Mathematical Tools for Neural and Cognitive Science

Fall semester, 2019

## Section 2: Least Squares

## Least squares regression:

$$
\min _{\beta} \sum_{n}\left(y_{n}-\beta x_{n}\right)^{2}
$$



In the space of measurements:

[Gauss, 1795 - age 18]

| $\boldsymbol{x}$ |  |
| :---: | :---: |
|  | $\min _{\beta} \sum_{n}\left(y_{n}-\beta x_{n}\right)^{2}$ |

$\min _{\beta} \sum_{n}\left(y_{n}-\beta x_{n}\right)^{2} \quad \begin{aligned} & \text { can solve this with } \\ & \text { calculus... [on board] }\end{aligned}$
... or with linear algebra! $\min _{\beta}\|\vec{y}-\beta \vec{x}\|^{2}$

$\min _{\beta}\|\vec{y}-\beta \vec{x}\|^{2}$
Geometry:

Note: this is not the twodimensional $(x, y)$ measurement space of previous plots!


Note: partition of sum of squared data values:

$$
\|\vec{y}\|^{2}=\left\|\beta_{\mathrm{opt}} \vec{x}\right\|^{2}+\left\|\vec{y}-\beta_{\mathrm{opt}} \vec{x}\right\|^{2}
$$

$\begin{aligned} & \text { Multiple } \\ & \text { regression: }\end{aligned} \quad \min _{\vec{\beta}}\left\|\vec{y}-\sum_{k} \beta_{k} \vec{x}_{k}\right\|^{2}=\min _{\vec{\beta}}\|\vec{y}-X \vec{\beta}\|^{2}$
Observation


Solution via the "Orthogonality Principle":
Construct matrix $X$, containing columns $\vec{x}_{1}$ and $\vec{x}_{2}$ Orthogonality: $\quad X^{T}(\vec{y}-X \vec{\beta})=\overrightarrow{0}$


2D vector space containing all linear combinations of $\vec{x}_{1}$ and $\vec{x}_{2}$

Alternatively, can solve using SVD...

$$
\begin{aligned}
\min _{\vec{\beta}}\|\vec{y}-X \vec{\beta}\|^{2} & =\min _{\vec{\beta}}\left\|\vec{y}-U S V^{T} \vec{\beta}\right\|^{2} \\
& =\min _{\vec{\beta}}\left\|U^{T} \vec{y}-S V^{T} \vec{\beta}\right\|^{2} \\
& =\min _{\vec{\beta}^{*}}\left\|\vec{y}^{*}-S \vec{\beta}^{*}\right\|^{2}
\end{aligned}
$$

$$
\text { where } \quad \vec{y}^{*}=U^{T} \vec{y}, \quad \vec{\beta}^{*}=V^{T} \vec{\beta}
$$

Solution: $\quad \beta_{\mathrm{opt}, k}^{*}=y_{k}^{*} / s_{k}, \quad$ for each $k$
or $\quad \vec{\beta}_{\mathrm{opt}}^{*}=S^{\#} \vec{y}^{*}$
[on board: transformations, elliptical geometry]

## Optimization problems



Note: fitting with a line does not guarantee data actually lie along a line...
These 4 data sets give the same regression fit, and same error:





## Polynomial regression



Polynomial regression - how many terms?

(to be continued, when we get to "statistics"...)

## Weighted Least Squares

$$
\begin{aligned}
& \min _{\beta} \sum_{n}\left[w_{n}\left(y_{n}-\beta x_{n}\right)\right]^{2} \\
&=\min _{\beta} \|
\end{aligned} \begin{aligned}
& \uparrow(\vec{y}-\beta \vec{x}) \|^{2}
\end{aligned}
$$

Solution via simple extensions of basic regression solution (i.e., let $\vec{y}^{*}=W \vec{y}$ and $\vec{x}^{*}=W \vec{x}$ and solve for $\beta$ )

## Outliers



## Outliers




Solution 1: "trimming"... discard points with "large" error.
Note: a special case of weighted least squares.


Trimming can be done iteratively (discard outlier, re-fit, repeat), a so-called "greedy" method. When do you stop?

Solution 2: Use a "robust" error metric.
For example:


Note: generally can't obtain solution directly (i.e., requires an iterative optimization procedure).
In some cases, can use iteratively re-weighted least squares (IRLS)...

## Iteratively Re-weighted Least Squares (IRLS)


initialize: $w_{n}^{(0)}=1$
iterate $\beta^{(i)}=\arg \min _{\beta} \sum_{n} w_{n}^{(i)}\left(y_{n}-\beta^{(i)} x_{n}\right)^{2}$
$w_{n}^{(i+1)}=\frac{f^{\prime}\left(y_{n}-\beta^{(i)} x_{n}\right)}{\left|y_{n}-\beta^{(i)} x_{n}\right|}$ (one of many variants)

## Constrained Least Squares

## Linear constraint:

$$
\min _{\vec{\beta}}\|\vec{y}-X \vec{\beta}\|^{2}, \quad \text { where } \vec{c} \cdot \vec{\beta}=\alpha
$$

Quadratic constraint:

$$
\min _{\vec{\beta}}\|\vec{y}-X \vec{\beta}\|^{2}, \quad \text { where }\|\beta\|^{2}=1
$$

Both can be solved exactly using linear algebra (SVD)...
[on board, with geometry]



## Constrained Least Squares



$$
\bar{\beta}_{\text {opt }, c}^{*}=\bar{\beta}_{\text {opt }, u}^{*}-\gamma \bar{c}^{*}
$$ and satisfies the constraint

$$
\begin{aligned}
& \bar{\beta}_{o p, c}^{*} \cdot \vec{c}^{\prime \prime}=\alpha \\
& =\bar{\beta}_{\text {opt }, u}^{*} \cdot \bar{c}^{\prime \prime}-\gamma \bar{c}^{\prime \prime} \cdot \bar{c}^{\prime \prime} \\
& \gamma=\frac{\bar{\beta}_{o p t, u}^{\prime \prime} \cdot \vec{c}^{\prime \prime}-\alpha}{\bar{c}^{*} \cdot \vec{c}^{\prime \prime}}=\frac{\bar{y}^{\prime \prime} \cdot \vec{c}^{\prime \prime}-\alpha}{\vec{c}^{*} \cdot \vec{c}^{\prime \prime}}
\end{aligned}
$$

Solution: $\gamma \rightarrow \bar{\beta}_{\text {opt }, c}^{*}$. Stetch by $\mathrm{s}^{-1} \vec{\beta}_{\text {opt }, c} \xrightarrow{\text { Rotate by } V} \bar{\beta}_{\text {opt }, c}$

Standard Least Squares regression

Error is vertical distance (in the "dependent variable") from the fitted line...

## Total Least Squares Regression

(a.k.a "orthogonal regression")

Error is squared distance from the fitted line...

expressed as: $\min _{\hat{u}}\|D \hat{u}\|^{2}, \quad$ where $\|\hat{u}\|^{2}=1$
Note: "data" matrix $D$ now includes both $x$ and $y$ coordinates

Variance of data $D$, projected onto axis $\hat{u}$ : $\left\|U S V^{T} \hat{u}\right\|^{2}=\left\|S V^{T} \hat{u}\right\|^{2}=\left\|S \hat{u}^{*}\right\|^{2}=\left\|\vec{u}^{* *}\right\|^{2}$, where $D=U S V^{T}, \quad \hat{u}^{*}=V^{T} \hat{u}, \quad \vec{u}^{* *}=S \hat{u}^{*}$


Set of $\hat{u}$ 's of length 1
(i.e., unit vectors)

Set of $\hat{u}^{*}$ s of length 1 (i.e., unit vectors)

First two components of $\vec{u}^{* *}$ (rest are zero!), for three example $S$ 's.

Olympic gold medalists (Rio, 2016)


Thomas Röhler (Germany)

3D geometry:
Javelin, Discus, Shotput


Sandra Perković (Croatia)

## Eigenvectors/eigenvalues

Define symmetric matrix:

$$
\begin{aligned}
C & =D^{T} D \\
& =\left(U S V^{T}\right)^{T}\left(U S V^{T}\right) \\
& =V S^{T} U^{T} U S V^{T} \\
& =V\left(S^{T} S\right) V^{T}
\end{aligned}
$$

- "rotate, stretch, rotate back"
- matrix $C$ "summarizes" the shape of the data with an ellipsoid: principal axes are columns of $V$, dimensions are elements of $S$
$\hat{v}_{k}$, the $k$ th column of $V$, is an eigenvector of $C$ :

$$
\begin{aligned}
C \hat{v}_{k} & =V\left(S^{T} S\right) V^{T} \hat{v}_{k} \\
& =V\left(S^{T} S\right) \hat{e}_{k} \\
& =s_{k}^{2} V \hat{e}_{k} \\
& =s_{k}^{2} \hat{v}_{k}
\end{aligned}
$$

- eigenvectors are vectors that are rescaled by the matrix (i.e., direction is unchanged) - this is true for all columns of V
- scale factor $s_{k}^{2}$ is called the eigenvalue associated with $\hat{v}_{k}$


## Principal Component Analysis (PCA)

The shape of a data cloud can be summarized with an ellipse (ellipsoid) using a simple procedure:
(1) Subtract mean of all data points, to re-center around origin
(2) Assemble centered data vectors in rows of a matrix, $D$
(3) Compute the SVD of $D$ :

$$
D=U S V^{T}
$$

or compute eigenvectors of $C=D^{T} D$ :

$$
C=V \Lambda V^{T}
$$

(4) Columns of $V$ are the principal components (axes) of the ellipsoid, diagonal elements $s_{k}$ or $\sqrt{\lambda_{k}}$ are the corresponding sizes of the ellipsoid

Example: PCA for dimensionality reduction and visualization


