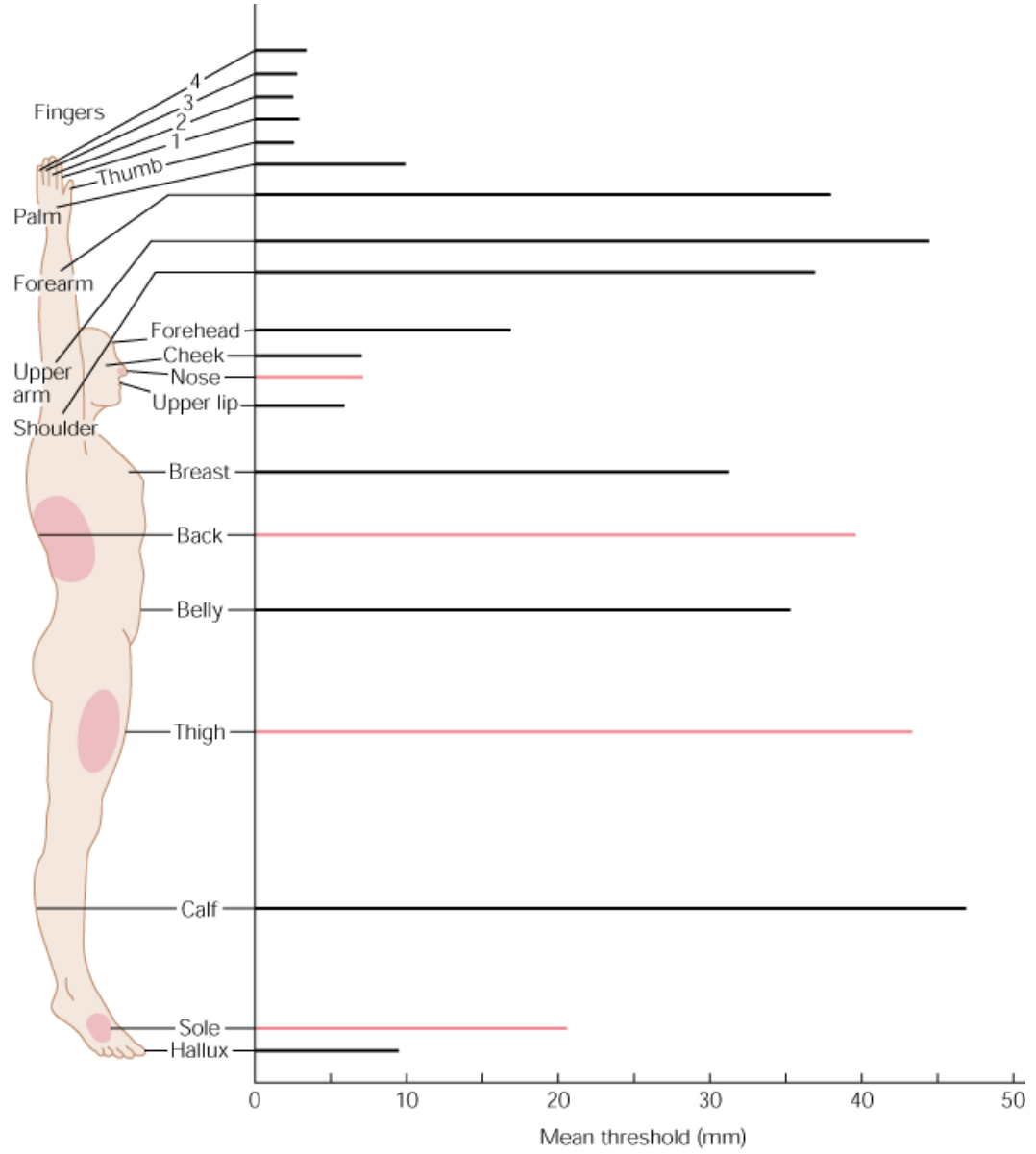
Two-point thresholds are smallest on the hand



Receptive field size determines spatial resolution



Two-point thresholds correlate with receptive field size



Spatial Resolution ... and Receptive Fields



20 x 20 pixel



60 x 60 pixel



400 x 400 pixel

Two-point discrimination threshold

- Reflects receptive field diameters of Meissner's corpuscle (RA1) and Merkel cell (SA1) afferents
- Receptive field diameter correlates inversely with innervation density
- Spatial acuity highest on densely innervated body regions (fingertips, lips, toes) that are used to touch external objects

Touch receptor response properties

ADAPTATION		RECEPTIVE FIELDS	INNERVATION DENSITY
Fast. no static response	Slow, static response present		
<p>Changes in fingertip forces, fine form discrimination, moving stimuli, slips, friction etc.</p> <p>FA-I (43 %) Meissner</p>	<p>Finger tip forces, fine form discrimination etc.</p> <p>SA-I (25 %) Merkel</p>	<p>Small, sharp borders</p>	<p>Increase distally</p> <p>140; 70 cm⁻¹ 40; 36 cm⁻¹ 24; 9 cm⁻¹</p>
<p>Mechanical transients & vibration (~40 - 400 Hz)</p> <p>FA-II (13 %) Pacini & Pacini-like</p>	<p>Directional strain in deep dermal and subdermal tissues</p> <p>SA-II (19 %) Ruffini</p>	<p>Large, obscure borders</p>	<p>~Uniform</p> <p>22; 12 cm⁻¹ 10; 16 cm⁻¹ 10; 18 cm⁻¹</p>